

Equivalence Relation.

Revision

H a Subgroup of a group G .

Define a relation

$$\underline{M_H \subseteq G \times G}$$

$$(x, y) \in M_H \Leftrightarrow xy^{-1} \in H$$

Equivalence relation:

i) Reflexive: $(x, x) \in M_H$

$$e = x \cdot x^{-1} \in H$$

ii) Symmetric

$$(x, y) \in M_H$$

$$(y, x) \in M_H.$$

iii) Transitive. ¹

$$(x, y) \in M_H, (y, z) \in M_H.$$

Question

$$(\alpha, \beta) \in \Gamma_H.$$

Γ_H defines an equivalence relation
on G . $G/\Gamma_H = \{ [], [], \dots \}$

✓
 D_{10} or D_{12}

look at the subgroups
generated by $\langle h^2 \rangle$
 $\langle s \rangle$, $\langle h^2 s \rangle$

Write down the coset of
 $\langle h^2 \rangle$ in D_{10}

$$\langle h^2 \rangle = \{$$

}

Question

$$D_{10} = \left\{ 1, \hbar, \hbar^2, \hbar^3, \hbar^4, \mathcal{S}, \hbar\mathcal{S}, \hbar^2\mathcal{S}, \hbar^3\mathcal{S}, \hbar^4\mathcal{S} \right\}$$

$$H =$$

$$\langle \hbar^2 \rangle = \{ e, \hbar^2, \hbar^4, \hbar, \hbar^3 \}$$

$$= \{ e, \hbar, \hbar^2, \hbar^3, \hbar^4 \}$$

$$(\hbar^2)^2 = \hbar^4$$

$$(\hbar^2)^3 = \hbar^6 = \hbar$$

$$(\hbar^2)^4 = \hbar^8 = \hbar^3$$

$$(\hbar^2)^5 = e$$

$$H\mathcal{S} = \{ \mathcal{S}, \hbar\mathcal{S}, \hbar^2\mathcal{S}, \hbar^3\mathcal{S}, \hbar^4\mathcal{S} \}$$

$$H = \{ e, \hbar^2, \hbar^4, \hbar, \hbar^3 \}$$

$$\langle \hbar^2\mathcal{S} \rangle =$$

Question

Write down the case.

$$B = \left\{ \begin{pmatrix} a & b \\ 0 & \frac{1}{a} \end{pmatrix} : a \in \mathbb{R}^*, b \in \underline{\mathbb{R}} \right\} \leq \mathcal{GL}_2(\mathbb{R})$$

$$A = \begin{pmatrix} a_1 & b_1 \\ 0 & 1/a_1 \end{pmatrix}$$

$$A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} \frac{1}{a_1} & -b_1 \\ 0 & a_1 \end{pmatrix} = \begin{pmatrix} \frac{1}{a_1} & -b_1 \\ 0 & a_1 \end{pmatrix}$$

$$AB = \begin{pmatrix} a_1 & b_1 \\ 0 & 1/a_1 \end{pmatrix} \cdot \begin{pmatrix} a_2 & b_2 \\ 0 & 1/a_2 \end{pmatrix}$$

$$\mathcal{SO}(2) = \left\{ \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} : \theta \in \mathbb{R} \right\}$$

Question

$$\leq SL_2(\mathbb{R})$$

$$\begin{aligned} AB &= \begin{pmatrix} a_1 & b_1 \\ 0 & 1/a_1 \end{pmatrix} \begin{pmatrix} a_2 & b_2 \\ 0 & 1/a_2 \end{pmatrix} \\ &= \begin{pmatrix} a_1 a_2 + 0 & a_1 b_2 + \frac{b_1}{a_2} \\ 0 + 0 & 0 + \frac{1}{a_1 a_2} \end{pmatrix} \\ &= \begin{pmatrix} \underline{a_1 a_2} & \boxed{a_1 b_2 + \frac{b_1}{a_2}} \\ \underline{0} & \underbrace{\frac{1}{a_1 a_2}} \end{pmatrix} \end{aligned}$$

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$A = \begin{pmatrix} \cos \theta_1 & -\sin \theta_1 \\ \sin \theta_1 & \cos \theta_1 \end{pmatrix}$$

$$B = \begin{pmatrix} \cos \theta_2 & -\sin \theta_2 \\ \sin \theta_2 & \cos \theta_2 \end{pmatrix}$$

