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Week 2

Lecture 4

In this lecture we shall discuss the basic properties of functions of one complex variable.

Functions of a Complex Variable

Def 2.1: Let $S \subseteq \mathbb{C}$ be a subset of complex numbers. A function f on S is a rule which assigns to each $z \in S$ a complex number (or complex numbers) $f(z)$, called the value of f at z . S is called the Domain of Definition (DoD)

Def 2.2: If for every z in the DoD corresponds one value w , then we say that f is single-valued function.

If to z correspond several values, then f is multi-valued function.

Ex 3.1 $f(z) = \frac{1}{z}$: f is not defined at $z=0$ and it is defined and single-valued everywhere else.

For example, the value of f at $z=8-3i$ is
 $f(8-3i) = \frac{1}{8-3i} = \frac{1}{8-3i} \cdot \frac{8+3i}{8+3i} = \frac{8}{8^2+3^2} + i \frac{3}{8^2+3^2} = \frac{8}{73} + i \frac{3}{73}$
 $f(i) = \frac{1}{i} = \frac{1}{i} \cdot \frac{-i}{-i} = \frac{-i}{1} = -i$

Ex 3.2: $f(z) = \sqrt{z+1}$ defined everywhere on \mathbb{C} and it is double-valued function: $f(0)=1$ and $f(0)=-1$ (for instance)

$f(1) = \sqrt{1}$: $|1|=1$, $\cos\theta = \frac{1}{1}$, $\sin\theta = \frac{0}{1} \Rightarrow \theta = 0 + 2\pi k$
 $\Rightarrow \sqrt{1} = \cos\left(\frac{2\pi k}{2}\right) + i \sin\left(\frac{2\pi k}{2}\right)$ $k=0,1$

$k=0$: $\cos 0 + i \sin 0 = 1$, $k=1$: $\cos \pi + i \sin \pi = -1$

Ex 3.3: $f(z) = \sqrt{z-1} + \sqrt{z+1}$ is 4-valued: for example, if $z=0$, we get $w_1 = i+1$, $w_2 = -i+1$, $w_3 = i-1$, $w_4 = -i-1$ (CHECK!)

Ex 3.4: Polynomials General form: $P_n(z) = \sum_{j=0}^n a_j z^j$ - polynomial of degree n of complex variable z with complex coefficients $a_j \in \mathbb{C}$.

For example: $f(z) = z^2$, $f(z) = 1 + iz - z^2 + (1+i)z^3$

Ex 3.5: Rational function {ratio of two polynomials}. General form $f(z) = \frac{a_0 + a_1 z + \dots + a_n z^n}{b_0 + b_1 z + \dots + b_m z^m}$ - defined and single-valued everywhere, except for the roots (zeros) of the denominator

Ex 3.6: The exponential function $f(z) = e^z$

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Defined to be the series $e^z = \sum_{n=0}^{\infty} \frac{z^n}{n!} = 1 + \frac{z}{1!} + \frac{z^2}{2!} + \dots$
 or equally well by Euler's formula: $e^z = e^x (\cos y + i \sin y)$
 {for $z = x + iy$ }

We will see later that the above series converges absolutely for all $z \in \mathbb{C}$, thus $f(z) = e^z$ can be defined for every z in \mathbb{C} , namely, we can take the DoD to be \mathbb{C} . It is single-valued.

Ex 3.7 Trigonometric and Hyperbolic functions: For $z \in \mathbb{C}$ define: (*) $\cos z = \frac{1}{2}(e^{iz} + e^{-iz})$ $\sin z = \frac{1}{2i}(e^{iz} - e^{-iz})$

which agrees with the definition for real z (by Euler's formula)

By analogy with the real case, we define

$$(**) \cosh z = \frac{1}{2}(e^z + e^{-z}), \quad \sinh z = \frac{1}{2}(e^z - e^{-z})$$

Using (*) and (**) it is easy to check that

$$\text{CHECK! } \cos z + i \sin z = e^{iz} = \cosh(iz) + \sinh(iz)$$

Let $z = x + iy$. We rewrite $f(z)$ and separate its real and imaginary parts as follows:

$$(1) f(z) = \operatorname{Re} f(z) + i \operatorname{Im} f(z) = u(x, y) + iv(x, y)$$

In this way we can think of f as of a real mapping:

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2: (2) (x, y) \mapsto (u(x, y), v(x, y)) \quad u, v: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

Let $z = r(\cos \theta + i \sin \theta)$ {the polar form}. Then, in a similar way

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2: (3) f(r, \theta) = \psi(r, \theta) + i\varphi(r, \theta)$$

Ex 3.8: Write in the form (1) or (3)

$$a) f(z) = z^2 \quad b) f(z) = |z| \quad c) f(z) = \operatorname{Re} z \quad d) f(z) = z^n \quad e) f(z) = e^z$$

Sol: a) Denote $z = x + iy$. Then $z^2 = (x + iy)^2 = (x^2 - y^2) + i2xy$

$$\Rightarrow \operatorname{Re} z^2 = x^2 - y^2, \quad \operatorname{Im} z^2 = 2xy, \quad \text{and } f(x, y) = (x^2 - y^2, 2xy)$$

