

MTP25, Lecture 2:  
Random Variables, Independence, Integration and  
Conditioning

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## Measurable functions

**Definition** Given two measurable spaces  $(\Omega, \mathcal{F})$  and  $(\Omega', \mathcal{F}')$ , a function  $X : \Omega \rightarrow \Omega'$  is said to be *measurable* if it satisfies

$$X^{-1}(B') \in \mathcal{F} \quad \text{for all } B' \in \mathcal{F}' \quad (1)$$

The  $\sigma$ -algebra  $\sigma(X)$  *induced* (or generated) by  $X$  is comprised of the sets  $X^{-1}(B')$ .

- It is sufficient to require the condition (1) to hold for any system  $\mathcal{G}'$  of generators (s.t.  $\mathcal{F}' = \sigma(\mathcal{G}')$ ).
- $\sigma(X)$  is the smallest  $\sigma$ -algebra in  $\Omega$  necessary to make  $X$  measurable.
- When the target space is  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$  we speak of a (real-valued) random variable. Then the measurability condition holds if  $X^{-1}((-\infty, x]) = \{\omega \in \Omega : X(\omega) \leq x\} \in \mathcal{F}$ .

## Product $\sigma$ -algebras

**Definition** For a family  $(X_t, t \in T)$  of measurable functions  $X_t : \Omega \rightarrow \Omega'$ , we denote  $\sigma(X_t, t \in T)$  the  $\sigma$ -algebra generated by the sets  $X_t^{-1}(B')$ , where  $B' \in \mathcal{F}', t \in T$ .

**Example** Let  $\Omega = \{0, 1\}^\infty$ ,  $X_n(\omega) = \omega_n$ . Then  $\sigma(X_n, n \in \mathbb{N})$  coincides with the  $\sigma$ -algebra generated by the finite-dimensional cylinders  $A(\epsilon_1, \dots, \epsilon_n) = \{\omega \in \Omega : \omega_1 = \epsilon_1, \dots, \omega_n = \epsilon_n\}$ . This is also an example of product  $\sigma$ -algebra.

**Definition** For a family  $((\Omega_t, \mathcal{F}_t), t \in T)$  of measurable spaces, let  $\Omega = \prod_{t \in T} \Omega_t$  (Cartesian product), and for  $\omega \in \Omega$  let  $X_t(\omega)$  be the  $t$ -th coordinate. The *product*  $\sigma$ -algebra

$$\bigotimes_{t \in T} \mathcal{F}_t = \sigma(X_t, t \in T)$$

is the  $\sigma$ -algebra generated by the family  $(X_t, t \in T)$ .

## Pushforward of measures

**Definition** For  $(\Omega, \mathcal{F}, \mu)$  measure space and measurable  $X : \Omega \rightarrow \Omega'$ , where  $(\Omega', \mathcal{F}')$  another measurable space, the measure on  $(\Omega', \mathcal{F}')$

$$\mu_X(B') := \mu(X^{-1}(B')), \quad B' \in \mathcal{F}'$$

is called *pushforward* of  $\mu$  (induced by  $X$ ).

**Example** Distribution of a random variable  $X$  defined on  $(\Omega, \mathcal{F}, \mathbb{P})$  is the induced probability measure  $P(A) = \mathbb{P}[X \in A], A \in \mathcal{B}(\mathbb{R})$ .

**Definition**  $(\Omega, \mathcal{F}, \mu), (\Omega', \mathcal{F}', \mu')$  are isomorphic mod 0 if there exist nullsets  $A \in \mathcal{F}, A' \in \mathcal{F}'$  and a bijection  $f : \Omega \setminus A \rightarrow \Omega' \setminus A'$  such that  $f, f^{-1}$  are both measurable and preserve the measure.

- Many probability spaces are isomorphic mod 0 to the ‘standard probability space’  $([0, 1], \mathcal{B}([0, 1]), \lambda)$ .

## Product of measures

**Definition** Let  $(\Omega_1, \mathcal{F}_1, \mu_1), (\Omega_2, \mathcal{F}_2, \mu_2)$  be  $\sigma$ -finite measure spaces. The *product measure space*  $(\Omega_1 \times \Omega_2, \mathcal{F}_1 \otimes \mathcal{F}_2, \mu_1 \times \mu_2)$  carries the *product measure* uniquely defined by extending the formula for 'rectangles'

$$\mu_1 \times \mu_2(B_1 \times B_2) = \mu_1(B_1)\mu_2(B_2), \quad B_1 \in \mathcal{F}_1, B_2 \in \mathcal{F}_2$$

to  $\mathcal{F}_1 \otimes \mathcal{F}_2$ .

