

Q1 (a)(i)  $\dot{x} = \sin(x) - \sinh(x) (= f(x))$

$f(0) = 0$  and  $f'(x) = \cos(x) - \cosh(x) \leq \cos(x) - 1 \leq 0$ .

$\therefore f$  is decreasing and  $f(x) > 0, x < 0$  &  $f(x) < 0, x > 0$

$\therefore x = 0$  is globally stable

seen examples like this



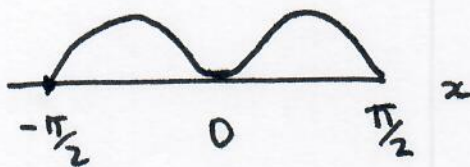
(ii)  $\dot{x} = \cos(x)(1 - \cos(x)) (= f(x))$

$\text{sgn}(f(x)) = \text{sgn}(\cos(x))$  except for  $x = n\pi$ . (double zero)

So  $\dot{x} > 0$  on  $x \in (-\pi/2, \pi/2) \setminus \{0\}$ , + translates by  $2\pi$

$\dot{x} < 0$  on  $x \in (\pi/2, 3\pi/2)$  + translates by  $2\pi$ .

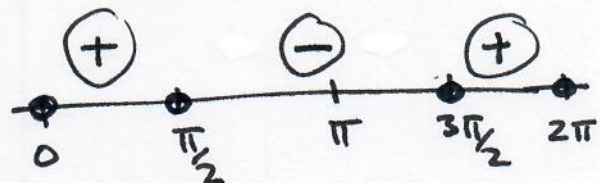
seen exs like this



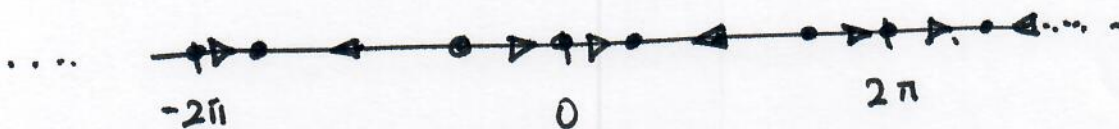
+ translates of  $2\pi$



We obtain a sequence



We get the following phase portrait



(b) The diagram indicates a possible scenario:

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$$\begin{array}{ll} \dot{x} > 0 & x < 0 \\ \dot{x} > 0 & 0 < x < 1 \\ \dot{x} > 0 & 1 < x < 2 \\ \dot{x} > 0 & 2 < x \end{array}$$



Possible system

$$\dot{x} = (x-0)(x-1)(x-2)^2$$

seen examples like this

(c)  $(x-0)(x-1)^2(x-2)^2(x-3)(x-4)^2$

(d) Let  $x_0 = \sup\{x \mid f(x) = 0\}$ . Either  $x_0 = \max\{x \mid f(x) = 0\}$  or  $\exists x_n, f(x_n) = 0$  such that  $x_n \rightarrow x_0$  as  $n \rightarrow \infty$ .  $f$  is differentiable and  $\therefore$  continuous  $\Rightarrow f(x_0) = 0$

Moreover,  $f(x) \neq 0$  for  $x > x_0$ . Note  $f(x) > 0$  for  $x > x_0$ .  $\therefore f(x) > 0$  for  $x > x_0$ , otherwise contradiction by intermediate value theorem.

Not seen

(e) for  $\dot{\theta} = f(\theta)$ ,

$$\dot{\theta} > 0 \quad 0 \leq \theta < \frac{\pi}{2}$$

$$\dot{\theta} > 0 \quad \frac{\pi}{2} < \theta < \pi$$

$$\dot{\theta} < 0 \quad \pi < \theta < \frac{3\pi}{2}$$

$$\dot{\theta} < 0 \quad \frac{3\pi}{2} < \theta < 2\pi$$

$$\text{So } \dot{\theta} = \sin \theta \text{ gives } \dot{\theta} > 0 \quad 0 < \theta < \pi$$

$$\text{and } \dot{\theta} < 0 \quad \pi < \theta < 2\pi$$

but has only two fixed points at  $\theta = 0$  &  $\theta = \pi$  on  $S^1$ . Introduce multiplicative factors which are positive except for  $\theta = \frac{\pi}{2}$  &  $\theta = \frac{3\pi}{2}$ .