OR: $z = r(\cos \theta + i \sin \theta) \Rightarrow z^2 = r^2(\cos 2\theta + i \sin 2\theta)$, where $r = |z|$, thus $\operatorname{Re} z^2 = r^2 \cos 2\theta$, $\operatorname{Im} z^2 = r^2 \sin 2\theta$, and $f(r, \theta) = (r^2 \cos 2\theta, r^2 \sin 2\theta)$

$$b) |z| = |x + iy| = \sqrt{x^2 + y^2} \Rightarrow f(x, y) = (\sqrt{x^2 + y^2}, 0) = \sqrt{x^2 + y^2} \rightarrow \text{real function!}$$

$$c) z = x + iy, \quad \operatorname{Re} z = x \Rightarrow f(x, y) = (x, 0) = x \rightarrow \text{real function!}$$

$$z = x + iy, \quad \operatorname{Im} z = y \Rightarrow \text{for } f(z) = \operatorname{Im} z: f(x, y) = (y, 0) = y \rightarrow \text{real!}$$

d) Let $z = r(\cos \theta + i \sin \theta)$ { $r = |z|$ }. Then, by De Moivre formula

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$$z^n = r^n (\cos(n\theta) + i\sin(n\theta)), \text{ and } f(r, \theta) = (r^n \cos(n\theta), r^n \sin(n\theta))$$

e) Let $z = x + iy$. Then, by Euler's formula: $e^z = e^x (\cos y + i\sin y)$
 $\Rightarrow f(x, y) = (e^x \cos y, e^x \sin y)$

We can also do the opposite: given a function of x, y we can rewrite it in terms of z and its conjugate:

Recall: $\operatorname{Re} z = \frac{1}{2}(z + \bar{z})$ $\operatorname{Im} z = \frac{1}{2i}(z - \bar{z})$

Ex 3.9: Rewrite in terms z and \bar{z} :

a) $f(x, y) = x^2 - y + i(x + y^2)$ b) $f(x, y) = x^2 - 1$

Sol: a) $x^2 - y + i(x + y^2) = \frac{1}{4}(z + \bar{z})^2 - \frac{1}{2i}(z - \bar{z}) + i\left(\frac{1}{2}(z + \bar{z}) + \frac{1}{4i}(z - \bar{z})^2\right) = \frac{1}{4}(z^2 + \bar{z}^2 + 2z\bar{z}) - \frac{1}{2i}(z - \bar{z}) + i\left(\frac{1}{2}(z + \bar{z}) - \frac{1}{4}(z^2 + \bar{z}^2 - 2z\bar{z})\right)$

$= \frac{1}{4}(z^2 + \bar{z}^2 + 2z\bar{z}) + \frac{i}{2}(z - \bar{z}) + \frac{i}{2}(z + \bar{z}) - \frac{1}{4}(z^2 + \bar{z}^2 - 2z\bar{z}) = \frac{1}{4}(z^2 + \bar{z}^2 + 2z\bar{z}) + iz - \frac{i}{4}(z^2 + \bar{z}^2 - 2z\bar{z})$
 $= \frac{1}{4}(z^2 + \bar{z}^2)(1 - i) + \frac{1}{2}z\bar{z}(1 + i) + iz$

b) $x^2 - 1 = \frac{1}{4}(z^2 + \bar{z}^2 + 2z\bar{z}) - 1 = \frac{1}{4}(z^2 + \bar{z}^2 + 2z\bar{z} - 4)$

Transformations of the Complex plane

A complex function is a map (transformation) from \mathbb{C} to \mathbb{C} , but to draw a graph of such mapping we would need $2+2=4$ real dimensions.

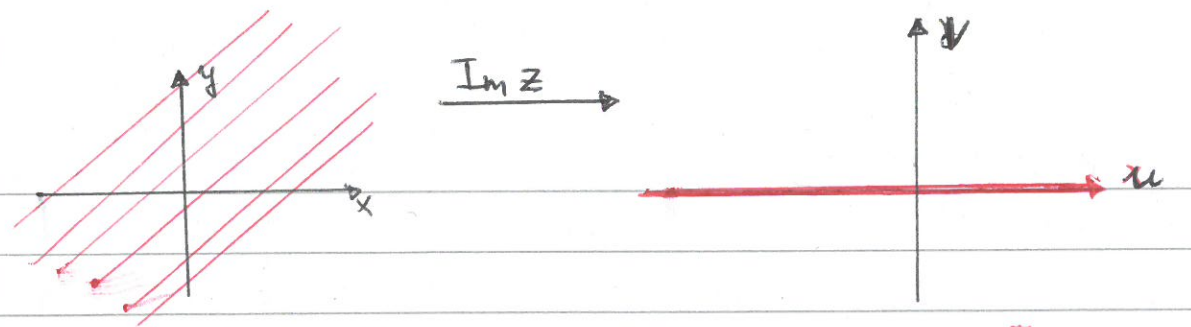
Instead, we shall examine what happens to various shapes - lines, circles, etc, under such map. Let us assume that f is single-valued function defined on some domain of definition. We will treat the function as a map that maps a set from (x, y) -plane to some other set in (u, v) -plane. Let us start with two simple examples.

Ex 4.1: Let $f(z) = \operatorname{Im} z$ (defined and single-valued everywhere).