**Definition** Let  $(P_t, t \in T)$  be probability measures on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ . There exists a unique probability measure  $P$  on the infinite product space  $(\mathbb{R}^T, \mathcal{B}(\mathbb{R}^T))$  with marginal measures that define the joint distribution of coordinates  $(X_{t_1}, \dots, X_{t_n})$  for  $\{t_1, \dots, t_n\} \subset T$  by the product formula

$$P_{t_1, \dots, t_n}(B_1 \times \dots \times B_n) = P_{t_1}(B_1) \cdots P_{t_n}(B_n),$$

where  $B_i \in \mathcal{B}(\mathbb{R}), n \in \mathbb{N}$ .

# Independence

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space.

## Definition

- (i) Events  $(A_t, t \in T)$  are independent if

$$\mathbb{P}(A_{t_1} \cap \cdots \cap A_{t_n}) = \mathbb{P}(A_{t_1}) \cdots \mathbb{P}(A_{t_n})$$

for any  $\{t_1, \dots, t_n\} \subset T, n \in \mathbb{N}$ .

- (ii)  $\sigma$ -algebras  $(\mathcal{F}_t, t \in T), \mathcal{F}_t \subset \mathcal{F}$ , are independent if any finite collection of events  $A_{t_1} \in \mathcal{F}_{t_1}, \dots, A_{t_n} \in \mathcal{F}_{t_n}, n \in \mathbb{N}$ , is independent.
- (iii) Random variables  $(X_t, t \in T)$  are independent if the generated  $\sigma$ -algebras  $\sigma(X_t)$  are independent.

## Zero-one laws and tail events

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space. For a series of events  $A_n \in \mathcal{F}, n \in \mathbb{N}$ ,

$$\{A_n \text{ i.o.}\} := \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k.$$

### Borel-Cantelli Lemma

( $\rightarrow$ ) If  $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$  then  $\mathbb{P}(A_n \text{ i.o.}) = 0$ .

( $\leftarrow$ ) If  $\sum_{n=1}^{\infty} \mathbb{P}(A_n) < \infty$  and  $A_1, A_2, \dots$  are independent then  $\mathbb{P}(A_n \text{ i.o.}) = 1$ .

**Example** (the problem of records) Let  $X_1, X_2, \dots$  be i.i.d. with continuous c.d.f.,  $A_n = \{X_n = \max(X_1, \dots, X_n)\}$  the event ' $X_n$  is a record'.

By symmetry (exchangeability of  $X_n$ 's)  $\mathbb{P}(A_n) = 1/n$  and the events  $A_n$  are independent. Hence there are infinitely many records almost surely.

**Definition** Let  $\mathcal{F}_n$  be  $\sigma$ -algebras  $\mathcal{F}_n \subset \mathcal{F}$ . The *tail  $\sigma$ -algebra* is defined as

$$\mathcal{T} = \bigcap_{n=1}^{\infty} \sigma \left( \bigcup_{k=n}^{\infty} \mathcal{F}_k \right).$$

Each  $A \in \mathcal{T}$  is a *tail event*.

**Example** Let  $X_1, X_2, \dots$  be random variables,  $\mathcal{F}_n = \sigma(X_n)$ . Tail events:

- (i)  $\{X_n > 2025 \text{ i.o.}\},$
- (ii)  $\left\{ \frac{X_1 + \dots + X_n}{n} \rightarrow 0 \text{ as } n \rightarrow \infty \right\},$
- (iii)  $\{\sum_{n=1}^{\infty} X_n \text{ converges}\},$

Not tail events:

- (a)  $\{X_n > X_1 \text{ i.o.}\},$
- (b)  $\{\sum_{n=1}^{\infty} X_n = 27\}.$

**Kolmogorov's 0-1 Law** Suppose  $\mathcal{F}_n, n \in \mathbb{N}$  are independent  $\sigma$ -algebras. Then their tail  $\sigma$ -algebra  $\mathcal{T}$  is trivial, meaning that  $\mathbb{P}(A) = 0$  or  $1$  for every  $A \in \mathcal{T}$ .

