## MTH5123 Differential Equations Exam 2017: Solution and Marking Scheme

All problems are modifications of problems that have been seen in the lectures and in the exercise classes

- a) Find the general solution of the homogeneous ordinary differential equation (ODE) y" + 2y' - 15y = 0. [5 marks]
   Solution: The characteristic equation is λ² + 2λ - 15 = 0 [1], which has two real roots: λ₁ = -5 and λ₂ = 3 [2]. The general solution of the homogeneous equation is thus given by y<sub>h</sub>(x) = c₁e<sup>-5x</sup> + c₂e<sup>3x</sup> [2].
  - b) Find the general solution of the inhomogeneous ODE  $y'' + 2y' 15y = -4e^x$ . [11 marks]

**Solution:** Since the function  $e^x$  is not a solution of the homogeneous equation [2], we may use the *educated guess* method and look for a particular solution of the inhomogeneous equation in the form of  $y_p(x) = d_0 e^x$  [2]. Substituting back into the inhomogeneous equation gives on the left-hand side  $e^x d_0(1+2-15) = -12d_0 e^x$  [2]. To match the right-hand side we have to choose  $d_0 = 1/3$  so that  $y_p(x) = e^x/3$  [2]. The general solution of the inhomogeneous equation is given by the sum  $y_g(x) = y_h(x) + y_p(x)$  [1] yielding

$$y_g(x) = c_1 e^{-5x} + c_2 e^{3x} + \frac{1}{3} e^x$$
. [2]

c) Find the general solution of the first order homogeneous linear ODE  $y' = \tan(x) y$ . [5 marks]

**Solution.** The homogeneous ODE  $y' = \tan(x)y$  is separable [1]. Following the standard procedure we introduce on the left-hand side  $H(y) = \int \frac{dy}{y} = \ln |y|$  [1]. Solving H(y) = u we find  $y = \pm e^u = H^{-1}(u)$ . On the right-hand side we have (see the formula sheet)

$$\int \tan x \, dx = -\ln|\cos x| + C \,. \quad [1]$$

Hence the general solution of the homogeneous equation is given by

$$y_h(x) = H^{-1}\left(-\ln|\cos x| + C\right) = \pm e^C \frac{1}{|\cos x|} = D \frac{1}{|\cos x|}, \quad [2]$$

where we denoted by  $D = \pm e^C$  the constant of arbitrary sign.

d) Use the solution in c) to solve the initial value problem for the first order linear inhomogeneous ODE  $y' = \tan(x) y + \sin x$ ,  $-\pi/2 < x < \pi/2$ , y(0) = 1 by the variation of parameters method. [4 marks]

**Solution.** According to the variation of parameters method we look for a solution of the inhomogeneous ODE in the form of

$$y = \frac{D(x)}{\cos x} \,.$$

Differentiating yields

$$y' = \frac{D'(x)}{\cos x} + D(x)\frac{\sin x}{\cos^2 x}$$
. [1]

Substituting back into the equation  $y' = \tan x \, y + \sin x$  we have

$$\frac{D'(x)}{\cos x} + D(x)\frac{\sin x}{\cos^2 x} = \frac{D(x)}{\cos x}\tan x + \sin x ,$$

which implies

$$D'(x) = \cos x \sin x \quad \Rightarrow \quad D(x) = \frac{1}{2} \sin^2 x + C \,.$$
 [1]

This gives for the general solution of the inhomogeneous ODE

$$y_g(x) = \frac{1}{\cos x} \left(\frac{1}{2}\sin^2 x + C\right)$$
. [1]

As y(0) = C = 1, we find the solution of the initial value problem

$$y_g(x) = \frac{1}{\cos x} \left( \sin^2 x + 1 \right) .$$
 [1]

2. a) Find all functions f(y) such that the following differential equation becomes exact:

$$x^{2} + \frac{f(y)}{x} + \ln(xy)\frac{dy}{dx} = 0$$
 ,  $x > 0, y > 0$ . [5 marks]

**Solution:** Denoting  $P(x, y) = x^2 + \frac{f(y)}{x}$ ,  $Q(x, y) = \ln(xy)$  [2] we have  $\frac{\partial P}{\partial y} = \frac{1}{x} \frac{df(y)}{dy}$ , whereas  $\frac{\partial Q}{\partial x} = \frac{1}{x}$  [2]. Hence the equation is exact only if  $\frac{df(y)}{dy} = 1$  or equivalently f(y) = y + C [1] with a real constant C.

