

APPLIED LINEAR ALGEBRA

WEEK 12 - LESSON 1 ①

1801 Italian astronomer
observes Ceres
(dwarf planet)

.....
↑ position in sky.

then sun appeared → lost track.
where would it be after transit
behind sun?

Orbit depended on 3
parameters x, y, z

To find x, y, z need to solve some linear equations
One for each observation ②

$$3x - 2y + 1z = 7$$

$$4x + y - 7z = 5$$

\vdots

\vdots

→
1 eqn
for obs
ervation

Much more eqns than unknowns

Systems like this do not
tend to have solution

(e.g. noisiness in observation)

What to do? (3)

This is an incompatible linear system

$$A\vec{x} = \vec{b}$$

Need some maths (Gauss)

Idea: Get x such that

Ax is as close as possible to b .

i.e. $Ax - b$

as small as possible.

i.e. $\|Ax - b\|$

is as small as possible.

Such an x will be 4
called the least squares

Solution of $Ax \approx b$
(even though it is not a
solution)

How do we find such an x ?

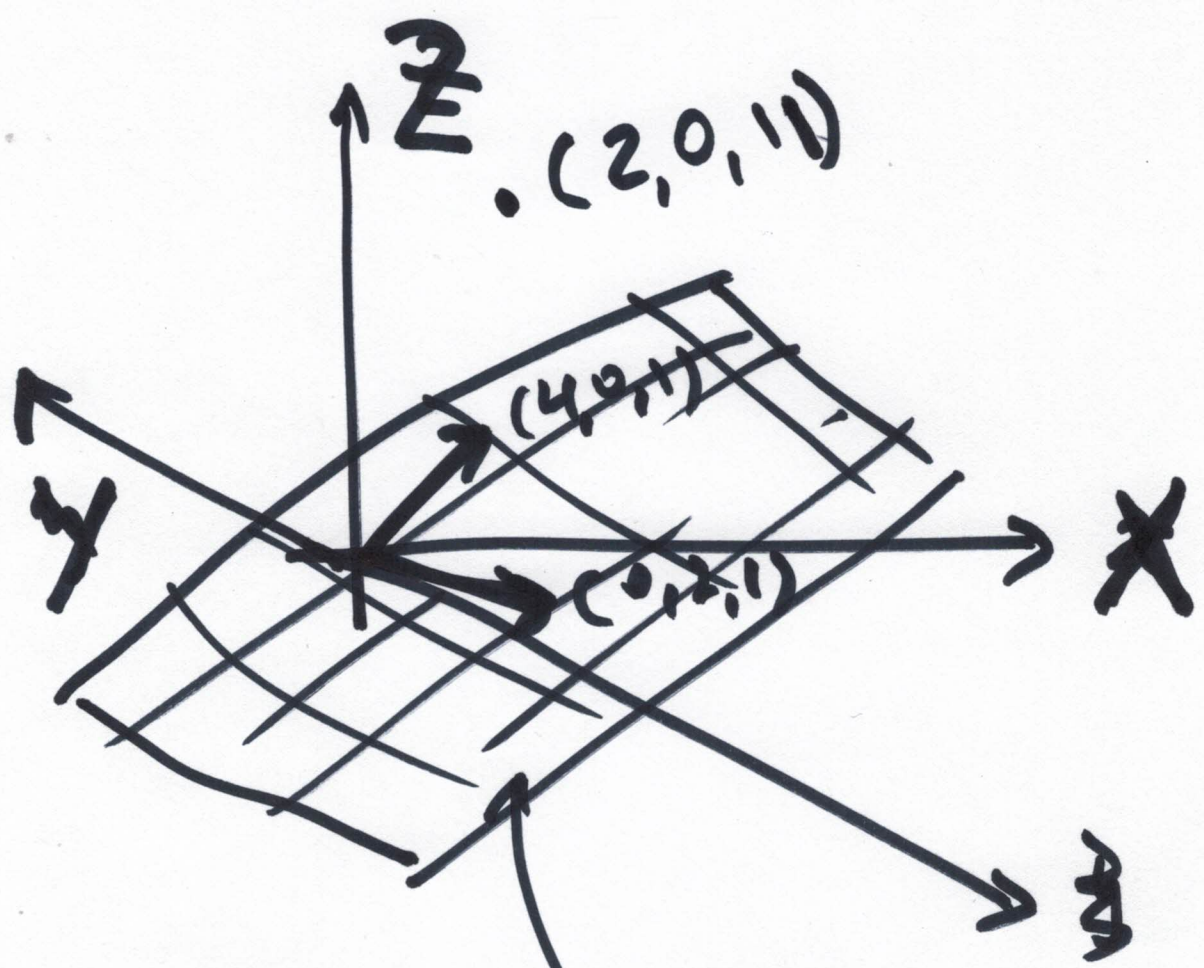
Let us look at a picture
In the case

$$\begin{cases} 4x + 0y = 2 \\ 0x + 2y = 0 \\ x + y = 11 \end{cases} \quad (\text{incompatible})$$

How do we draw this?

3 dim vector depending on x, y → 3 dim vector

(5)



here reside all
 $(4x + 0y, 0x + 2y, x + y)$

$$= \cancel{4(1, 0, 1)} +$$

$$= x(4, 0, 1) + y(0, 2, 1)$$

Need to find (x, y) such that

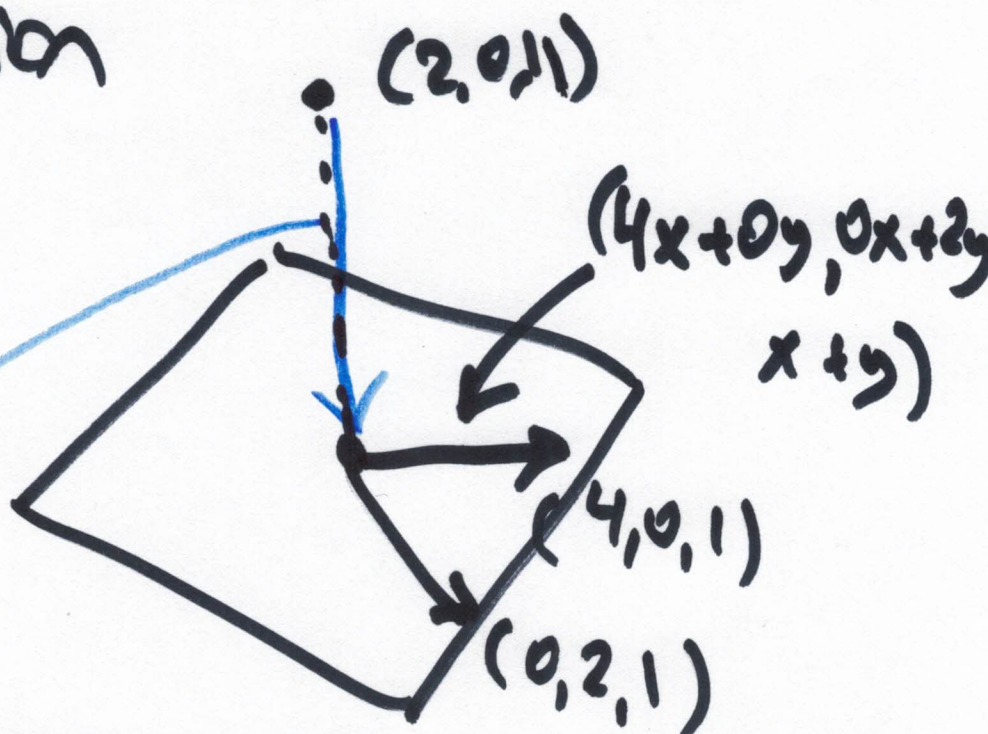
$$(4x + 0y, 0x + 2y, x + y)$$

is as close as possible to

$$(2, 0, 11)$$

Answer : orthogonal
projection

6



just need to demand

$(4x + 0y, 0x + 2y, x + y) - (2, 0, 1)$
perpendicular to $(4, 0, 1)$ & $(0, 2, 1)$