Let us find its image f namely, where to the complex plane \mathbb{C} is mapped?

$\operatorname{Im} z = y \in \mathbb{R} \Rightarrow$ the complex plane \mathbb{C} is mapped to \mathbb{R} :

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Ex 4.2: What is the image of the ray $\arg z = \frac{\pi}{3}$ under $f(z) = z^3$?

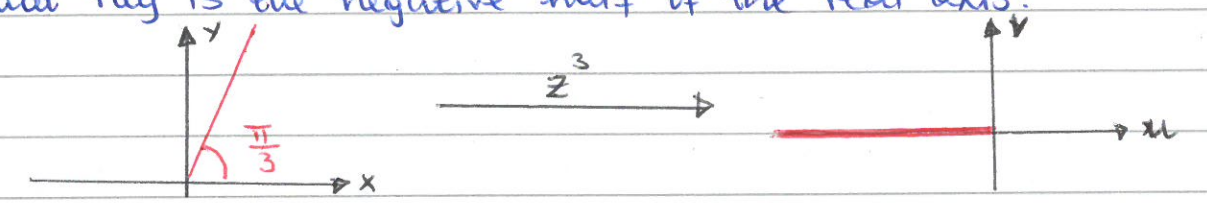
Sol: let us write the function f in polar coordinates:

$$f(z) = r^3 (\cos \theta + i \sin \theta)^3 = r^3 (\cos 3\theta + i \sin 3\theta) \quad \{ r = |z| \}$$

↓
De Moivre

Thus, the image of $\arg z = \frac{\pi}{3}$ under z^3 is
 $r^3 (\cos (3 \frac{\pi}{3}) + i \sin (3 \frac{\pi}{3})) = -r^3 \quad (r \geq 0!)$

Recall that $r = |z|$, therefore $r \geq 0$ always. Hence, the image of that ray is the negative half of the real axis:



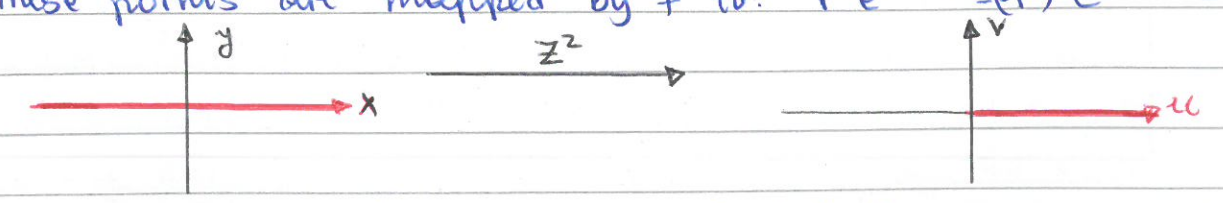
$f(z) = z^2$

Now we will examine the mapping $f(z) = z^2$ and will find the image of various curves and shapes under this mapping. Let us rewrite f in the polar and algebraic form:

$$z = x + iy : f(x, y) = u(x, y) + iv(x, y) = x^2 - y^2 + i 2xy$$

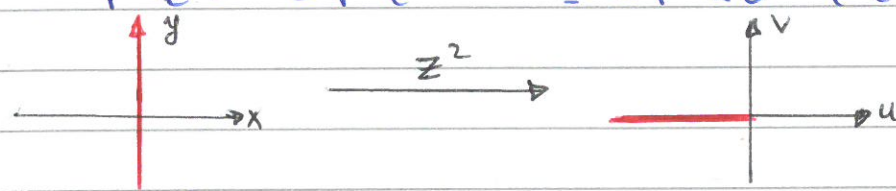
$$z = r e^{i\theta} : f(r, \theta) = r^2 e^{2i\theta} = r^2 \cos 2\theta + i r^2 \sin 2\theta$$

Ex 4.3: First, we determine what is the image of x-axis and of y-axis. The real axis \mathbb{R} is mapped to the positive half of the real axis \mathbb{R}_+ : $\mathbb{R} \xrightarrow{z^2} \mathbb{R}_+$. To see that we represent \mathbb{R} as $\mathbb{R} = \mathbb{R}_+ \cup \mathbb{R}_-$, where \mathbb{R}_+ (\mathbb{R}_-) the positive (negative) half of \mathbb{R} . Every point in \mathbb{R}_+ is of the form $r e^{i0} = r > 0$ and every point in \mathbb{R}_- is of the form $r e^{i\pi} = -r \leq 0$. These points are mapped by f to: $r^2 e^{2 \cdot i \cdot 0} = (r)^2 e^{2 \cdot i \cdot 0} = r^2 \in \mathbb{R}_+$

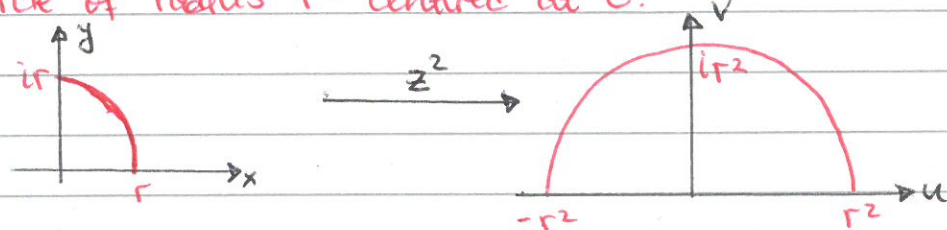


Now we will show (in the same way) that the imaginary axis is mapped to the negative half of the real axis: $i\mathbb{R} \xrightarrow{z^2} \mathbb{R}_-$

