

Main Examination period 2019 MTH4115/MTH4215: Vectors & Matrices

Duration: 2 hours

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You should attempt ALL questions. Marks available are shown next to the questions.

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Complete all rough work in the answer book and cross through any work that is not to be assessed.

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Question 1. [20 marks] Let A, B, C be points in 3-space with respective position vectors $\mathbf{a} = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}, \mathbf{b} = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}, \mathbf{c} = \begin{pmatrix} -1 \\ -3 \\ -2 \end{pmatrix}$. Determine: (a) The length of the vector $3\mathbf{a} - \mathbf{b}$; (b) A unit vector in the direction of \mathbf{b} ; (c) $\mathbf{a} \cdot \mathbf{b}$;

- (d) $\mathbf{a} \times \mathbf{b}$; [3]
- (e) A vector equation for the line through *A* and *B*; [4]
- (f) The coordinates of the point *D* such that *ABCD* is a parallelogram. [4]

Question 2. [20 marks] Suppose that vectors $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}$ and $\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$ are given.

(a)	Write down an expression for the scalar product $\mathbf{u} \cdot \mathbf{v}$ (in terms of the coordinates of \mathbf{u} and \mathbf{v}).	[3]
(b)	What does it mean to say that two vectors are orthogonal ?	[3]
(c)	Show that if a vector is orthogonal to all vectors, then it must be the zero vector.	[4]
(d)	How is the vector product u \times v defined (in terms of the coordinates of u and v)?	[3]
(e)	Show that $\mathbf{u} \times \mathbf{v}$ is orthogonal to \mathbf{u} .	[3]
(f)	Show that if u has the property that $\mathbf{u} \times \mathbf{v} = 0$ for all vectors v , then necessarily $\mathbf{u} = 0$.	[4]

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Question 3. [20 marks] Let Π_1 be the x-y plane (i.e. with equation z = 0), let Π_2 be the x-z plane (i.e. with equation y = 0), let Π_3 be the y-z plane (i.e. with equation x = 0), and let Π_4 be the plane with equation x + y + z = 1. Let Q be the point with position vector $\mathbf{q} = \begin{pmatrix} -3 \\ 2 \\ 1 \end{pmatrix}$. (a) Determine the distance between Q and Π_1 . [2] (b) Determine the distance between Q and Π_4 . [3] (c) Determine the coordinates of the point on Π_4 that is closest to Q. [3] (d) If A denotes the point in the intersection $\Pi_1 \cap \Pi_2 \cap \Pi_4$, and B denotes the point in the intersection $\Pi_1 \cap \Pi_3 \cap \Pi_4$, determine the coordinates of the mid-point *C* of *A* and *B*. [3] (e) If l denotes the line through the points C (from part (d) above) and Q, then determine the coordinates of the point in the intersection $l \cap \Pi_3$. [4] (f) Determine the coordinates of a point which is equidistant from the four planes Π_1, Π_2 , Π_3 , Π_4 (i.e. the point has the same distance from each of these planes). [5] Question 4. [20 marks] Consider the linear system (a) Write down the augmented matrix of the system. [3] (b) Bring the augmented matrix to reduced row echelon form, indicating the elementary [4] row operations used at each step. (c) Identify the leading and the free variables, and write down the solution set of the [4]

(d) Let l_1 , l_2 and l_3 be lines in 3-space, such that l_1 passes through (1, 4, -3) in the direction $\begin{pmatrix} 1\\2\\-1 \end{pmatrix}, l_2 \text{ passes through } (1,3,-2) \text{ in the direction } \begin{pmatrix} 2\\3\\-1 \end{pmatrix}, \text{ and } l_3 \text{ passes through}$ $(2,6,-4) \text{ in the direction } \begin{pmatrix} 2\\3\\-1 \end{pmatrix}.$

Write down parametric equations for each of these three lines.

(e) For the lines l_1 , l_2 , l_3 as in part (d) above, determine the intersection $l_1 \cap l_2$ of l_1 and l_2 , the intersection $l_1 \cap l_3$ of l_1 and l_3 , and the intersection $l_2 \cap l_3$ of l_2 and l_3 . [6]

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- system.

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Question 5. [20 marks] Let

$$A = \begin{pmatrix} 1 & 3 \\ -2 & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 2 & 0 \\ 0 & -1 \end{pmatrix}, \quad C = \begin{pmatrix} 2 & 0 & 0 & 3 \\ 9 & 0 & 1 & 8 \\ -8 & 2 & 4 & 5 \\ 3 & 0 & 0 & 5 \end{pmatrix}.$$

(a) For each of the products A², AB, BA, B², BC, CB, state whether or not it exists; if it exists then evaluate it.

(b)	Explain what it means for a matrix <i>M</i> to be invertible , and what is meant by the inverse	
	of <i>M</i> .	[4]
(c)	Calculate $det(C)$ and decide whether C is invertible or not.	[4]

- (d) Using part (c) above, evaluate $det(C^6)$ and det(3C). In each case, briefly explain which property of determinants you are using. [4]
- (e) Find det(D), where D is the matrix obtained from C by subtracting 13 times column 1 from column 4. Briefly explain which property of determinants you are using. [2]

End of Paper.