$$\text{Consider } \dot{\theta} = \sin \theta (1 - \cos(\theta - \frac{\pi}{2})) (1 - \cos(\theta - \frac{3\pi}{2}))$$

unseen example  
but technique for  
"squeezing" function  
shown in tutorial

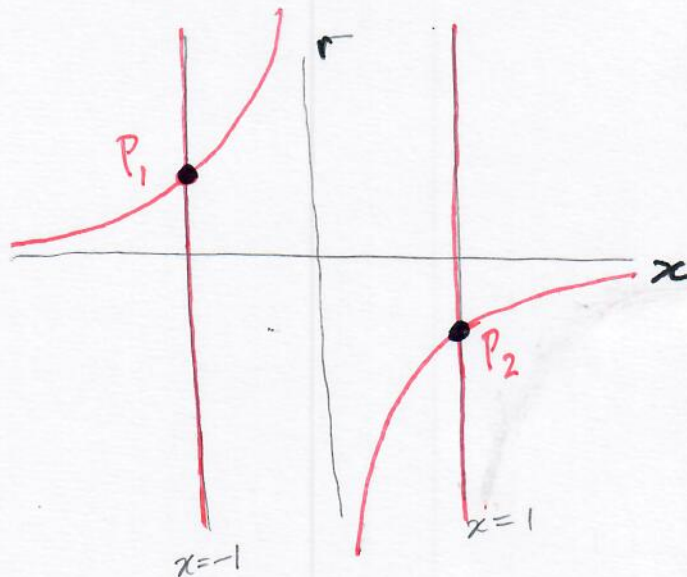
Q2 (a) (i)  $\dot{x} = 1 + rx - x^2 - rx^3 (= f_r(x))$  (1)

(4)

$$\dot{x} = (1+rx)(1-x^2)$$

Fixed pt sets are given by either

$$1+rx = 0 \text{ or } 1-x^2 = 0$$



Fixed pts in  
x-r-plane

Examples seen  
of (a) (i) - (iv)  
a(v) only briefly  
mentioned "singular"  
perturbations

(ii)

$P_1 = (-1, 1)$  &  $P_2 = (1, -1)$  have double roots of  
 $f(x)$ .

(iii)  $\Rightarrow P_1, P_2$  are potential bifurcation pts for (1)  
above.

Taylor expansion of (1)

Let  $y = x + 1$ ,  $\mu = r - 1$ , then

$$\begin{aligned} f_r(x) = f(x, r) &= 1 + (\mu+1)(y-1) - (y-1)^2 - (\mu+1)(y-1)^3 \\ &= 1 + \mu y + \mu + y - 1 - y^2 + 2y - 1 \\ &\quad - (\mu+1)(y^3 - 3y^2 + 3y - 1) \\ &= \boxed{1} + \mu y - \mu + \boxed{y-1} - y^2 + \boxed{2y-1} \\ &\quad - \mu y^3 + 3\mu y^2 - 3\mu y + \mu \\ &\quad - y^3 + 3y^2 - 3y + \boxed{1} \end{aligned}$$

Collecting

$$\begin{aligned} \text{Terms} &= \mu y - y^2 - \mu y^3 + 3\mu y^2 - 3\mu y \\ &\quad - y^3 + 3y^2 \end{aligned}$$

$$= -2\mu y + 2y^2 - \mu y^3 + 3\mu y^2 - y^3$$

So we get  $A = \frac{\partial f}{\partial r}(P_1) = 0$ ,  $B \frac{\partial^2 f}{\partial x^2}(P_1) = 2$