b) Solve the equation in (a) in implicit form for a particular choice of f(y) ensuring exactness such that f(0) = 0. [11 marks]
Solution: The condition f(0) = 0 + C = 0 implies C = 0 so that f(y) = y [2]. Then the general solution should be looked for in implicit form as F(x, y) = Const., where

$$F = \int P(x,y) \, dx = \int \left(x^2 + \frac{y}{x}\right) \, dx = \frac{x^3}{3} + y \ln x + g(y) \,.$$
 [3]

g(y) is to be determined from the condition  $Q = \frac{\partial F}{\partial y} = \ln x + g'(y)$  [1]. We conclude that  $g'(y) = \ln y$  [1] so that (see formula sheet)  $g(y) = \int \ln y dy = y \ln |y| - y$  [2]. Thus the solution in implicit form is

$$F(x,y) = \frac{x^3}{3} + y \ln x + y \ln y - y = Const.$$
 [2]

c) Consider the initial value problem

$$\frac{dy}{dx} = f(x,y), \ f(x,y) = \sqrt{25 + 4y^2}, \ y(1) = 0$$

Show that the Picard-Lindelöf Theorem guarantees the existence and uniqueness of the solution of the above problem in a rectangular domain  $\mathcal{D} = (|x - a| \le A, |y - b| \le B)$  in the xy plane, and specify the parameters a and b. Find the possible range of values of the height B of the domain  $\mathcal{D}$  given that the width A of the domain satisfies A < 1/3. [9 marks]

**Solution:** The right-hand side f(x, y) is continuous everywhere, and its derivative  $\frac{\partial f}{\partial y}$  satisfies  $\left|\frac{\partial f}{\partial y}\right| = 4|y|/\sqrt{25 + 4y^2} < 2$  [2], hence is bounded. The initial conditions are a = 1 and b = y(1) = 0 [1]. Therefore, in the rectangular domain  $\mathcal{D} = (|x - 1| \leq A, |y| \leq B)$  the solution of the ODE exists and is unique provided A < B/M with  $M = \max_{\mathcal{D}} \sqrt{25 + 4y^2}$  [1]. The function  $f(x, y) = \sqrt{25 + 4y^2}$  on the right-hand side of the ODE grows with |y|. Thus, for a given B its maximum M is achieved for |y| = B [1]. We then have  $M = \sqrt{25 + 4B^2}$  [1], which implies that the width A should satisfy  $A < B/M = B/\sqrt{25 + 4B^2}$  [1]. Requiring that the maximal value of the width  $A = B/\sqrt{25 + 4B^2}$  fulfills A < 1/3 we obtain

$$B/\sqrt{25+4B^2} < 1/3$$
 [1]  $\Rightarrow$   $(3B)^2 < 25+4B^2$  and  $B < \sqrt{5}$  [1]

Given A < 1/3, for these values of B existence and uniqueness of the solution are guaranteed.

3. Find the solution of the following boundary value problem (BVP) for the second order inhomogeneous ODE

$$\frac{1}{\cos x}\frac{d^2y}{dx^2} + \left(\frac{\sin x}{\cos^2 x}\right)\frac{dy}{dx} = f(x) , \ y(0) = 0 , \ y\left(\frac{\pi}{4}\right) = 0$$

by using the Green's function method along the following lines:

a) Show that the left-hand side of the ODE can be written down in the form  $\frac{d}{dx} \left( r(x) \frac{dy}{dx} \right)$  for some function r(x). Use this fact to determine the general solution of the associated homogeneous ODE. [4 marks] Solution: We have

$$\frac{d}{dx}\left(r(x)\frac{dy}{dx}\right) = r(x)\frac{d^2y}{dx^2} + r'(x)\frac{dy}{dx},$$

which coincides with the original ODE for  $r(x) = \frac{1}{\cos x}$ . Therefore, the homogeneous ODE has the form

$$\frac{d}{dx}\left(\frac{1}{\cos x}\frac{dy}{dx}\right) = 0 \quad [\mathbf{2}]$$

This can be integrated to find the general solution

$$\frac{1}{\cos x}\frac{dy}{dx} = C_1 \quad \Rightarrow \quad y(x) = C_1\sin x + C_2 \quad [2]$$

for real constants  $C_1$  and  $C_2$ .

b) Formulate the left-end and right-end initial value problems corresponding to the above BVP. [9 marks]