Represent the imaginary axis $i\mathbb{R}$ as: $i\mathbb{R} = (i\mathbb{R})_+ \cup (i\mathbb{R})_-$
 where $(i\mathbb{R})_+$ are points of the form $re^{i\frac{\pi}{2}} = ir$ ($r > 0$) and
 $(i\mathbb{R})_- : re^{i\frac{3\pi}{2}} = -ir$. f maps these points to
 $r^2 e^{i\frac{\pi}{2} \cdot 2} = r^2 e^{i\frac{3\pi}{2} \cdot 2} = -r^2 < 0$ ($e^{i\pi} = e^{i3\pi} = -1$)

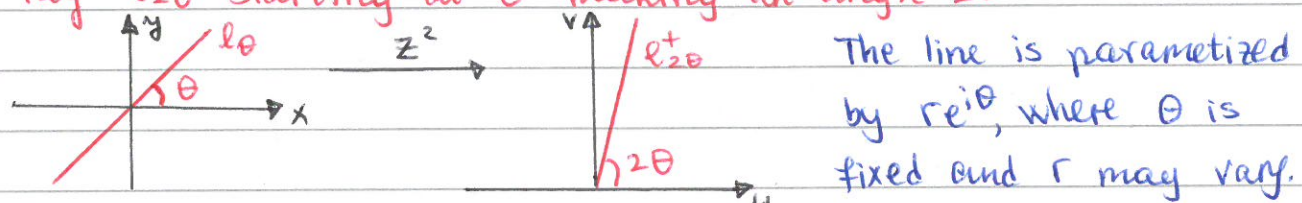


A quarter circle of radius r centered at 0 is mapped by z^2 to a half circle of radius r^2 centered at 0 :



Pf: The quarter circle is given by points $re^{i\theta}$ where $0 \leq \theta \leq \frac{\pi}{2}$.
 It is mapped by z^2 to $r^2 e^{2i\theta}$. Since $0 \leq \theta \leq \frac{\pi}{2} \Rightarrow 0 \leq 2\theta \leq \pi$,
 thus we obtain a half circle of radius r^2 centered at 0 . \square

A line l_θ passing through the origin at angle θ is mapped to a ray $l_{2\theta}^+$ starting at 0 making an angle 2θ .



The line is parametrized by $re^{i\theta}$, where θ is fixed and r may vary.

The map $f(z) = z^2$ sends r to r^2 resulting in a ray and the angle is transformed from θ to 2θ .

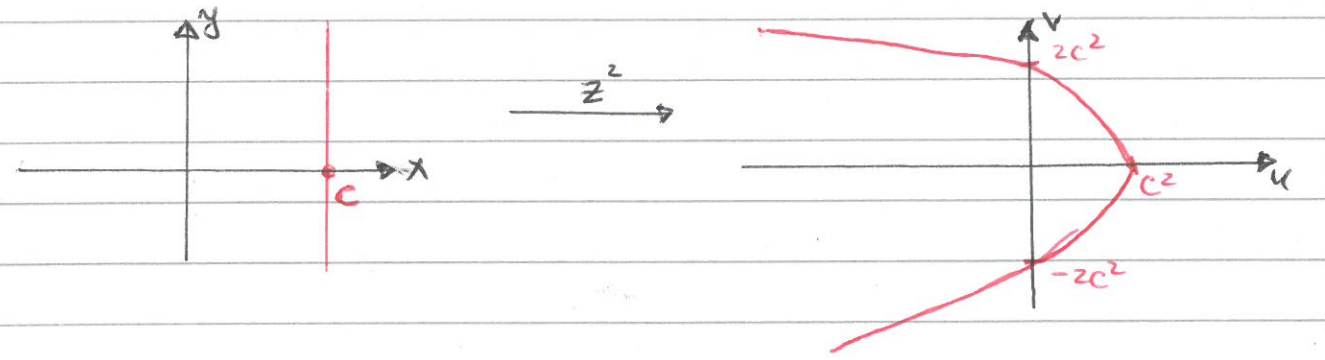
Now let us find the image of a vertical line $x = c \in \mathbb{R}$.
 In this case the geometric representation is more convenient:

$z \rightarrow z^2 : (x, y) \mapsto (x^2 - y^2, 2xy)$. Set $x = c$

We have the following system, from which we may eliminate the variable y to get an equation for a curve in (u, v) -plane:

$$\begin{cases} u = x^2 - y^2 = c^2 - y^2 \\ v = 2xy = 2cy \end{cases} \Rightarrow y = \frac{v}{2c} \Rightarrow u = c^2 - \frac{v^2}{4c^2}$$

this is leftward opening parabola with vertex $(c^2, 0)$, intersecting the v -axis at $(0, \pm 2c^2)$ {Note that: if c is negative, the image again is the same, namely, the image is independent of the sign of c }



Lectures 5+6

We continue to examine the images under z^2 and other transformations.