$$\left((4x + 0y, 0x + 2y, x + y) - (2, 0, 1) \right) \cdot (4, 0, 1) = 0$$

$$= 0$$

$$\left((4x + 0y, 0x + 2y, x + y) - (2, 0, 1) \right) \cdot (0, 2, 1) = 0$$

$$= 0$$

This is 2 eqns in x, y ✓

$$\begin{cases} 18x + x + y = 8 + 11 & (7) \\ 4y + x + y = 11 \end{cases}$$

$$\begin{cases} 17x + y = 19 \\ x + 5y = 11 \end{cases}$$

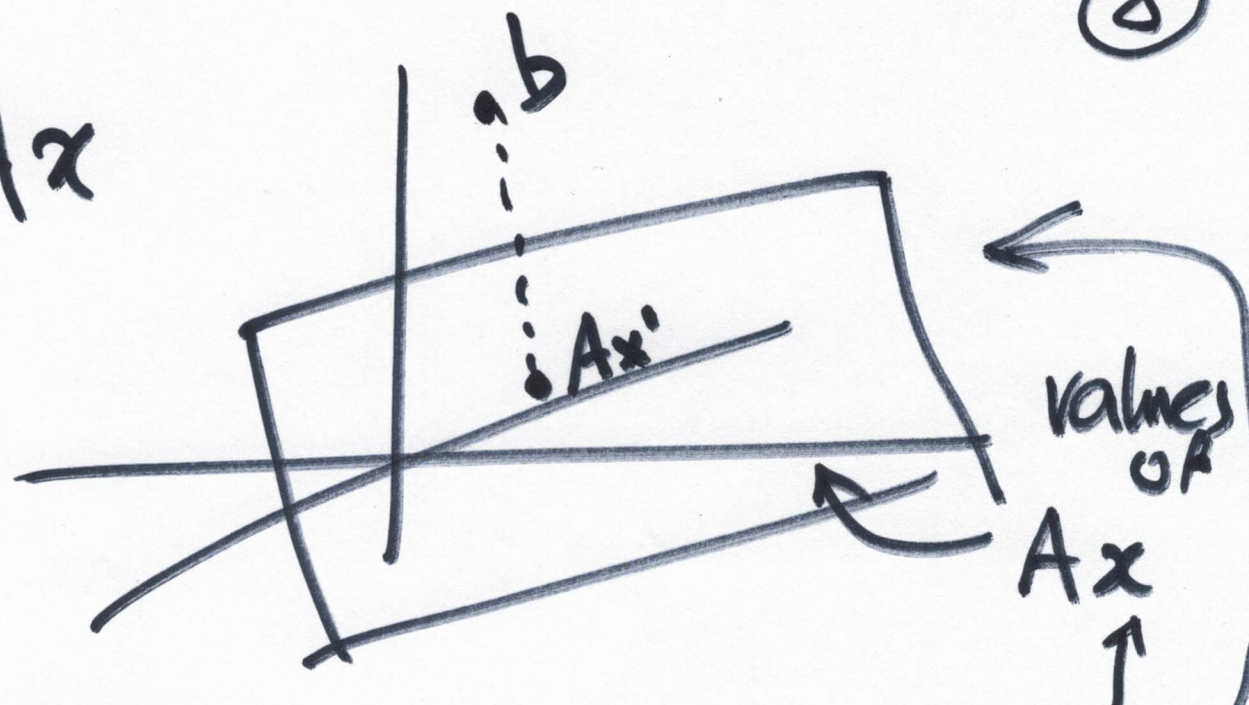
~~(Some mistake in arithmetic
in homework)~~

Solution is $(x, y) = (1, 2)$

How does this work more abstractly?

(need this if numbers or # of variables gets big)

Ax



find x st. Ax as close as possible to b .
 \Rightarrow projection of b on this subspace

$\Rightarrow Ax' - b$ is perpendicular to all vectors in ~~Ax~~ span of columns of A .

\Rightarrow Scalar product of columns of A with $Ax' - b$ is zero.

$$A^T (Ax' - b) = 0 \quad (9)$$

$$A^T A x' = A^T b$$

Remark If A is arbitrary ~~(not square)~~ }
the $A^T A$ is always square

$$A = \begin{pmatrix} a & b \\ c & d \\ e & f \end{pmatrix}$$

$$A^T = \begin{pmatrix} a & c & e \\ b & d & f \end{pmatrix}$$

$$A^T A = \begin{pmatrix} a & c & e \\ b & d & f \end{pmatrix} \begin{pmatrix} a & b \\ c & d \\ e & f \end{pmatrix}$$

$$= \begin{pmatrix} \vdots & \vdots \end{pmatrix} \text{ square.}$$

Therefore

$$A^T A x = A^T b$$

is a $n \times n$ system which we can solve.

