

# SOLUTIONS: CW3

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① Only the second and the fourth make sense.  
 In the first one, the free indices don't match.  
 In the third expression the index  $k$  appears as a dummy index on the left while it's a free index on the right. In the fifth, the free indices don't match and  $k$  appears as both a free and a dummy index on the r.h.s.

②  $G_{ij}: G_{11}, G_{12}, G_{21}, G_{22}$

$$A^i B_i = A^1 B_1 + A^2 B_2$$

$$\Gamma^i_{jk}: \Gamma^1_{11}, \Gamma^1_{12}, \Gamma^1_{21}, \Gamma^1_{22}, \Gamma^2_{11}, \Gamma^2_{12}, \Gamma^2_{21}, \Gamma^2_{22}$$

$$\Gamma^i_{ij}: \Gamma^1_{11} + \Gamma^2_{21}, \Gamma^1_{12} + \Gamma^2_{22}$$

$$R^i_{jke}: R^1_{111}, R^1_{112}, R^1_{121}, R^1_{122}$$

$$R^1_{211}, R^1_{212}, R^1_{221}, R^1_{222}$$

$$R^2_{111}, R^2_{112}, R^2_{121}, R^2_{122}$$

$$R^2_{211}, R^2_{212}, R^2_{221}, R^2_{222}$$

$$R^i_i = R^1_1 + R^2_2$$

③ The first part is covered in the lectures.

• Timelike:  $\bar{A} \cdot \bar{A} < 0$

• Spacelike:  $\bar{A} \cdot \bar{A} > 0$

• Null:  $\bar{A} \cdot \bar{A} = 0$

For the second part,

$$\bar{A}: \text{timelike} \Rightarrow \bar{A} \cdot \bar{A} = -(A^0)^2 + |\underline{A}|^2 < 0$$

$$\Rightarrow |\underline{A}| < A^0 \quad \text{and} \quad A^0 > 0 \quad \text{wlog}$$

Here  $|\underline{A}| = \sqrt{(A^1)^2 + (A^2)^2 + (A^3)^2}$  is the usual norm of a 3-vector.

$$\bar{B}: \text{null} \Rightarrow \bar{B} \cdot \bar{B} = -(B^0)^2 + |\underline{B}|^2 = 0 \Rightarrow B^0 = \pm |\underline{B}|$$

We can choose the + sign wlog.

Then,

$$\underline{A} \cdot \underline{B} = -A^0 B^0 + \underline{A} \cdot \underline{B} < -|\underline{A}| |\underline{B}| + \underline{A} \cdot \underline{B} =$$

$$= -|\underline{A}| |\underline{B}| + |\underline{A}| |\underline{B}| \cos \theta =$$

$$= -|\underline{A}| |\underline{B}| (1 - \cos \theta)$$

$$\Rightarrow \underline{A} \cdot \underline{B} < -|\underline{A}| |\underline{B}| (1 - \cos \theta) < 0$$

④ If  $\bar{A}$  is a unit spacelike vector, then  $|\bar{A}| = 1$ .

It follows that  $-(A^0)^2 + 4 = 1 \Rightarrow A^0 = \pm \sqrt{3}$ .

If  $\bar{A}$  and  $\bar{B}$  are orthogonal, then

$$\bar{A} \cdot \bar{B} = -3A^0 + 2B^2 = 0$$

$$\Rightarrow B^2 = \frac{3}{2}A^0 = \pm \frac{3\sqrt{3}}{2}$$

⑤ a)  $\bar{A} \cdot \bar{B} = \eta_{ab} A^a B^b$

$|\bar{A}|^2$  is invariant means that is the same in all reference frames, i.e., it is unchanged by a Lorentz transf.

b) Shown in the lectures.

c)  $|\bar{A}|^2, |\bar{B}|^2 > 0, \bar{A} \cdot \bar{B} = 0$

$$\begin{aligned} (\bar{A} + \bar{B})^2 &= |\bar{A}|^2 + |\bar{B}|^2 + 2\bar{A} \cdot \bar{B} \\ &= |\bar{A}|^2 + |\bar{B}|^2 > 0 \end{aligned}$$