Question

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark$$

$$= \begin{pmatrix} \overset{0}{\cos(90^\circ)} & \\ & \cos(90^\circ) \end{pmatrix}$$

$$= \begin{pmatrix} \cos(0) & -\sin(0) \\ \sin(0) & \cos(0) \end{pmatrix} = I \checkmark$$



$$\{1, 2\}$$

$$f \sim_{\text{sn}} g$$

$$\exists h, h \circ f \circ h^{-1} = g$$

Question

S_9

$$f = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 3 & 8 & 5 & 9 & 6 & 1 & 4 & 2 & 7 \end{pmatrix}$$

$$h = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 4 & 1 & 6 & 3 & 8 & 2 & 7 & 5 & 9 \end{pmatrix}$$

$$h = (14362)(58)$$

i) Disjoint cycle of f .

$$\boxed{f = (\underline{1356})(\underline{28})(\underline{497})} \in S_9$$

$$= (\underline{1356})(\underline{497})(\underline{28})$$

4 3 2

$$h = (\underline{14362})(\underline{58}) = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\ 4 & 1 & 6 & 3 & 8 & 2 & 7 & 5 & 9 \end{pmatrix}$$

5 2

$$g = (\underline{4682})(\underline{15})(\underline{397})$$

4 2 3

$$= h \cdot g \cdot h^{-1}$$

Question

Order: f g h
 $12, 12, 10$

$f \cdot g, g \cdot f,$

iii) conjugate

f & g are conjugate.

iv) $f, g, h \in A_9$

Remember that $f, g \in A_9$ if
we'll be able to write
down f and g as even
no of Transpositions.

$$f = (1356)(28)(497)$$

Question

$$h = (14362)(58)$$

$$g = (4682)(15)(397)$$

We keep the cycle of f and
use h to build g

$$f \sim_{S_n} g, \Rightarrow \exists h \quad \text{page 25}$$

$$hfh^{-1} = g \quad \text{of Lecture Notes.}$$

Centraliser Definition

G is a group and $A \subseteq G$

$$C_G(A) = \left\{ g \in G \mid \forall a \in A: ga = ag \right\}$$

Question

Consider D_8 :

Consider r^3 in D_8

$$D_8 = \{1, r, r^2, r^3, s, rs, r^2s, r^3s\}$$

$$r \cdot r^3 = r^4 = r^3 \cdot r$$

but r^3 commute with all rotations.

$$\rightarrow r^3 \cdot s = r^2 \cdot r \cdot s = r^3 \cdot \underline{s \cdot r} \cdot r^{-1}$$

$$= r^3 \cdot r^{-1} \cdot s \cdot r^{-1}$$

$$= r^2 \cdot s \cdot \underline{r^{-1}}$$

$$= r^3 \cdot s \cdot \underline{r^3}$$

$$= r^3 \cdot \underline{s \cdot r} \cdot r^2$$

$$= r^3 \cdot \underline{r^{-1} \cdot s} \cdot r^2$$

$$= r^2 \cdot s \cdot r^2$$

$$= r^2 \cdot \underline{s \cdot r} \cdot r$$

$$= r^2 \cdot r^{-1} \cdot s \cdot r$$

$$= r \cdot s \cdot r$$

$$r^3 = r^{-1} \text{ as}$$

$$r^4 = 1$$

$$r^3 = r^{-1}$$

$$= R R^{-1} S = S$$

Question

Let's Try R^2

$$\begin{aligned}
 R^2 S &= R \cdot R \cdot S \cdot \underline{R \cdot R^{-1}} \\
 &= R^2 \cdot \underline{R^{-1} S} \cdot R^{-1} \\
 &= R S \cdot R^{-1} = R S R^3 \\
 &= R S \cdot R \cdot R^2 \\
 &= R \cdot R^{-1} S \cdot R^2 \\
 &= \underline{S \cdot R \cdot R} = S R^2
 \end{aligned}$$

$R^2 S = S R^2$

$$\begin{aligned}
 R^2 \underline{S R} &= R^2 R^{-1} S \\
 &= R \cdot \underline{S \cdot R \cdot R^{-1}} \\
 &= R \cdot R^{-1} S \cdot R^{-1} \\
 &= S \cdot R^{-1} \\
 &= S \cdot R^3 \\
 &= S R \cdot R^2
 \end{aligned}$$

$R^2 \cdot S R = S R \cdot R^2$