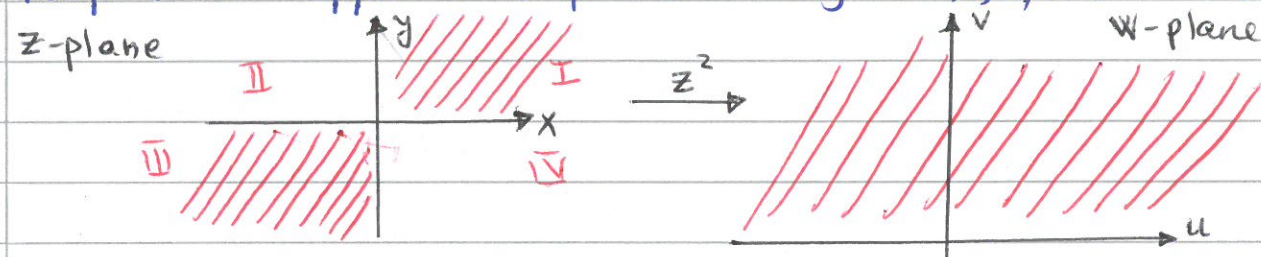
Ex 4.4: Determine which regions (if any) of the z -plane are mapped to the upper half part of the w -plane under the mapping $w = z^2$

First, we identify: the upper half of w -plane = $\{w \in \mathbb{C} \mid \text{Im } w \geq 0\}$

An element $z = re^{i\theta} \xrightarrow{z^2} w = r^2 e^{2i\theta}$ is in the upper half plane iff the argument of w lies between 0 and π $0 \leq \arg w \leq \pi$:

$$0 + 2\pi k \leq 2\theta \leq \pi + 2\pi k, k \in \mathbb{Z} \Rightarrow k\pi \leq \theta \leq \frac{\pi}{2} + \pi k$$

Namely, z must lie in the first or third quadrant in order to map to the upper half plane [Plug $k=1, 2, 3, 4$ to see this!]



Alternatively: we could use the algebraic form $x+iy$ and get:

$$w = z^2 = x^2 - y^2 + i2xy \Rightarrow \text{Im } w \geq 0 \Leftrightarrow 2xy \geq 0 \Leftrightarrow x, y \geq 0 \text{ or } x, y \leq 0$$

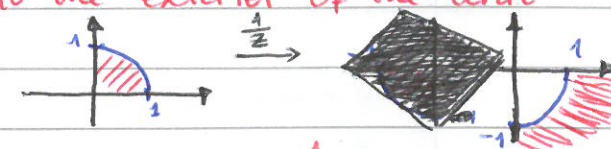
This gives again I and III quadrant

Now let us study another function and its images.

Ex 4.5 Look at $z \rightarrow \frac{1}{z} = w$

It is an instructive exercise to draw a picture trying to determine where to various regions of the plane are mapped.

EXERCISE: 1) Show that $w = \frac{1}{z}$ maps the interior of the unit circle in the first quadrant to the exterior of the unit circle in the fourth quadrant:



2) What is the image of the unit circle under $\frac{1}{z}$?

3) Write down how $z \rightarrow \frac{1}{z} = w$ maps the punctured plane $\mathbb{C} \setminus \{0\}$ to itself (and $\mathbb{C} \cup \{\infty\}$ to itself)

Back to Ex 4.5. Let us study two images under $\frac{1}{z}$

a) Find the image of the line $z = t + i(1-t)$ under $\frac{1}{z}$.

Sol: Denote: $w = u + iv, z = x + iy \Rightarrow x = t, y = (1-t)$

$$w = u + iv = \frac{1}{z} = \frac{1}{x + iy} = \frac{1}{z} \quad (\text{for } z \neq 0, w \neq 0) \Leftrightarrow x + iy = \frac{1}{u + iv} = \frac{u}{u^2 + v^2} + i \frac{-v}{u^2 + v^2}$$

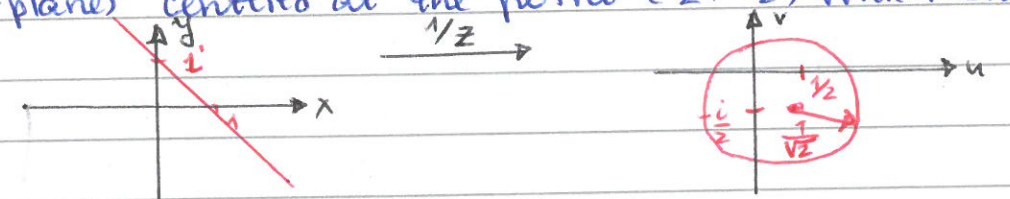
Thus, plugging $x = t, y = 1 - t$, we obtain the following system:

$$\begin{cases} t = \frac{u}{u^2 + v^2} \\ 1 - t = \frac{-v}{u^2 + v^2} \end{cases} \Leftrightarrow \begin{cases} t(u^2 + v^2) = u \\ (1 - t)(u^2 + v^2) = -v \end{cases} \Leftrightarrow \begin{cases} t(u^2 + v^2) = u \\ u^2 + v^2 - t(u^2 + v^2) = -v \end{cases}$$

$$\Leftrightarrow u^2 + v^2 = u - v \quad (\text{we add the equations}) \Leftrightarrow u^2 - u + v^2 + v = 0$$

$$\Leftrightarrow (u - \frac{1}{2})^2 + (v + \frac{1}{2})^2 = \frac{1}{2} \quad (\text{complete the square in } u \text{ and } v)$$