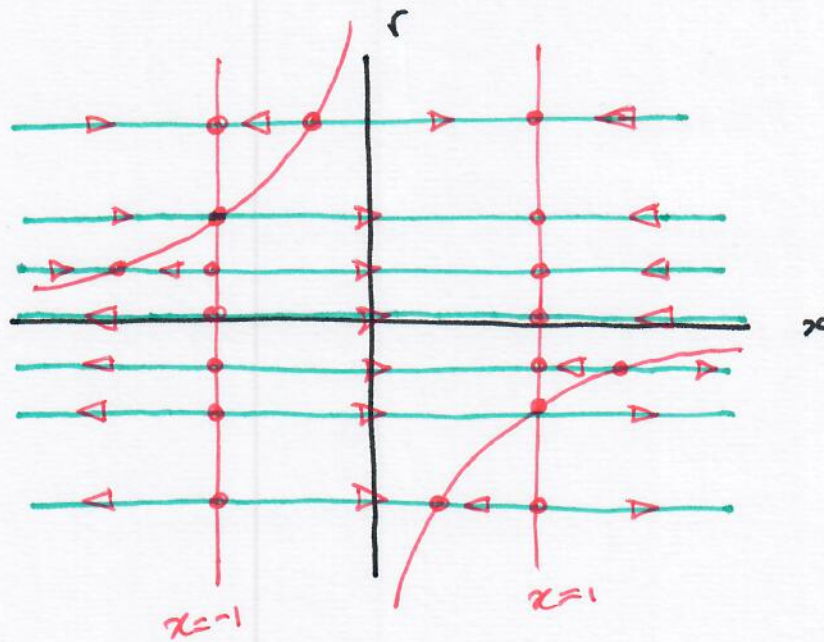
and  $C = \frac{\partial^3 f}{\partial x \partial r}(P_1) = -2$

∴ Transcritical at  $P_1$

Similar analysis at  $P_2$  also gives transcritical

with  $A = 0$ ,  $B = 2$ ,  $C = -2$ .

(iv)



(v) As  $r \rightarrow 0$  from either  $< 0$  or  $> 0$ , one of the fixed points moves off to  $\infty / -\infty$  (for  $r < 0 / r > 0$ )

$$(b) \quad \dot{x} = Ax + Bx^2 + Cxr = f(x, r), \quad A, B \neq 0 \quad (6)$$

Note  $f(0,0) = 0$  and  $\frac{\partial f}{\partial x}(0,0) = 2Bx + Cr \Big|_{(0,0)} = 0$ .

So we have a potential bifurcation.

Let  $y = \left(x + \frac{Cr}{2B}\right)$ , then

$$\begin{aligned} \dot{y} = \dot{x} &= Ar + B\left(y - \frac{Cr}{2B}\right)^2 + C\left(y - \frac{Cr}{2B}\right)r \\ &= Ar + B\left(y^2 - \frac{Cry}{B} + \frac{C^2r^2}{4B^2}\right) + Cy r - \frac{C^2r^2}{2B} \\ &= Ar + By^2 + \frac{C^2r^2}{4B} - \frac{C^2r^2}{2B} \\ &= Ar - \frac{C^2r^2}{2B} + By^2 \end{aligned}$$

Let  $y = \alpha z$

$$\dot{y} = \alpha \dot{z} = \alpha \left( Ar - \frac{C^2r^2}{2B} \right) + B\alpha^2 z^2$$

Let  $B\alpha = 1$ , i.e.  $\alpha = \frac{1}{B}$ , ( $B \neq 0$  given)

$$\dot{z} = \frac{A}{B}r - \frac{C^2r^2}{2B^2} + z^2$$

Let  $v = \frac{A}{B}r - \frac{C^2r^2}{2B^2}$

(non-singular change of parameter at  $r=0$ )

$$\frac{\partial v}{\partial r} \Big|_{r=0} = \frac{A}{B} \neq 0$$

$$\therefore \dot{z} = v + z^2$$

Completing the square mentioned but not seen in detail

Q3 (a)  $\dot{x} = y, \dot{y} = -x^3 + x + y$

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Fixed pt  $\dot{x} = 0, \dot{y} = 0$

$y = 0, x^3 = x \Rightarrow x = 0, \pm 1$

Jacobian matrix  $J = \begin{bmatrix} 0 & 1 \\ -3x^2 + 1 & 1 \end{bmatrix}$

at  $(0,0)$ :  $J = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$  E-eq<sup>n</sup>  $\lambda^2 - \lambda - 1 = 0$

Eigenvalues  $\lambda_1 = \frac{1}{2}(1 + \sqrt{5}), \lambda_2 = \frac{1}{2}(1 - \sqrt{5})$

Eigenvectors  $v_1 = (\frac{1}{2}(-1 + \sqrt{5}), 1) = (0.62, 1) \quad \Delta \quad v_2 = (\frac{1}{2}(-1 - \sqrt{5}), 1) = (-1.62, 1)$

at  $(1,0)$ :  $J = \begin{bmatrix} 0 & 1 \\ -2 & 1 \end{bmatrix}$  E-eq<sup>n</sup>  $\lambda^2 - \lambda + 2 = 0$

