

# Why use matrix approaches to Linear Regression?

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# Re-writing the simple linear regression model

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Think of the previous model with  $n$  observations as  $n$  equations

$$y_1 = \beta_0 + \beta_1 x_1 + \varepsilon_1$$

$$y_2 = \beta_0 + \beta_1 x_2 + \varepsilon_2$$

...

$$y_n = \beta_0 + \beta_1 x_n + \varepsilon_n$$

# We can write the $n$ equations with matrices and vectors

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- $\mathbf{Y}$  is a  $(n \times 1)$  vector of observations  $y_i$
- $\mathbf{X}$  is a  $(n \times 2)$  matrix called the *design matrix* where the first column is a series of 1's and the second column is the set of observations  $x_i$
- $\boldsymbol{\beta}$  is a  $(2 \times 1)$  vector of the unknown parameters  $\beta_0$  and  $\beta_1$

# Matrix form

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$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\varepsilon}$$

- sometimes called the *General Linear Model*
- but be careful with terminology here
- this is not Generalised Linear Modelling or GLM which you will see in later Statistics modules
- note that  $\mathbf{Y}$  and  $\boldsymbol{\varepsilon}$  are *random vectors* that is vectors of random variables

Why are we doing  
matrices in a stats  
module?

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What variables would you like to know about if you were modelling ....

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profitability of  
a new business  
venture

win % for a  
sports team  
next year

success rate of  
nests of a  
species of bird

streaming  
views of a new  
Netflix series

followers for a  
QM society's  
Instagram

# We soon need multiple explanatory variables

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Very quickly `model <- lm(y~x)` will not do the job

Need to be able to consider

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \beta_3 x_{3i} + \beta_4 x_{4i} + \varepsilon_i$$

Remember how we found  $\hat{\beta}_0$  and  $\hat{\beta}_1$  in the simple linear model

Solving simultaneous equations in betas is not scaleable

# Why are we doing matrices?

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- We don't need matrices for the simple linear regression model
- However, we are about to move to models with more than one explanatory variable
- Matrices and vectors will give us an approach that is easier to expand with more  $x_i$  type inputs
- It is easier to develop the matrix form with the simplest case of simple linear regression first
  - Where we already know the results



# Three matrix results / properties we'll need

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- Random vectors

2

- Variance Covariance or Dispersion Matrix

3

- Multivariate Normal Distribution

# Random vectors

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We need to introduce some properties of random vectors before we continue

- The expected value of a random vector is the vector of expected values of its components

if  $z = (z_1, \dots, z_n)^T$  is a random vector

$$E[z] = E \begin{pmatrix} z_1 \\ z_2 \\ \dots \\ z_n \end{pmatrix} = \begin{pmatrix} E[z_1] \\ E[z_2] \\ \dots \\ E[z_n] \end{pmatrix}$$

# Linear transformation of random vectors

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If  $a$  is a constant,  $b$  is a constant vector and  $\mathbf{A}$ ,  $\mathbf{B}$  are matrices of constants

Then

- $E[az + b] = aE[z] + b$
- $E[\mathbf{A}z] = \mathbf{A}E[z]$
- $E[z^T \mathbf{B}] = E[z]^T \mathbf{B}$

# Variations and covariances

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With random vectors, variances and covariances of the random variables  $z_i$  together form the *dispersion matrix* sometimes called the *variance-covariance matrix*.

$$\text{Var}(z) = \begin{pmatrix} \text{var}(z_1) & \cdots & \text{cov}(z_1, z_n) \\ \vdots & \ddots & \vdots \\ \text{cov}(z_n, z_1) & \cdots & \text{var}(z_n) \end{pmatrix}$$

# Dispersion matrix properties

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- $Var(z)$  can also be expressed as  $E[(z - E[z])(z - E[z])^T]$
- the dispersion matrix is symmetric since  $cov(z_i, z_j) = cov(z_j, z_i)$
- if all of the  $z_i$  are uncorrelated all  $cov(z_i, z_j) = 0$  and hence the dispersion matrix is diagonal with the variances
- if  $\mathbf{A}$  is a matrix of constants then  $Var(\mathbf{A}z) = \mathbf{A} Var(z) \mathbf{A}^T$

# Multivariate Normal Distribution

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- for  $\mathbf{Y}$  and  $\varepsilon$  we will need normal distribution for multiple variables
- extension of the Bivariate Normal Distribution for 2 random variables introduced in MTH5129
- for  $> 2$  random variables we use the Multivariate Normal Distribution which is the general case of the Bivariate Normal

# Multivariate Normal

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A random vector  $z$  has a multivariate normal distribution if its probability density function (pdf) can be written in the form

$$f(z) = \frac{1}{(2\pi)^{n/2} \sqrt{\det(\mathbf{V})}} \exp\left\{-\frac{1}{2} (z - \mu)^T \mathbf{V}^{-1} (z - \mu)\right\}$$

# Multivariate Normal

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where,

- vector  $\mu$  is the mean of  $z$
- $\mathbf{V}$  is the dispersion matrix of  $z$
- $\det(\mathbf{V})$  is the determinant of  $\mathbf{V}$

We usually write this as  $z \sim N_n(\mu, \mathbf{V})$



# Least Squares Estimation with matrices

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Our goal is to find  $\hat{\beta}$  a (2x1) vector with the least squares estimates of the model parameters  $\beta_0$  and  $\beta_1$ .

