

$\dot{x} = f(x)$ , differentiable  $f$

Dynamics of  $x$ , needed the regions of  $+$ ,  $-$ ,  $=0$  of  $f$

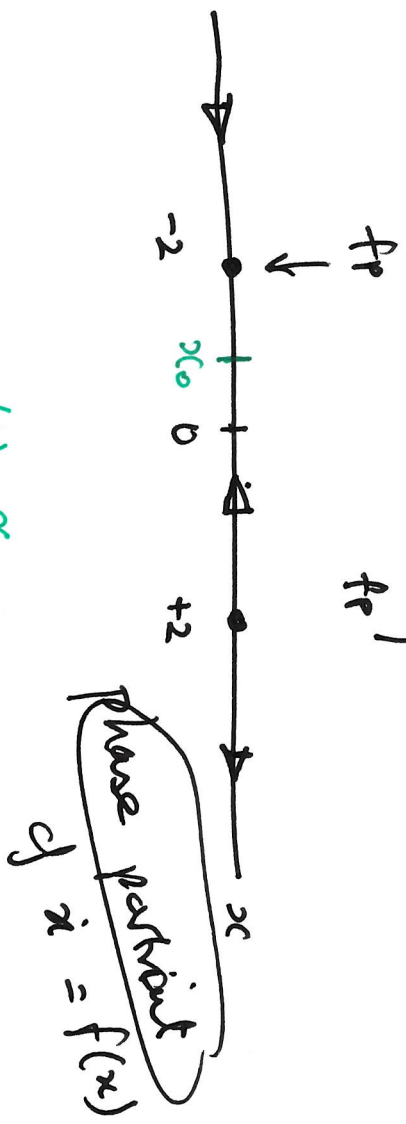
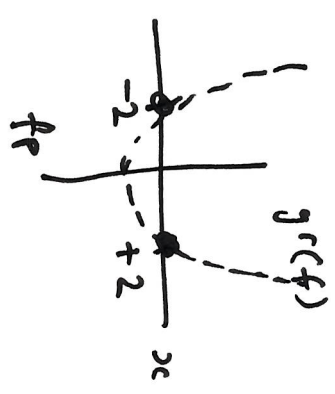
$g_r(f)$  was vital.

2.2.1 (Strogatz p 37)

$$\boxed{\dot{x} = 4x^2 - 16} = 4(x-2)(x+2)$$

zeros of  $f$   
 = fixed pts of  $\dot{x} = f(x)$

$f(x_0) = 0 \Leftrightarrow x(t) = x_0$  is a solution  
 "fixed pt"



$x(t), x(0) = x_0$   
 $t \rightarrow \infty, x(t) \rightarrow -2$   
 $t \rightarrow -\infty, x(t) \rightarrow 0$