**Example** Suppose  $X_n \sim \mathcal{N}(m_n, \sigma_n^2), n \in \mathbb{N}$ , are independent normal r.v. Does the series  $\sum_{n=1}^{\infty} X_n$  converge?

**Kolmogorov Three-Series Theorem** Let  $X_1, X_2, \dots$  be independent random variables. The series  $\sum_n X_n$  converges a.s. (almost surely) if and only if for some  $c > 0$

- (i)  $\sum_n \mathbb{P}[|X_n| > c] < \infty$ ,
  - (ii)  $\sum_n \mathbb{E}[X_n \mathbf{1}(|X_n| \leq c)] < \infty$ ,
  - (iii)  $\sum_n \text{Var}[X_n \mathbf{1}(|X_n| \leq c)] < \infty$ ,
- If (i), (ii), (iii) hold for some  $c > 0$  then also for all  $c > 0$ .
  - For normal r.v.'s the convergence holds iff both series  $\sum_n m_n$  and  $\sum_n \sigma_n^2$  converge.

## Lebesgue integral and expectation

$(\Omega, \mathcal{F}, \mu)$  measure space,  $X = X(\omega)$  measurable function with values in  $(\bar{\mathbb{R}}, \mathcal{B}(\bar{\mathbb{R}}))$ ,  $\bar{\mathbb{R}} = \mathbb{R} \cup \{-\infty, \infty\}$ . Suppose first  $X \geq 0$ , and let

$$X_n = \sum_{k=0}^{n2^n-1} \frac{k}{2^n} \mathbf{1} \left[ \frac{k}{2^n} \leq X < \frac{k+1}{2^n} \right] + n \mathbf{1}[X \geq n],$$

so  $X_n \uparrow X$  a.s. Then set

$$\begin{aligned} \int_{\Omega} X_n(\omega) \mu(d\omega) &:= \sum_{k=0}^{n2^n-1} \frac{k}{2^n} \mu \left\{ \omega : \frac{k}{2^n} \leq X(\omega) < \frac{k+1}{2^n} \right\} + \\ &\quad n \mu \{ \omega : X(\omega) \geq n \}, \end{aligned}$$

and define the Lebesgue integral as the (monotone) limit

$$\int_{\Omega} X(\omega) \mu(d\omega) := \lim_{n \rightarrow \infty} \int_{\Omega} X_n(\omega) \mu(d\omega).$$

For the general  $X$ , split  $X = X_+ - X_-$  with  $X_{\pm} := \max(\pm X, 0)$ , and define

$$\int_{\Omega} X(\omega) \mu(d\omega) := \int_{\Omega} X_+(\omega) \mu(d\omega) - \int_{\Omega} X_-(\omega) \mu(d\omega)$$

provided at least one of the integrals in the r.h.s. is finite.

**Example** The Dirichlet function  $f(x) = \mathbf{1}_{\mathbb{R} \setminus \mathbb{Q}}(x)$  has Lebesgue integral 0 (w.r.t.  $\lambda$ ), but is not Riemann-integrable.

- For r.v.  $X$  on probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  the *expectation* is denoted

$$\mathbb{E}[X] := \int_{\Omega} X(\omega) \mathbb{P}(d\omega).$$

This can be computed as the *Lebesgue-Stieltjes* integral

$$\mathbb{E}[X] := \int_{\mathbb{R}} x dF_X(x),$$

where  $F_X(x) := \mathbb{P}[X \leq x]$  is the c.d.f. of  $X$ .

## Constructing a non-product measure

**Definition** Given a product space  $(\Omega_1 \times \Omega_2, \mathcal{F}_1 \otimes \mathcal{F}_2)$ , call a function  $K(\omega_1, B_2) : (\Omega_1, \mathcal{F}_2) \rightarrow ([0, 1], \mathcal{B}([0, 1]))$  a *transition function* (aka *Markov kernel*) if

- (i)  $K(\omega_1, \cdot)$  is a probability measure on  $(\Omega_2, \mathcal{F}_2)$  for each  $\omega_1 \in \Omega_1$ ,
- (ii)  $K(\cdot, B_2)$  is a measurable function for each  $B_2 \in \mathcal{F}_2$ .

