

Main Examination period 2018

MTH5112: Linear Algebra I

Duration: 2 hours

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You should attempt ALL questions. Marks available are shown next to the questions.

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Complete all rough work in the answer book and cross through any work that is not to be assessed.

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Question 1. [16 marks]

(a) Consider the system of linear equations

- (i) Write down the augmented matrix of the system. [2]
- (ii) Put the augmented matrix into reduced row echelon form (RREF), indicating which elementary row operation you have used at each step. [5]
- (iii) State which of the variables are leading variables and which are free variables, and write down the solution set of the system. [3]
- (b) Use the Gauss–Jordan algorithm to find the inverse of the matrix

$$A = egin{pmatrix} 1 & 2 & -2 \ 0 & -3 & 0 \ 0 & 0 & 1 \end{pmatrix}$$
 ,

indicating which elementary row operation you have used at each step. [6]

Question 2. [17 marks]

- (a) Suppose that *A* is an invertible matrix. Prove that the system of linear equations $A\mathbf{x} = \mathbf{0}$ has only the trivial solution. [5]
- (b) Consider the matrices

$$B = egin{pmatrix} 0 & 1 \ 2 & 4 \end{pmatrix}$$
 and $C = egin{pmatrix} -1 & 1 \ 3 & 0 \ 1 & 2 \end{pmatrix}$.

- (i) Compute the matrix $B^T 2B$.
- (ii) For each of the matrix products

| entite compute the product, of explain with it is not defined. | either comp | oute the product, | or explain why | it is not defined. | [4] |
|--|-------------|-------------------|----------------|--------------------|-----|
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(c) Give examples of the following:

- (i) a symmetric 3×3 matrix; [3]
- (ii) an upper triangular 3×3 matrix. [3]

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[2]

Question 3. [18 marks]

(a) Consider the matrix

$$A = \begin{pmatrix} 7 & -5 & 1 & 4 \\ 0 & 0 & 4 & 0 \\ 3 & -1 & 2 & 2 \\ 0 & 1 & -6 & 0 \end{pmatrix}.$$

- (i) Compute the determinant of *A*. [4]
 (ii) Using your answer to part (i), explain whether *A* is invertible or not. (Do not attempt to compute the inverse.) [2]
- (b) Suppose that *B* is a square matrix with det(B) = 5. Compute the following:

| (i) $det(B^3)$; | | [2] |
|---------------------|---|-----|
| (ii) det (B^{-1}) | ; | [2] |

- (iii) $\det(B^T)$. [2]
- (c) Suppose that *C* is a 4×4 matrix with det(*C*) = 3. Compute the determinants of the following matrices:
 - (i) the matrix obtained by swapping the first and second rows of *C*; [2]
 - (ii) the matrix obtained by multiplying the fourth row of C by -6; [2]
 - (iii) the matrix obtained by subtracting the third row of *C* from the first row. [2]

Question 4. [15 marks]

(a) Prove that

$$H = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 : x + y + z = 0 \right\}$$

is a subspace of \mathbb{R}^3 .

- (b) Write down a set of five linearly independent vectors in R⁴, or explain why it is impossible to do so. [4]
- (c) Consider the matrix

$$A = \begin{pmatrix} 1 & -1 & 5 & 2 & 0 \\ 0 & 1 & -4 & -2 & 1 \\ 0 & 0 & 0 & 1 & 6 \\ 0 & 0 & 0 & -1 & -6 \end{pmatrix}.$$

(i) Write down a basis for the row space of *A*, and determine the rank of *A*. [3]

(ii) Using your answer to part (i), determine the nullity of *A*. [3]

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[5]

Question 5. [16 marks] Consider the matrix

$$A = \begin{pmatrix} 1 & 3 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

- (a) Find the eigenvalues of *A*.
- (b) For each of the eigenvalues of *A*, find a basis for the corresponding eigenspace. [6]
- (c) Using your answer to part (b), find an invertible matrix *P* and a diagonal matrix *D* such that $P^{-1}AP = D$, or explain why this is impossible. [6]

Question 6. [18 marks]

(a) Consider the vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \in \mathbb{R}^3$ given by

$$\mathbf{v}_1 = \begin{pmatrix} 1\\1\\1 \end{pmatrix}, \quad \mathbf{v}_2 = \begin{pmatrix} 2\\0\\-2 \end{pmatrix}, \quad \mathbf{v}_3 = \begin{pmatrix} 1\\-2\\1 \end{pmatrix}.$$

(i) Show that $\mathcal{B} = {\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3}$ is an orthogonal basis for \mathbb{R}^3 . [6]

- (ii) Write down the transition matrix from \mathcal{B} to the standard basis of \mathbb{R}^3 . [4]
- (iii) Find the best approximation to the vector

$$\mathbf{w} = \begin{pmatrix} 1\\0\\2 \end{pmatrix}$$

by vectors in the subspace $H = \text{span}(\mathbf{v}_1, \mathbf{v}_2)$ of \mathbb{R}^3 .

(b) Let $A \in \mathbb{R}^{m \times n}$ and $\mathbf{b} \in \mathbb{R}^m$, and suppose that the system of linear equations

$$A\mathbf{x} = \mathbf{b}$$

has no solutions. What does it mean to say that a vector $\mathbf{x} \in \mathbb{R}^n$ is a **least** squares solution of such a system?

[4]

[4]

End of Paper.

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[4]