T.1.2

$$\frac{dx}{dt} = 4(x^2 - 4)$$

Calculus  $\rightarrow \int \frac{dx}{(x-2)(x+2)} = \int 4 dx$

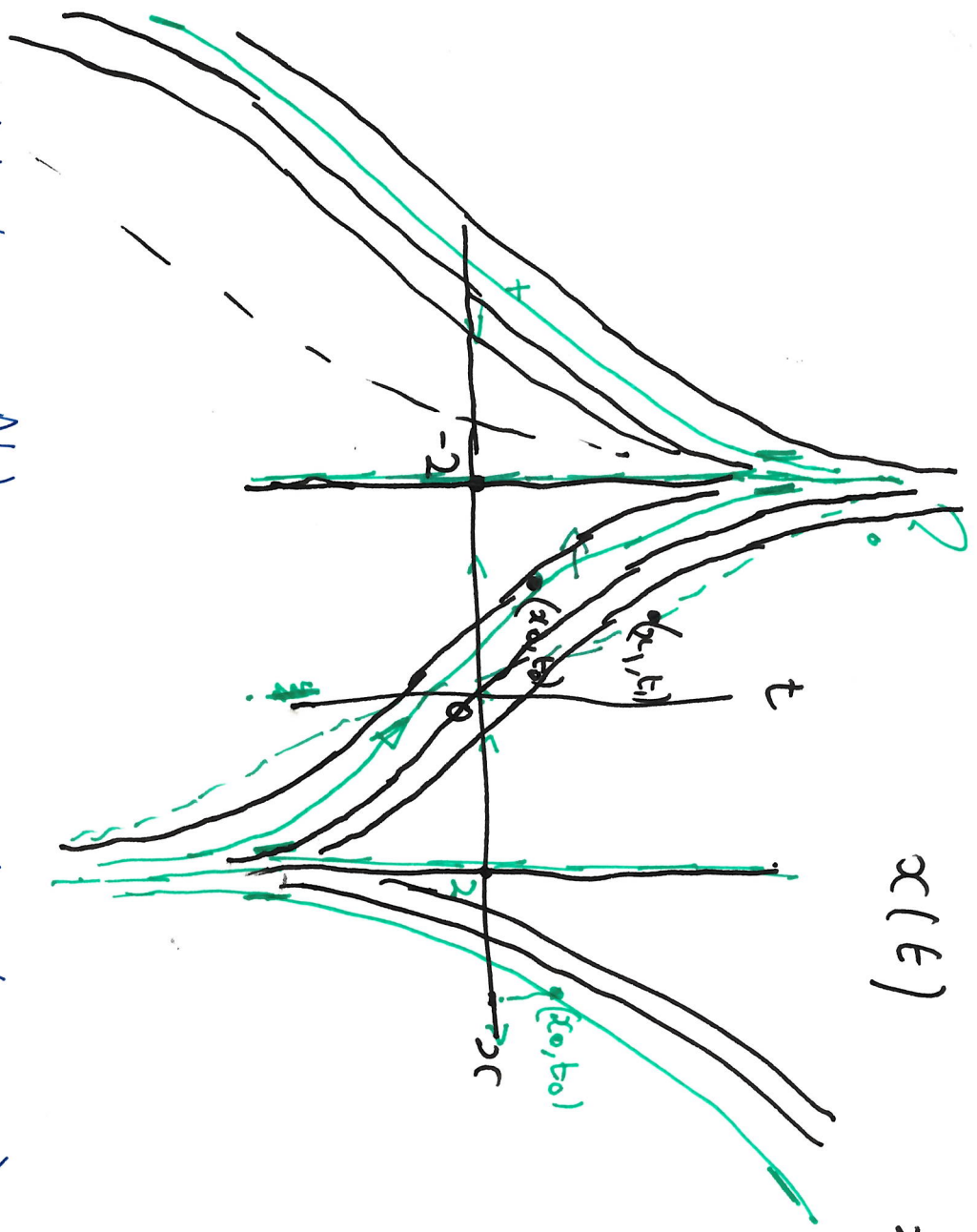
$$x(t)$$

$$x = x_0, t = t_0$$

initial conditions

$$x(t) \equiv 2$$

try the calculus



Mathematics Alpha

Streamplot (y, -x)

Example ~~1.2~~ 1.2.  
 $\dot{x} = y, y = -x$

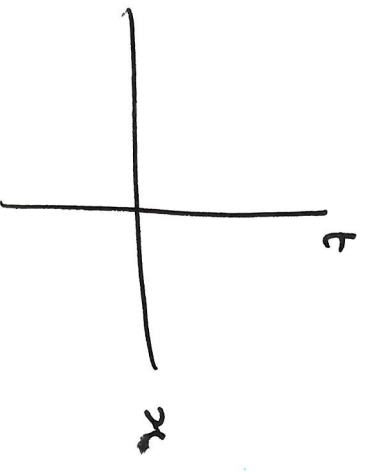
T1.3

Suppose  $x(t)$  is a solution to  $\dot{x} = f(x)$  } check that

Then  $x(t+c)$  is also a solution of  $\dot{x} = f(x)$ .

$x(t+c)$  is a translate of  $x(t)$  in the  $t$ -direction

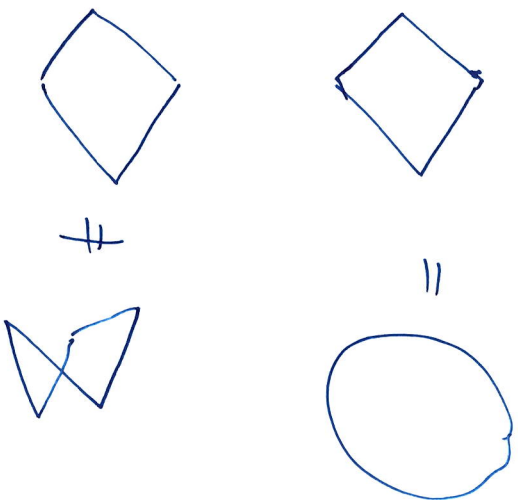
Once you have sketched one curve between two fixed (two vertical lines) all the other solution curves are (t)-translated versions