Conclusion If $Ax = b$

⑩

is a system with more eqns than unknowns then it is usually incompatible.

In order to find x s.t. Ax is as close possible to b we must solve

$$A^T A x = A^T b$$

(normal equations)

This is how the orbit of Ceres was found.

Example Let us redo

using normal equations

$$\begin{cases} 4x + 0y = 2 \\ 0x + 2y = 0 \\ x + y = 11 \end{cases}$$

$$A = \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix}$$

$$b = \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix}$$

(11)

$$A^T A = \begin{pmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 17 & 1 \\ 1 & 5 \end{pmatrix}$$

$$A^T b = \begin{pmatrix} 4 & 0 & 1 \\ 0 & 2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \\ 11 \end{pmatrix} = \begin{pmatrix} 19 \\ 11 \end{pmatrix}$$

Normal eqns

$$\begin{pmatrix} 17 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 19 \\ 11 \end{pmatrix}$$

~ Solution is $(x, y) = (1, 2)$

Remark If $A^T A$ is invertible

then

$$x = (A^T A)^{-1} A^T b$$

this happens when A has maximum rank

(12)

Remark Incompatible systems
like the ones above are
sometimes called "over
determined"

In applications, where observations
are noisy, you do not
want 3 eqns for 3 unknowns

Because if observations are
a bit wrong then 3 eqns
will be a bit wrong &
solutions could be very wrong.

⇒ Want many eqns
for 3 unknowns.

Applications of linear algebra (13)

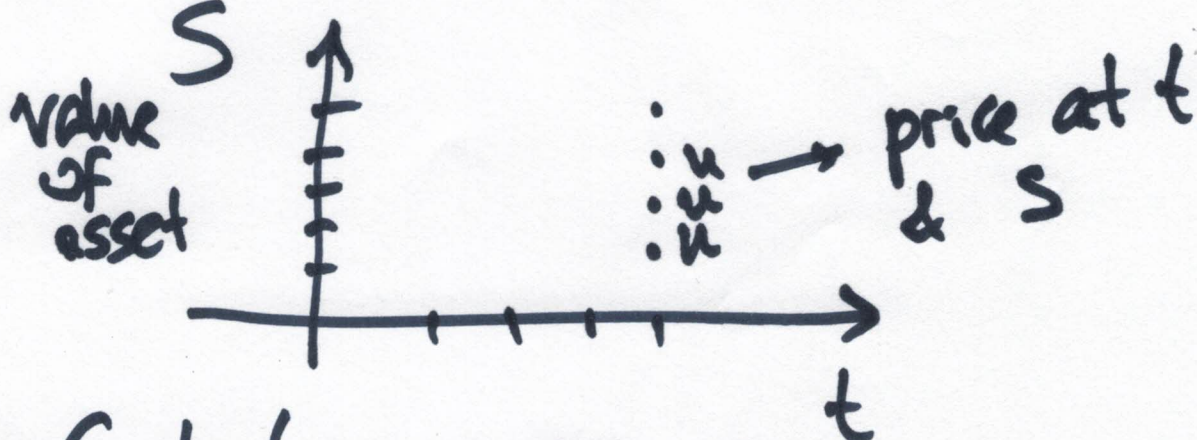
→ linear algebra is everywhere

Some examples

In Finance in pricing derivatives
need to solve Partial Differential
Equations ($\frac{du}{dt}$, $\frac{du}{dS}$, ...)