Namely, the map $w = \frac{1}{z}$ maps the line $z = t + i(1 - t)$ to the circle (in w -plane) centered at the point $(\frac{1}{2}, -\frac{1}{2})$ with radius $\frac{1}{\sqrt{2}}$:



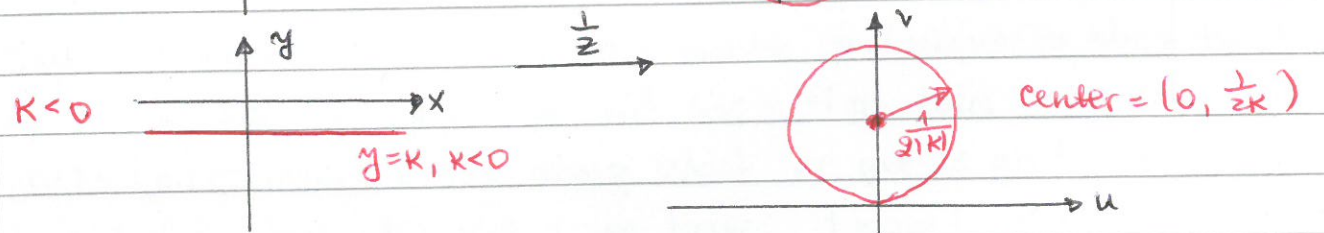
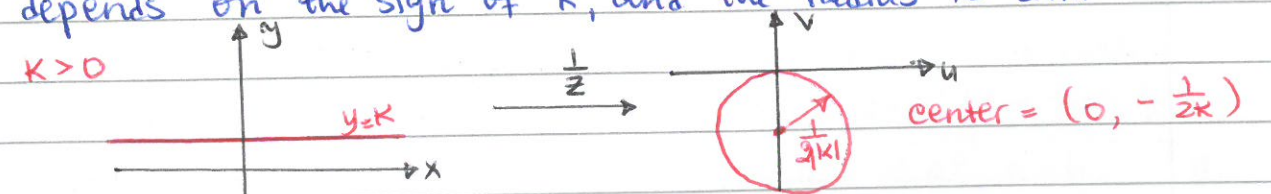
b) Determine how the horizontal line $y = k$ is transformed under $w = \frac{1}{z}$

Sol: Substitute as before: $x = \frac{u}{u^2 + v^2}, y = \frac{-v}{u^2 + v^2}$. Plug $y = k$:

$$k = \frac{-v}{u^2 + v^2} \Leftrightarrow ku^2 + kv^2 + v = 0 \Leftrightarrow (k \neq 0) u^2 + v^2 + \frac{v}{k} = 0$$

$$\Leftrightarrow u^2 + (v + \frac{1}{2k})^2 = \frac{1}{4k^2} \quad (\text{complete the square in } v)$$

Namely, the line is mapped onto a circle, centre of which depends on the sign of k , and the radius is $\frac{1}{2|k|}$



Now we have a feeling on geometrical description of the complex functions; we will study more transformations later.

Next subject - the limits of complex functions. The introduction of a limit will allow us to investigate what it means for the complex function f to be continuous and differentiable. Through several explicit examples, we contrast our findings

with corresponding results for real functions.

Limits

Let f be a complex function. We say that $\lim_{z \rightarrow z_0} f(z) = w_0$ if when z is "close" to z_0 , $f(z)$ is "close" to w_0 . Formally:

Def 3.1: $\lim_{z \rightarrow z_0} f(z) = w_0$ if for any given $\epsilon > 0$, there exists $\delta = \delta(\epsilon) > 0$ such that $\forall z \rightarrow z_0$ if $0 < |z - z_0| < \delta$, then $|f(z) - w_0| < \epsilon$

Ex 5.1: Let $f(z) = \frac{\bar{z}}{z}$. Claim: for any $z_0 \neq 0$, $\lim_{z \rightarrow z_0} \frac{\bar{z}}{z} = \frac{\bar{z}_0}{z_0}$

Pf: Given $\epsilon > 0$, choose $\delta = 2\epsilon$. Then, if $|z - z_0| < \delta$:

$$\left| \frac{\bar{z}}{z} - \frac{\bar{z}_0}{z_0} \right| = \frac{1}{2} |\bar{z} - \bar{z}_0| = \frac{1}{2} |z - z_0| < \frac{1}{2} \delta = \frac{1}{2} 2\epsilon = \epsilon$$

Thus, for a given $\epsilon > 0$ we have found δ (that depends on ϵ !) s.t. if $|z - z_0| < \delta$, then $|f(z) - w_0| = \left| \frac{\bar{z}}{z} - \frac{\bar{z}_0}{z_0} \right| < \epsilon$ (for any $z_0 \neq 0$!)

Ex 5.2: Let $f(z) = \frac{\bar{z}}{z}$, $z \neq 0$. Prove that $\lim_{z \rightarrow 0} \frac{\bar{z}}{z}$ does not exist.