# Ex 2

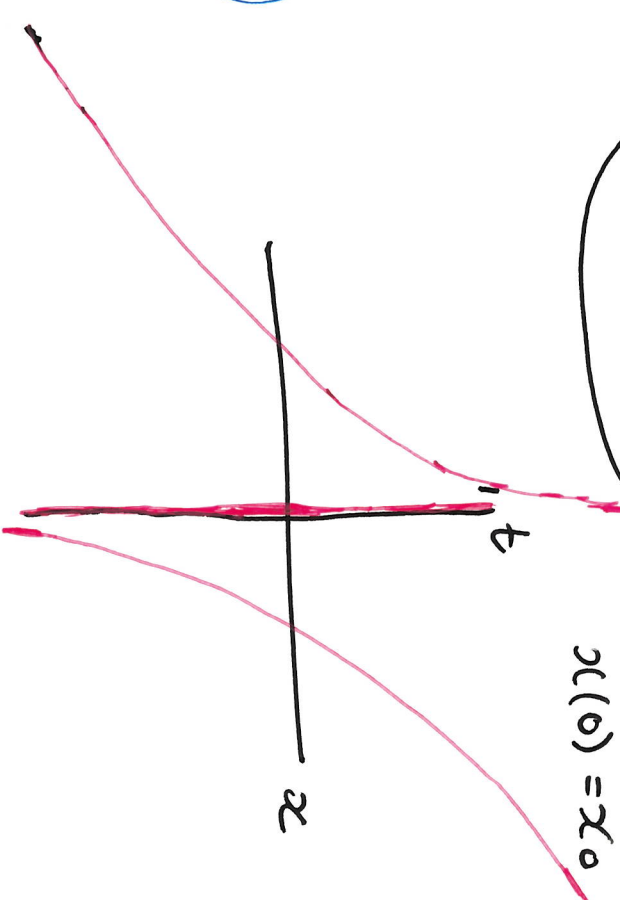
$$\begin{cases} \dot{x} = x^2 \\ \dot{y} = x^4 \\ \dot{z} = x^6 \\ \vdots \end{cases}$$

Top



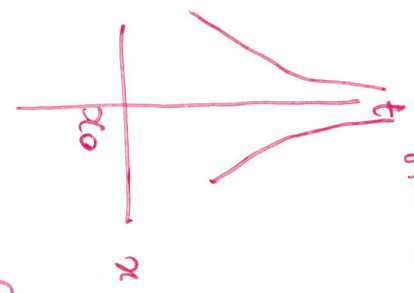
$t \rightarrow -\infty \quad x \rightarrow -\infty$   
 $t \rightarrow \infty \quad x \rightarrow 0$

$t \rightarrow -\infty \quad x(t) \rightarrow 0$   
 $t \rightarrow +\infty \quad x(t) \rightarrow \infty$   
 $x(0) = x_0$



**(11.5)**  
 unstable fixed point

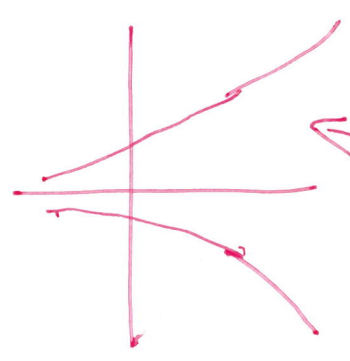
stable fixed pt



unstable fixed pt

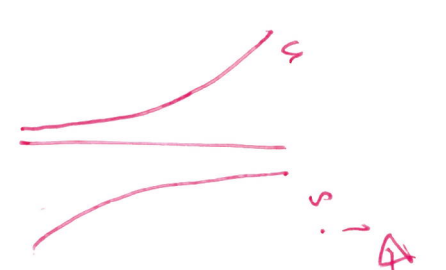
(1)

(2)



$\dot{x} = -x$  stable

$\dot{x} = +x$  unstable



(1)