⑥ Since  $\bar{A}$  and  $\bar{B}$  are timelike,

$$|\bar{A}|^2 = -(A^0)^2 + (A^1)^2 < 0, \quad |\bar{B}|^2 = -(B^0)^2 + (B^1)^2 < 0$$

Hence,  $A^1 < A^0$  and  $B^1 < B^0$  since  $A^0, A^1, B^0, B^1$  are all positive. Adding,

$$(A^1 + B^1)^2 < (A^0 + B^0)^2$$

Hence,

$$|\bar{A} + \bar{B}|^2 = -(A^0 + B^0)^2 + (A^1 + B^1)^2 < 0$$

⑦ Since  $\bar{A}$  is a 4-vector, its transformation under Lorentz transf. is given by

$$A^{10} = \gamma(A^0 - v A^1), \quad A^{11} = \gamma(A^1 - v A^0), \quad A^{12} = A^2, \quad A^{13} = A^3$$

The norm of  $\bar{A}'$  is given by

$$\begin{aligned} |\bar{A}'|^2 &= -(A^{10})^2 + (A^{11})^2 + (A^{12})^2 + (A^{13})^2 = \\ &= -\gamma^2 (A^0 - v A^1)^2 + \gamma^2 (A^1 - v A^0)^2 + (A^2)^2 + (A^3)^2 \\ &= \gamma^2 (1 - v^2) (-(A^0)^2 + (A^1)^2) + (A^2)^2 + (A^3)^2 \\ &= -(A^0)^2 + (A^1)^2 + (A^2)^2 + (A^3)^2 \end{aligned}$$

$$\text{since } \gamma^2 (1 - v^2) = 1$$

⑧

The relation between Cartesian and polar coordinates is

$$x = r \cos \theta, \quad y = r \sin \theta \Rightarrow r = \sqrt{x^2 + y^2}, \quad \theta = \arctan \frac{y}{x}$$

Taking differentials,

$$dx = \cos \theta dr - r \sin \theta d\theta$$

$$dy = \sin \theta dr + r \cos \theta d\theta$$

Therefore,

$$ds^2 = dx^2 + dy^2 =$$

$$= (\cos \theta dr - r \sin \theta d\theta)^2 + (\sin \theta dr + r \cos \theta d\theta)^2$$

$$= dr^2 + r^2 d\theta^2$$

$$F_{tr} = -F_{rt} = -\frac{Q}{r^2}$$

$$T_{ab} = F_{ac} F_b{}^c - \frac{1}{4} g_{ab} F_{cd} F^{cd}$$

$$\eta = -dt^2 + dr^2 + r^2(d\theta^2 + \sin^2\theta d\phi^2)$$

$$\rightarrow F^{tr} = -F^{rt} = \eta^{ta} \eta^{rb} F_{ab} = \eta^{tt} \eta^{rr} F_{tr} = (-1) F_{tr} = \frac{Q}{r^2}$$

$$F_{ab} F^{ab} = F_{tr} F^{tr} + F_{rt} F^{rt} = -\frac{2Q^2}{r^4}$$

The first term only has  $tt$  and  $rr$  components. Indeed,

$$F_{tc} F_r{}^c = F_{tr} F_r{}^r = F_{tr} F_{rb} \eta^{br} = F_{tr} F_{rr} \eta^{rr} = 0$$

$$F_{ta} F_t{}^a = F_{tr} F_t{}^r = F_{tr} F_{tr} \eta^{rr} = +\frac{Q^2}{r^4}$$

$$F_{ra} F_r{}^a = F_{rt} F_r{}^t = F_{rt} F_{rt} \eta^{tt} = -\frac{Q^2}{r^4}$$

Therefore we get:

$$T_{tt} = F_{ta} F_t{}^a - \frac{1}{4} \eta_{tt} F^2 = \frac{Q^2}{r^4} - \frac{1}{4} (-1) \left(-\frac{2Q^2}{r^4}\right) = \frac{Q^2}{2r^4}$$

$$T_{rr} = F_{ra} F_r{}^a - \frac{1}{4} \eta_{rr} F^2 = -\frac{Q^2}{r^4} - \frac{1}{4} \left(-\frac{2Q^2}{r^4}\right) = -\frac{Q^2}{2r^4}$$