Before we proceed to the proof, let us show the following:

Claim 3.1: If $\lim_{z \rightarrow z_0} f(z)$ exists, then it is unique.

Pf: Assume $\lim_{z \rightarrow z_0} f(z) = a$ and $\lim_{z \rightarrow z_0} f(z) = b$. By Def 3.1 for any $\epsilon > 0$ there exist $\delta_1 > 0$ and $\delta_2 > 0$ such that

$$\text{if } |z - z_0| < \delta_1 \Rightarrow |f(z) - a| < \epsilon/2$$

$$\text{if } |z - z_0| < \delta_2 \Rightarrow |f(z) - b| < \epsilon/2$$

Choose $\delta < \min(\delta_1, \delta_2) \Rightarrow$ for $0 < |z - z_0| < \delta$ $|f(z) - a| < \epsilon/2$ and $|f(z) - b| < \epsilon/2$. Thus, using triangle inequality, we obtain

$$\textcircled{*} |a - b| = |a - f(z) + f(z) - b| \leq |a - f(z)| + |f(z) - b| < \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon$$

Since $\textcircled{*}$ holds for any $\epsilon > 0$ we obtain that $a = b$. \square

Back to Ex 5.2: we will use a common technique to show that the limit does not exist - we will show that there exist two different paths (directions) $z \rightarrow z_0$ along which we get 2 different limits

Ex 5.2 Pf: Note: for real z we have: {namely, fix $y=0$ }

$$z = x \in \mathbb{R}: \frac{\bar{z}}{z} = \frac{\bar{x}}{x} = \frac{x}{x} = 1 \Rightarrow \lim_{x \rightarrow 0} \frac{\bar{z}}{z} = 1$$

On the other hand, for purely imaginary z we get: {namely, fix $x=0$ }

$$z = iy \in i\mathbb{R}: \frac{\bar{z}}{z} = \frac{-iy}{iy} = \frac{-iy}{iy} = -1 \Rightarrow \lim_{iy \rightarrow 0} \frac{\bar{z}}{z} = -1$$

\Rightarrow the limit as $z \rightarrow 0$ does not exist. \square

Note: For any $z_0 \neq 0$, $\lim_{z \rightarrow z_0} \frac{\bar{z}}{z} = \frac{\bar{z}_0}{z_0}$

Pf: Given $\epsilon > 0$, choose $\delta = \frac{\epsilon}{2} |z_0|$. Then

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$$\begin{aligned} \left| \frac{\bar{z}}{z} - \frac{\bar{z}_0}{z_0} \right| &= \left| \frac{z\bar{z}_0 - \bar{z}z_0}{z z_0} \right| = \left| \frac{\bar{z}z_0 + \bar{z}z - \bar{z}z - \bar{z}_0 z}{z z_0} \right| = \left| \frac{\bar{z}(z_0 - z) + z(\bar{z} - \bar{z}_0)}{z z_0} \right| \\ &\leq \left| \frac{\bar{z}(z_0 - z)}{z z_0} \right| + \left| \frac{z(\bar{z} - \bar{z}_0)}{z z_0} \right| = \frac{|\bar{z}| |z_0 - z|}{|z| |z_0|} + \frac{|z| |\bar{z} - \bar{z}_0|}{|z| |z_0|} = \\ &= \frac{|z| |z_0 - z|}{|z| |z_0|} + \frac{|z - z_0|}{|z_0|} = 2 \frac{|z - z_0|}{|z_0|} < \frac{2}{|z_0|} \delta = \frac{2}{|z_0|} \cdot \frac{\epsilon}{2} |z_0| = \epsilon \quad \square \end{aligned}$$

Ex 5.3 Show that $\lim_{z \rightarrow 0} \frac{z^2}{\bar{z}}$ does not exist

Sol: Here, for $z = x \in \mathbb{R}$: $\frac{z^2}{\bar{z}} = \frac{x^2}{x^2} = 1$ and for $z = iy \in i\mathbb{R}$
 $\frac{z^2}{\bar{z}} = \frac{(iy)^2}{(iy)} = \frac{-y^2}{-iy} = 1$. However, choosing the path $z = (1+i)t$

for $t \in \mathbb{R} \setminus \{0\}$ gives us $\frac{z^2}{\bar{z}} = \frac{2it^2}{-2it^2} = -1 \neq 1$ - does not agree

with the value on previous two paths, thus we can conclude that the original limit does not exist

Alternatively: Let $z = re^{i\theta}$, $r, \theta \in \mathbb{R}$. Then $z \rightarrow 0$ means $r \rightarrow 0$
since $e^{i\theta} \neq 0$ for all $\theta \in \mathbb{R}$. We have: $\frac{z^2}{\bar{z}} = \frac{r^2 e^{2i\theta}}{r e^{-i\theta}} = r e^{3i\theta}$
 $\Rightarrow \lim_{z \rightarrow 0} \frac{z^2}{\bar{z}} = \lim_{r \rightarrow 0} \frac{r^2 e^{2i\theta}}{r e^{-i\theta}} = \lim_{r \rightarrow 0} r e^{3i\theta} = 0$

For different θ -s we get different limits - namely, on different paths the limit does not agree \Rightarrow the limit does not exist.

Ex 5.3 shows that the different paths need not be the real and imaginary axes!