**Solution:** The left-end boundary condition y(0) = 0 is imposed at  $x_1 = 0$ . By comparing it to the standard form  $\alpha y'(x_1) + \beta y(x_1) = 0$  we conclude that  $\alpha = 0, \beta = 1$  [1]. Then the left-end initial value problem for the function  $y_L(x)$  is formulated as

$$y_L(x_1) = \alpha, y'_L(x_1) = -\beta \implies y_L(0) = 0, y'_L(0) = -1.$$
 [2]

Substituting the general solution of the homogeneous equation yields  $C_2 = 0, C_1 = -1$  [1] so that

$$y_L(x) = -\sin x \,. \quad [\mathbf{1}]$$

Similarly,  $x_2 = \frac{\pi}{4}$  and by comparing the right-end boundary condition  $y\left(\frac{\pi}{4}\right) = 0$  to the standard form  $\gamma y'(x_2) + \delta y(x_2) = 0$  we conclude that  $\gamma = 0, \delta = 1$  [1]. Then the right-end initial value problem for the function  $y_R(x)$  is formulated as

$$y_R(x_2) = \gamma , \ y'_R(x_2) = -\delta \quad \Rightarrow \quad y_R\left(\frac{\pi}{4}\right) = 0 , \ y'_R\left(\frac{\pi}{4}\right) = -1 , \quad [\mathbf{2}]$$

which gives  $\frac{1}{\sqrt{2}}C_1 + C_2 = 0$ ,  $C_1 = -\sqrt{2}$  and thus  $C_2 = 1$  so that

$$y_R(x) = -\sqrt{2}\sin x + 1$$
. [1]

c) Use the solutions of these initial value problems to construct the Green's function G(x, s) of the BVP. [5 marks]
 Solution: Using y<sub>L</sub>(x), y<sub>R</sub>(x) for the construction of the Green's function G(x, s), first we calculate the Wronskian

$$W(s) = y_L(s)y'_R(s) - y_R(s)y'_L(s)$$
  
=  $-\sin s(-\sqrt{2}\cos s) - (-\sqrt{2}\sin s + 1)(-\cos s) = \cos s$ . [1]

From the original ODE we have  $a_2(s) = \frac{1}{\cos s}$  so that  $a_2(s)W(s) = 1$ , hence

$$A(s) = y_R(s) / (a_2(s)W(s)) = (-\sqrt{2}\sin s + 1),$$
  
$$B(s) = y_L(s) / (a_2(s)W(s)) = -\sin s .$$
 [2]

The Green's function is then constructed as

$$G(x,s) = \begin{cases} A(s)y_L(x) , & 0 \le x \le s \\ B(s)y_R(x) , & s \le x \le \pi/4 \end{cases}$$
$$= \begin{cases} (\sqrt{2}\sin s - 1)\sin x , & 0 \le x \le s \\ (\sqrt{2}\sin x - 1)\sin s , & s \le x \le \pi/4 \end{cases} .$$
[2]

d) Write down the solution of the BVP in terms of G(x, s) and f(x). Use it to find the explicit form of the solution for f(x) = 1. [7 marks]
Solution: The solution of the boundary value problem is given by

$$y(x) = \int_0^{\pi/4} G(x,s) f(s) \, ds = \int_0^x G(x,s) f(s) \, ds + \int_x^{\pi/4} G(x,s) f(s) \, ds \,.$$
 [2]

Substituting G(x,s) and f(x) = 1 we obtain

$$y(x) = \int_0^x (\sqrt{2}\sin x - 1)\sin s \, ds + \int_x^{\frac{\pi}{4}} (\sqrt{2}\sin s - 1)\sin x \, ds \,. \quad [\mathbf{1}]$$

After integration we get

$$y(x) = (\sqrt{2}\sin x - 1)(-\cos s)|_0^x + \sin x(-\sqrt{2}\cos s - s)|_x^{\frac{\pi}{4}}, \quad [\mathbf{1}]$$

which can be written as

$$y(x) = (1 - \cos x)(\sqrt{2}\sin x - 1) + \sin x \left(-1 - \frac{\pi}{4} + \sqrt{2}\cos x + x\right) .$$
 [1]

Simplification yields

$$y(x) = \sqrt{2}\sin x - 1 + \cos x - \sin x(1 + \frac{\pi}{4}) + x\sin x$$
. [2]

4. Consider the system of two nonlinear first-order ODEs

$$\dot{x} = -4y - x^3, \ \dot{y} = 3x - y^3.$$
 (1)