Eigenvalues:  $\lambda_1 = \frac{1}{2}(1 + i\sqrt{7}), \lambda_2 = \frac{1}{2}(1 - i\sqrt{7})$

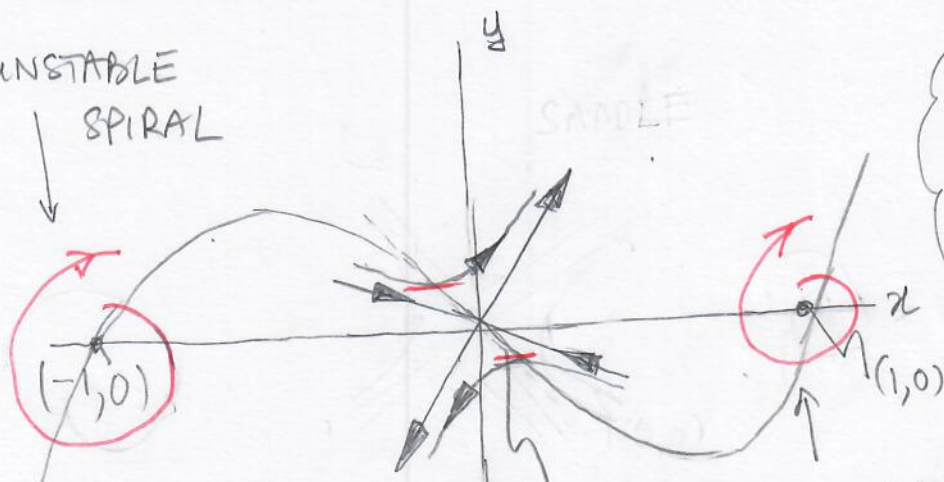
Eigenvectors:  $v_1 = \frac{1}{4}(1 + i\sqrt{7}), v_2 = \frac{1}{4}(1 - i\sqrt{7})$

at  $(-1,0)$ : same as  $(1,0)$

(b)

UNSTABLE SPIRAL

SADDLE



NOTE  $\dot{x} = y$  implies left  $\rightarrow$  right for  $y > 0$  and right-left for  $y < 0$

(c)(i)

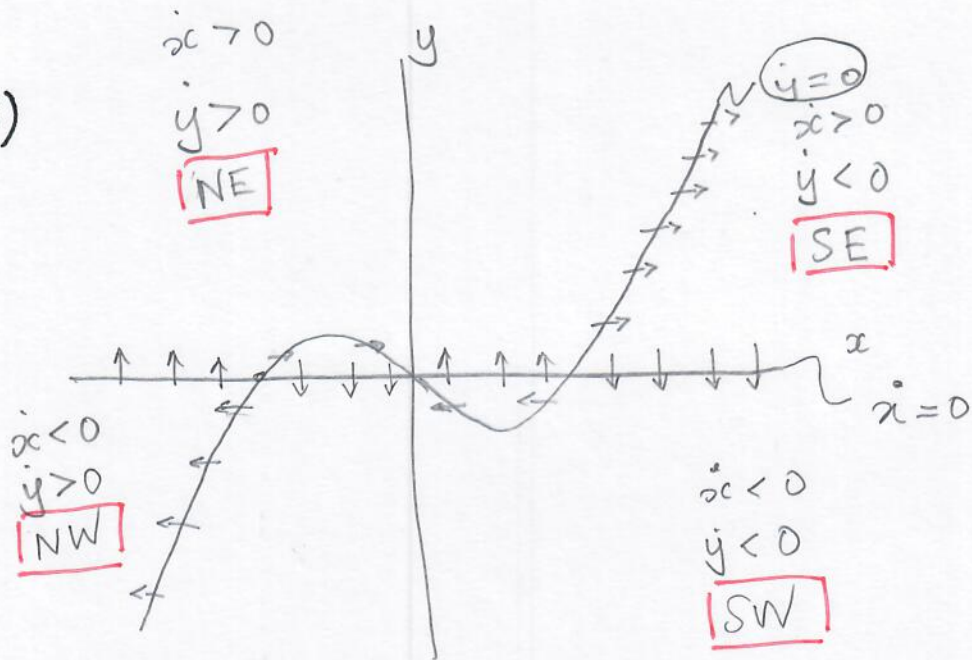
$\dot{x} = 0 \Rightarrow y = 0$  (vertical)