$$T_{\theta\theta} = -\frac{1}{4} \eta_{\theta\theta} F^2 = -\frac{1}{4} (r^2) \left(-\frac{2Q^2}{r^4}\right) = +\frac{Q^2}{2r^2}$$

$$T_{\phi\phi} = \sin^2\theta T_{\theta\theta}$$

$$\begin{aligned} T = T^a{}_a &= \eta^{ab} T_{ab} = \eta^{tt} T_{tt} + \eta^{rr} T_{rr} + \eta^{\theta\theta} T_{\theta\theta} + \eta^{\phi\phi} T_{\phi\phi} = \\ &= (-1) \left(\frac{Q^2}{2r^4}\right) + \left(-\frac{Q^2}{2r^4}\right) + \frac{1}{r^2} \left(\frac{Q^2}{2r^2}\right) + \frac{1}{r^2 \sin^2\theta} \left(\frac{Q^2}{2r^2} \sin^2\theta\right) = 0 \end{aligned}$$

# ① Question: Geometry

- Consider the object  $F_{ij} = \partial_i A_j - \partial_j A_i$ , where  $A_i$  is a  $(0,1)$  tensor. Compute the transformation of  $F_{ij}$  under a change of coordinates  $x^a = x^a(x'^b)$ . Is  $F_{ij}$  a tensor?

• Solution:

Since  $A_i$  is a tensor, it transforms as

$$A_i = \frac{\partial x'^j}{\partial x^i} A'_j$$

As for the partial derivatives one has,

$$\frac{\partial}{\partial x^i} = \frac{\partial x'^j}{\partial x^i} \frac{\partial}{\partial x'^j}$$

Putting these two results together, we get

$$\begin{aligned} F_{ij} &= \partial_i A_j - \partial_j A_i \\ &= \frac{\partial x'^k}{\partial x^i} \frac{\partial}{\partial x'^k} \left( \frac{\partial x'^l}{\partial x^j} A'_l \right) - \frac{\partial x'^p}{\partial x^j} \frac{\partial}{\partial x'^p} \left( \frac{\partial x'^q}{\partial x^i} A'_q \right) \\ &= \frac{\partial x'^k}{\partial x^i} \left[ \frac{\partial^2 x'^l}{\partial x'^k \partial x^j} A'_l + \frac{\partial x'^l}{\partial x^j} \frac{\partial}{\partial x'^k} A'_l \right] \end{aligned}$$

$$- \frac{\partial x^p}{\partial x^j} \left[ \frac{\partial^2 x^i}{\partial x^p \partial x^i} A'_f + \frac{\partial x^i}{\partial x^i} \frac{\partial}{\partial x^p} A'_f \right]$$

The first terms on each line cancel. To see this, one realizes that they are equal to

$$\frac{\partial x^k}{\partial x^i} \frac{\partial}{\partial x^k} \left( \frac{\partial x^e}{\partial x^j} \right) A'_e = \frac{\partial^2 x^e}{\partial x^i \partial x^j} A'_e$$

$$\frac{\partial x^p}{\partial x^j} \frac{\partial}{\partial x^p} \left( \frac{\partial x^i}{\partial x^i} \right) A'_f = \frac{\partial^2 x^i}{\partial x^j \partial x^i} A'_f$$

Therefore, one is left with,

$$\begin{aligned} F_{ij} &= \frac{\partial x^k}{\partial x^i} \frac{\partial x^e}{\partial x^j} \frac{\partial A'_e}{\partial x^k} - \frac{\partial x^p}{\partial x^j} \frac{\partial x^i}{\partial x^i} \frac{\partial}{\partial x^p} A'_f \\ &= \frac{\partial x^k}{\partial x^i} \frac{\partial x^e}{\partial x^j} \left( \frac{\partial A'_e}{\partial x^k} - \frac{\partial A'_k}{\partial x^e} \right) \\ &= \frac{\partial x^k}{\partial x^i} \frac{\partial x^e}{\partial x^j} F'_{ek} \end{aligned}$$

Therefore,  $F_{ij}$  transforms as a (0,2) tensor.