**Theorem** For probability measure  $P_1$  on  $(\Omega_1, \mathcal{F}_1)$ , the formula

$$P(B_1 \times B_2) = \int_{B_1} K(\omega_1, B_2) P_1(d\omega_1)$$

defines a unique probability measure on  $(\Omega_1 \times \Omega_2, \mathcal{F}_1 \otimes \mathcal{F}_2)$ .

## Exchanging $\mathbb{E}$ and $\lim$

Let  $X_1, X_2, \dots, X, Y$  be (real) random variables on some  $(\Omega, \mathcal{F}, \mathbb{P})$ .

**Monotone Convergence** If  $X_n \uparrow X$  a.s. and  $X_n \geq Y$  for some  $Y$  with  $\mathbb{E}[Y] > -\infty$  then  $\mathbb{E}[X_n] \uparrow \mathbb{E}[X]$  as  $n \rightarrow \infty$ .

**Fatou Lemma** If  $X_n \geq Y, \mathbb{E}[Y] > -\infty$  then

$$\mathbb{E}[\liminf_{n \rightarrow \infty} X_n] \leq \liminf_{n \rightarrow \infty} \mathbb{E}[X_n].$$

**Dominated Convergence** If  $|X_n| \leq Y$ , where  $\mathbb{E}[Y] < \infty$  then  $X_n \rightarrow X$  a.s. implies

- (i)  $\mathbb{E}[X] < \infty$ ,
- (ii)  $\mathbb{E}[X_n] \rightarrow \mathbb{E}[X]$  as  $n \rightarrow \infty$ ,
- (iii)  $\mathbb{E}|X_n - X| \rightarrow 0$  as  $n \rightarrow \infty$ .

## Absolute continuity

**Definition** Given measures  $\mu, \nu$  on  $(\Omega, \mathcal{F})$ , we say that  $\mu$  *dominates*  $\nu$  (written  $\mu \gg \nu$ ) if for  $A \in \mathcal{F}$

$$\mu(A) = 0 \Rightarrow \nu(A) = 0.$$

Then it is also said that  $\nu$  is *absolutely continuous* w.r.t.  $\mu$ . The measure are *equivalent*, written  $\mu \sim \nu$ , if  $\mu \gg \nu$  and  $\nu \gg \mu$ .

**The discrete case**  $\mu = \sum_k p_k \delta_{\omega_k}$ ,  $\nu = \sum_k q_k \delta_{\omega_k}$ , where  $a_k > 0$ ,  $b_k \geq 0$ .

$$\begin{aligned} \int_{\Omega} f(\omega) \nu(d\omega) &= \\ \sum_k f(\omega_k) b_k &= \sum_k f(\omega_k) a_k \left( \frac{b_k}{a_k} \right) = \\ \int_{\Omega} f(\omega) \xi(\omega) \mu(d\omega), \end{aligned}$$

where  $\xi(\omega) = \sum_k \left( \frac{b_k}{a_k} \right) \mathbf{1}[\omega = \omega_k]$ .

**Radon-Nykodým Theorem** If  $\mu \gg \nu$  and  $\mu$  is  $\sigma$ -finite, then there exists measurable  $\xi : \Omega \rightarrow \mathbb{R}_+$  such that

$$\int_{\Omega} f(\omega) \nu(d\omega) = \int_{\Omega} f(\omega) \xi(\omega) \mu(d\omega)$$

for all measurable  $f : \Omega \rightarrow \mathbb{R}$ . Such function  $\xi$  is unique up to a set of  $\mu$ -measure zero.

- Such  $\xi$  is called the Radon-Nykodým derivative, denoted  $\xi = \frac{d\nu}{d\mu}$ .
- For probability distributions on  $\mathbb{R}$  the absolute continuity means existence of the density function  $f$  such that the c.d.f. satisfies

$$F(x) = \int_{-\infty}^x f(y) dy.$$

So  $f$  is the RN derivative w.r.t.  $\lambda$ .