Rmk: If $\lim_{z \rightarrow z_0} f(z) = w_0$ exists, then $f(z) \rightarrow w_0$ as $z \rightarrow z_0$ on every path (uniqueness of the limit!) If on different paths $z \rightarrow z_0$ there are different values of the limit (or there exists a path on which the limit does not exist), then the limit $\lim_{z \rightarrow z_0} f(z)$ does not exist.

Similarly to the real functions we have the following proposition for the complex functions.

Prop 3.1: If $\lim_{z \rightarrow z_0} f(z) = w_0$ and $\lim_{z \rightarrow z_0} g(z) = w_1$, then

- 1) $\lim_{z \rightarrow z_0} (f(z) + g(z)) = w_0 + w_1$
- 2) $\lim_{z \rightarrow z_0} f(z) \cdot g(z) = w_0 \cdot w_1$
- 3) If $w_1 \neq 0$, then $\lim_{z \rightarrow z_0} \frac{f(z)}{g(z)} = \frac{w_0}{w_1}$

Pf: EXERCISE - a very good exercise to "play" with ϵ - δ definition!
Next proposition provides a relation between the limit of the

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complex function and its real and imaginary parts (that are real functions)

Prop 3.2: Let $f(z) = u(x,y) + iv(x,y)$, $z_0 = x_0 + iy_0$. Then

$$\lim_{z \rightarrow z_0} f(z) = u_0 + iv_0 = w_0 \Leftrightarrow \lim_{(x,y) \rightarrow (x_0,y_0)} u(x,y) = u_0 = \operatorname{Re} w_0 \text{ and } \lim_{(x,y) \rightarrow (x_0,y_0)} v(x,y) = v_0 = \operatorname{Im} w_0$$

Note: the first limit is complex, but the last two limits are real!

Pf: \Rightarrow Assume that $\lim_{z \rightarrow z_0} f(z) = u_0 + iv_0$. Let us show that

$$\lim_{(x,y) \rightarrow (x_0,y_0)} u(x,y) = u_0 = \operatorname{Re} w_0 \text{ and } \lim_{(x,y) \rightarrow (x_0,y_0)} v(x,y) = v_0 = \operatorname{Im} w_0.$$

By Def 3.1: given $\epsilon > 0$ there exists $\delta = \delta(\epsilon) > 0$ s.t. for all z with $0 < |z - z_0| < \delta$ we have $|f(z) - (u_0 + iv_0)| < \epsilon$.

Since for any $z \in \mathbb{C}$: $|\operatorname{Im} z|, |\operatorname{Re} z| < |\operatorname{Re} z + i \operatorname{Im} z| = |z|$, we get:

$$\begin{aligned} |v(x,y) - v_0|, |u(x,y) - u_0| &< |u(x,y) - u_0 + i(v(x,y) - v_0)| \\ &= |u(x,y) + iv(x,y) - (u_0 + iv_0)| \\ &= |f(z) - (u_0 + iv_0)| < \epsilon \end{aligned}$$

Thus $|u(x,y) - u_0| < \epsilon$ and $|v(x,y) - v_0| < \epsilon$

CHECK: $|z - z_0|$ is the distance from (x,y) to (x_0,y_0) in \mathbb{R}^2

$$\Rightarrow \lim_{(x,y) \rightarrow (x_0,y_0)} u(x,y) = u_0 \text{ and } \lim_{(x,y) \rightarrow (x_0,y_0)} v(x,y) = v_0$$

Note: $|z - z_0| < \delta \Rightarrow |x + iy - (x_0 + iy_0)| = |(x - x_0) + i(y - y_0)| < \delta$, and we get $|x - x_0|, |y - y_0| \leq |(x - x_0) + i(y - y_0)| < \delta$

\Leftarrow Assume that $\lim_{(x,y) \rightarrow (x_0,y_0)} u(x,y) = u_0$ and $\lim_{(x,y) \rightarrow (x_0,y_0)} v(x,y) = v_0$ \otimes

Let $\epsilon > 0$. Since u and v have real limits u_0, v_0 as $(x,y) \rightarrow (x_0,y_0)$ from Def 3.1 there exist $\delta_1 > 0$ and $\delta_2 > 0$ such that if

$$\begin{aligned} 0 < \|(x,y) - (x_0,y_0)\| < \delta_1, \text{ then } |u(x,y) - u_0| < \frac{\epsilon}{2}, \text{ and} \\ 0 < \|(x,y) - (x_0,y_0)\| < \delta_2, \text{ then } |v(x,y) - v_0| < \frac{\epsilon}{2}. \end{aligned}$$

Choose $\delta < \min(\delta_1, \delta_2)$. Then, whenever $0 < \|(x,y) - (x_0,y_0)\| < \delta$:

$$\begin{aligned} |u(x,y) + iv(x,y) - (u_0 + iv_0)| &= |u(x,y) - u_0 + i(v(x,y) - v_0)| \\ &\leq |u(x,y) - u_0| + |v(x,y) - v_0| < \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon \end{aligned}$$

\downarrow triangle inequality \downarrow by \otimes

Namely, for any $\epsilon > 0$ we have found $\delta > 0$ such that whenever $0 < |z - z_0| < \delta$: $|f(z) - (u_0 + iv_0)| < \epsilon$, as required. \square