When we estimated parameters  $\beta_0$  and  $\beta_1$  in the simple linear regression model before:

- we solved the two simultaneous “normal equations”
- found from taking the derivative of the equation for the sum of squares of errors with respect to each of the two parameters

# Least Squares Estimation with matrices

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In matrix form the normal equations become

$$\mathbf{X}^T \mathbf{y} = \mathbf{X}^T \mathbf{X} \hat{\boldsymbol{\beta}}$$

as long as  $\mathbf{X}^T \mathbf{X}$  is invertible, that is its determinant is not zero, there is a unique solution to the matrix form normal equations

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

# $X^T X$ is invertible

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$$X^T X = \begin{pmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{pmatrix}$$

which means that the determinant of  $X^T X$  is

$$|X^T X| = n \sum x_i^2 - (\sum x_i)^2 = n S_{xx} \neq 0$$

so there is a solution to the normal equations in the simple linear regression model expressed in matrix form

# Solving the normal equations

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$$(\mathbf{X}^T \mathbf{X})^{-1} = \frac{1}{n S_{xx}} \begin{pmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{pmatrix} = \frac{1}{S_{xx}} \begin{pmatrix} \frac{1}{n} \sum x_i^2 & -\bar{x} \\ -\bar{x} & 1 \end{pmatrix}$$

So we now have what we need to solve the normal equations

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

# Solving the normal equations

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$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\hat{\boldsymbol{\beta}} = \frac{1}{S_{xx}} \begin{pmatrix} \frac{1}{n} \sum x_i^2 & -\bar{x} \\ -\bar{x} & 1 \end{pmatrix} \begin{pmatrix} \sum y_i \\ \sum x_i y_i \end{pmatrix}$$

$$\hat{\boldsymbol{\beta}} = \frac{1}{S_{xx}} \begin{pmatrix} \frac{1}{n} \sum x_i^2 \sum y_i - \bar{x} \sum x_i y_i \\ \sum x_i y_i - \bar{x} \sum y_i \end{pmatrix} = \frac{1}{S_{xx}} \begin{pmatrix} \bar{y} S_{xx} - \bar{x} S_{xy} \\ S_{xy} \end{pmatrix} = \begin{pmatrix} \bar{y} - \hat{\beta}_1 \bar{x} \\ \hat{\beta}_1 \end{pmatrix}$$

Which is exactly the same as  $\hat{\beta}_0$  and  $\hat{\beta}_1$  before we used matrix form

# Fitted model

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$$\hat{\boldsymbol{\beta}} = \begin{pmatrix} \bar{y} - \hat{\beta}_1 \bar{x} \\ \hat{\beta}_1 \end{pmatrix}$$

Gives us the fitted values

$$\hat{\mu}_i = \mathbf{x}_i^T \hat{\boldsymbol{\beta}} = \hat{\beta}_0 + \hat{\beta}_1 x_i$$

# Residual Sum of Squares

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Residual Sum of Squares in matrix form is

$$SS_E = \text{observed} - \text{fitted}$$

$$SS_E = \mathbf{y}^T \mathbf{y} - \hat{\boldsymbol{\beta}}^T \mathbf{X}^T \mathbf{y}$$

which if you complete all the matrix multiplication gives

$$SS_E = S_{yy} - \hat{\beta}_1 S_{xy} = S_{yy} - \frac{(S_{xy})^2}{S_{xx}}$$

# Properties of the model

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We can now state a number of properties of the parameters and residuals in the simple linear regression model in matrix form

Again, these are not new results for the module, but they are a new way of stating them and this will help us when we move to multiple linear regression

(a) The least squares estimator  $\hat{\beta}$  is an unbiased estimator of  $\beta$

$$E[\hat{\beta}] = \beta$$



# Properties (continued)

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(b)  $Var[\boldsymbol{\beta}] = \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}$

(c) If,  $\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\varepsilon}$  and  $\boldsymbol{\varepsilon} \sim N_n(\mathbf{0}, \sigma^2 \mathbf{I})$

then  $\hat{\boldsymbol{\beta}} \sim N_p(\boldsymbol{\beta}, \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1})$

# Fitted values and the Hat matrix

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(d) The vector of fitted values,  $\hat{\mu} = \hat{Y} = X\hat{\beta}$

can be written  $\hat{\mu} = HY$

$H$  is called the *hat matrix*

$$H = X(X^T X)^{-1} X^T$$

$H$  has the two properties:

$$H = H^T \text{ and } HH = H \text{ (an } \textit{indempotent matrix})$$

# Residual properties

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The residual vector is  $\mathbf{e} = \mathbf{Y} - \hat{\mathbf{Y}} = \mathbf{Y} - \mathbf{H}\mathbf{Y} = (\mathbf{I} - \mathbf{H})\mathbf{Y}$

(e)  $E[\mathbf{e}] = \mathbf{0}$

(f)  $\text{var}[\mathbf{e}] = \sigma^2(\mathbf{I} - \mathbf{H})$

(g) The sum of squares of the residuals is  $\mathbf{Y}^T(\mathbf{I} - \mathbf{H})\mathbf{Y}$

(h) The elements of the residual vector  $\mathbf{e}$  sum to zero

(i) Because the residuals sum to zero,  $\frac{1}{n}\sum \hat{Y}_i = \bar{Y}$