$\dot{y} = 0 \Rightarrow y = x^3 - x$  (horizontal)

Slope -1

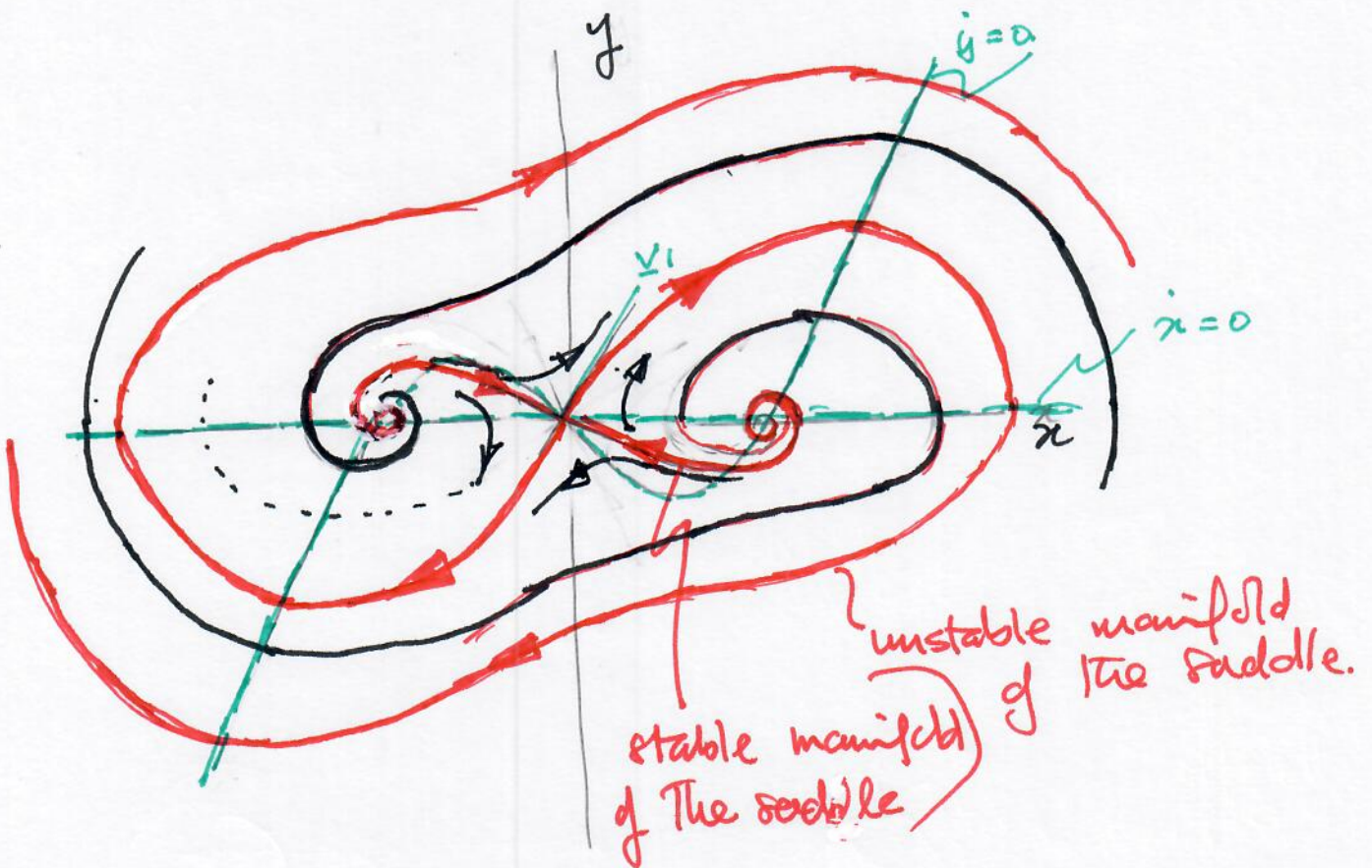
UNSTABLE SPIRAL

(c)  
(ii & iii)



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(d)



seen technique but not the system.