(a) Write down in matrix form the linear system obtained by linearization of the above equations around the point x = y = 0. Then find the corresponding eigenvalues and eigenvectors. [8 marks]
Solution. Discarding the nonlinear terms we see that the matrix associated with the linearized system is given by A = \$\begin{pmatrix} 0 & -4 \\ 3 & 0 \\ \end{pmatrix}\$. [1] The characteristic equation is \$\lambda^2 + 12 = 0\$ [1], which has the two complex conjugate roots \$\lambda\_1 = 2i\sqrt{3}\$, \$\lambda\_2 = -2i\sqrt{3}\$ [1]. Looking for the eigenvectors in the form \$\mathbf{u} = \$\binom{p}{q}\$ we have for the eigenvector corresponding to \$\lambda\_1\$

$$\begin{pmatrix} 0 & -4 \\ 3 & 0 \end{pmatrix} \begin{pmatrix} p \\ q \end{pmatrix} = 2i\sqrt{3} \begin{pmatrix} p \\ q \end{pmatrix} .$$
 [2]

This implies  $-4q = 2i\sqrt{3}p$ , hence we can choose p = 1 and  $q = -i\frac{\sqrt{3}}{2}$  [1]. For the second eigenvalue we will have components obtained by complex conjugation of the above. The two eigenvectors are thus

$$\mathbf{u}_1 = \begin{pmatrix} 1\\ -i\frac{\sqrt{3}}{2} \end{pmatrix} \quad , \quad \mathbf{u}_2 = \begin{pmatrix} 1\\ i\frac{\sqrt{3}}{2} \end{pmatrix} \quad . \quad [\mathbf{2}]$$

b) Determine the type of fixed point for the linear system. Is it stable? Is it asymptotically stable? Can one judge the stability of the nonlinear system by the linear approximation?
 [4 marks]

**Solution.** We see that the linear system is of *center type* [1], hence stable [1] but not asymptotically stable [1]. We cannot judge the stability of the zero equilibrium solution for the nonlinear system by its linear counterpart [1].

c) Write down the general solution of the linear system. [2 marks]Solution. The general solution of the linear system is given by:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = C_1 e^{2i\sqrt{3}t} \begin{pmatrix} 1 \\ -i\frac{\sqrt{3}}{2} \end{pmatrix} + C_2 e^{-2i\sqrt{3}t} \begin{pmatrix} 1 \\ i\frac{\sqrt{3}}{2} \end{pmatrix} .$$
 [2]

d) Find the solution of the linear system for the initial conditions x(0) = 2, y(0) = 0 in terms of real-valued functions. What is the shape of the corresponding trajectory in the phase plane? [6 marks]

Solution. From the general solution we have

$$x(t) = C_1 e^{2i\sqrt{3}t} + C_2 e^{-2i\sqrt{3}t} \quad \Rightarrow \quad x(0) = C_1 + C_2 = 2 \quad [\mathbf{1}]$$
$$y(t) = -i\frac{\sqrt{3}}{2} \left( C_1 e^{2i\sqrt{3}t} - C_2 e^{-2i\sqrt{3}t} \right) \quad \Rightarrow \quad y(0) = -i\frac{\sqrt{3}}{2} (C_1 - C_2) = 0 , \quad [\mathbf{1}]$$

which gives  $C_1 = C_2 = 1$  [1]. Hence the trajectory is determined by

$$x(t) = e^{2i\sqrt{3}t} + e^{-2i\sqrt{3}t} = 2\cos 2\sqrt{3}t \quad [\mathbf{1}]$$
$$y(t) = -i\frac{\sqrt{3}}{2} \left(e^{2i\sqrt{3}t} - e^{-2i\sqrt{3}t}\right) = \sqrt{3}\sin 2\sqrt{3}t \quad [\mathbf{1}] ,$$

which has the shape of an ellipse:  $\frac{x^2}{4} + \frac{y^2}{3} = 1$  [1].

e) Demonstrate how to use the function V(x, y) = 3x<sup>2</sup> + 4y<sup>2</sup> to investigate the stability of the original nonlinear system (1). [5 marks]
Solution. It is V(x, y) = 3x<sup>2</sup> + 4y<sup>2</sup> > 0 for (x, y) ≠ (0, 0) [1], and the orbital derivative is given by

$$\mathcal{D}_f V = \frac{\partial V}{\partial x} \dot{x} + \frac{\partial V}{\partial y} \dot{y}$$
$$= 6x(-4y - x^3) + 8y \left(3x - y^3\right) = -6x^4 - 8y^4 < 0 \ \forall (x, y) \neq (0, 0) .$$
[3]

Therefore V(x, y) is a valid Lyapunov function ensuring the asymptotic stability of the solution of the nonlinear equation in the whole (x, y) plane [1].