# The conditional expectation

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space,  $X$  a nonnegative r.v. and  $\mathcal{G} \subset \mathcal{F}$  a sub- $\sigma$ -algebra. Then

$$\mathbb{Q}(A) = \mathbb{E}[X \mathbf{1}_A] = \int_A X(\omega) \mathbb{P}(d\omega), \quad A \in \mathcal{G}$$

is a probability measure on  $(\Omega, \mathcal{G})$  satisfying  $\mathbb{P} \gg \mathbb{Q}$ . By the RN theorem there exists  $\mathcal{G}$ -measurable r.v.  $\xi$  such that

$$\mathbb{Q}(A) = \int_A \xi(\omega) \mathbb{P}(d\omega).$$

We denote this r.v.  $\xi = \mathbb{E}[X|\mathcal{G}]$  and call the *conditional expectation* of  $X$  given  $\mathcal{G}$ . For the general  $X$  with definite  $\mathbb{E}[X]$  we split  $X = X_+ - X_-$  and define  $\mathbb{E}[X|\mathcal{G}]$  by linearity.

- The defining property of the conditional expectation is that  $\mathbb{E}[X|\mathcal{G}]$  is  $\mathcal{G}$ -measurable, s.t.

$$\mathbb{E}[\mathbb{E}[X|\mathcal{G}]\mathbf{1}_A] = \mathbb{E}[X\mathbf{1}_A], \quad A \in \mathcal{G}.$$

- The conditional probability of  $A \in \mathcal{F}$  given  $\mathcal{G}$  is

$$\mathbb{P}[A|\mathcal{G}] = \mathbb{E}[\mathbf{1}_A|\mathcal{G}],$$

which is a random variable! If  $\mathcal{G}$  is generated by partition  $\Omega = \cup_j B_j$ , then

$$\mathbb{P}[A|\mathcal{G}](\omega) = \mathbb{P}[A|B_j] = \frac{\mathbb{P}[A \cap B_j]}{\mathbb{P}[B_j]} \quad \text{if } \omega \in B_j.$$

- Iterated conditioning, tower property:

$$\mathcal{G}_1 \subset \mathcal{G}_2 \Rightarrow \mathbb{E}[\mathbb{E}[X|\mathcal{G}_2]|\mathcal{G}_1] = \mathbb{E}[X|\mathcal{G}_1].$$

- $\mathbb{E}[aX + bY|\mathcal{G}] = a\mathbb{E}[X|\mathcal{G}] + b\mathbb{E}[Y|\mathcal{G}]$  a.s.
- If  $X$  is  $\mathcal{G}$ -measurable, then

$$\mathbb{E}[X|\mathcal{G}] = X \text{ a.s.}, \quad \mathbb{E}[XY|\mathcal{G}] = X\mathbb{E}[Y|\mathcal{G}] \text{ a.s.}$$

## $\mathbb{E}[X|Y]$ as a function of $Y$

For r.v.  $X, Y$

$$\mathbb{E}[X|Y] := \mathbb{E}[X|\sigma(Y)]$$

- There exists a function  $h(y)$  such that

$$\mathbb{E}[X|Y](\omega) = h(Y(\omega)), \quad \omega \in \Omega.$$

We call  $h(y)$  *conditional expectation of  $X$  given  $Y = y$*  and write

$$\mathbb{E}[X|Y = y] := h(y).$$

This satisfies then the identity, for  $B \in \mathcal{B}(\mathbb{R})$

$$\mathbb{E}[X \mathbf{1}[Y \in B]] = \int_B h(y) dF_Y(y),$$

where  $F_Y$  is the c.d.f. of  $Y$ .

## Regular conditional probability

For disjoint  $A_n$ ,

$$\mathbb{P}[\cup_n A_n | \mathcal{G}] = \sum_n \mathbb{P}[A_n | \mathcal{G}]$$

almost surely, so for *fixed*  $\omega$  this cannot be considered as a probability measure on  $\mathcal{F}$ .

**Definition/Theorem** Let  $X$  be a (real) r.v. there exists a *regular conditional distribution function of  $X$  given  $\sigma$ -algebra  $\mathcal{G}$* , such that

- (i)  $F(\omega, x)$  is a distribution function (c.d.f.) in  $x$  for every  $\omega \in \Omega$ ,
- (ii) for  $x \in \mathbb{R}$

$$F(\omega, x) = \mathbb{P}[X \leq x | \mathcal{G}](\omega) \quad \text{a.s.}$$

Then

$$\mathbb{E}[X | \mathcal{G}](\omega) = \int_{-\infty}^{\infty} x \, d_x F(\omega, x), \quad \omega \in \Omega.$$