Often cannot find an analytical
solution → Need to approximate

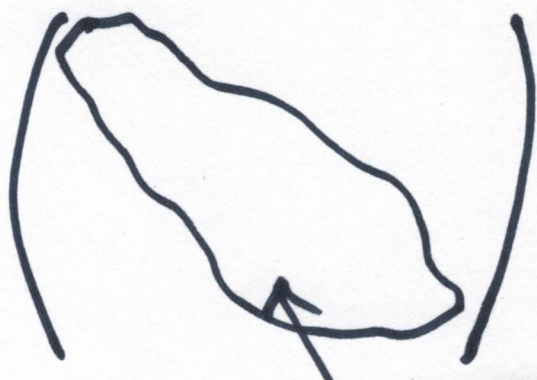
end up discretizing space & time



⇒ Get linear Equations

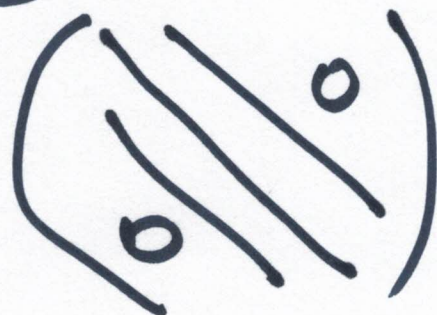
200 unknowns \times 200 eqns (14)
 \times 200

They are "sparse linear equations"



non zero
only in some
region.

tridiagonal
systems



In math Fibonacci sequence

$$x_0 = 1, x_1 = 1, x_n = x_{n-1} + x_{n-2}$$

$$x_2 = 2, x_3 = 3, x_4 = 5, x_5 = 8, \dots$$

How do these numbers grow?

Nice way to solve this:

Can we convert this to a
recurrence with 1 step?

let us use vectors:

(15)

$$\begin{pmatrix} x_n \\ x_{n+1} \end{pmatrix} = \begin{pmatrix} \rightarrow \\ \rightarrow \end{pmatrix}$$

$$\begin{pmatrix} x_{n+1} \\ x_n \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_n \\ x_{n-1} \end{pmatrix}$$

In particular

$$\begin{pmatrix} x_2 \\ x_1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} x_3 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} x_4 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

So

$$\begin{pmatrix} x_{n+1} \\ x_n \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}^n \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

If we can calculate $\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}^n$ we can get closed form for x_n .

To do this, we diagonalise $\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} & \\ & \end{pmatrix}^{-1} \begin{pmatrix} 1.61 & \\ & 0.61 \end{pmatrix} \begin{pmatrix} & \\ & \end{pmatrix}$$

eigen values eigen vectors

Eigenvalues

$$0 = \begin{vmatrix} 1-x & 1 \\ 1 & -x \end{vmatrix} = x^2 - x - 1 \quad \leadsto \quad x^{-1} = 1+x$$

$$x = \frac{1 \pm \sqrt{1+4}}{2} = \frac{1 \pm \sqrt{5}}{2} = \begin{matrix} 1.61... \\ 0.61... \end{matrix} \quad \begin{matrix} \Rightarrow \sigma \\ \text{"}\sigma^{-1}\text{"} \end{matrix}$$

Golden ratio: σ

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} & \\ & \end{pmatrix}^{-1} \begin{pmatrix} 1.61 & \\ & 0.61 \end{pmatrix} \begin{pmatrix} & \\ & \end{pmatrix}$$

Eigen vectors

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \sigma x \\ \sigma y \end{pmatrix}$$

→ non zero solution
→ only 1 indep egn.

$$\begin{matrix} \curvearrowright \\ x+y = \sigma x \end{matrix}$$

$$(1, \sigma-1)$$

other

$$(1, \sigma^{-1}-1)$$

So

$$\begin{pmatrix} x_{n+1} \\ x_n \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ \sigma^{-1} & \sigma^{-1} \end{pmatrix}^{-1} \begin{pmatrix} \sigma^n \\ (\sigma^{-1})^n \end{pmatrix} \begin{pmatrix} 1 \\ \sigma^{-1} \end{pmatrix}$$

& doing "the algebra"

we get $x_n = \dots \sigma^n + \dots + \sigma^{-n}$
(homework)

where $\sigma = 1.61$ golden ratio
 $\sigma^{-1} = 0.61$

These same ideas work for any recurrence

$$\begin{cases} x_{n+1} = 3x_n - 4x_{n-1} + 7x_{n-2} \\ x_0 = x_1 = x_2 = 3 \end{cases}$$

(here will use vectors of size 3)

Newton Raphson

$f(x) = 3$

~~$\sin x = 3$~~

$x_0 = 1$

$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

→ solution.