

Lecture 10B

MTH6102: Bayesian Statistical Methods

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Today's agenda

Today's lecture

- Learn how to use the law of total probability to compute prior and posterior predictive probabilities.

Predicting new data

- In previous lectures, we looked at updating the probability of parameters (hypotheses) based on data.
- We have observed data (result of the experiment) $y \sim p(y \mid \theta)$, dependent on parameters θ .
- Suppose we have found the posterior distribution $p(\theta \mid y)$.
- **Question:** What is the probability distribution of new data x of a future experiment?

Predictive probabilities

- In this lecture, we are going to focus on **predictive probabilities**.
- Predictive probability means assigning a probability to each possible outcome of a **future experiment**.
- There are many examples where we want to make probabilistic prediction: weather forecasting,
“Tomorrow it will rain with probability 60% ”
- Other examples: medical treatment outcomes, climate change, sports betting etc

Example: Three types of coins

There are three types of coins

- Type A coins are fair, with probability 0.5 of heads.
- Type B coins have probability 0.6 of heads.
- Type C coins have probability 0.9 of heads.

You have a drawer containing 4 coins: 2 of type A, 1 of type B, and 1 of type C.

You pick a coin at random.

Example: Three types of coins

- **Prior predictive probabilities.** Before taking data, what is the probability that our chosen coin will land heads?
- Let $D_{1,H}$ be the event that the first toss lands heads.
- Let A be the event the chosen coin is of type A . Likewise for B and C . Then,

$$P(A) = 0.5, \quad P(B) = 0.25, \quad P(C) = 0.25.$$

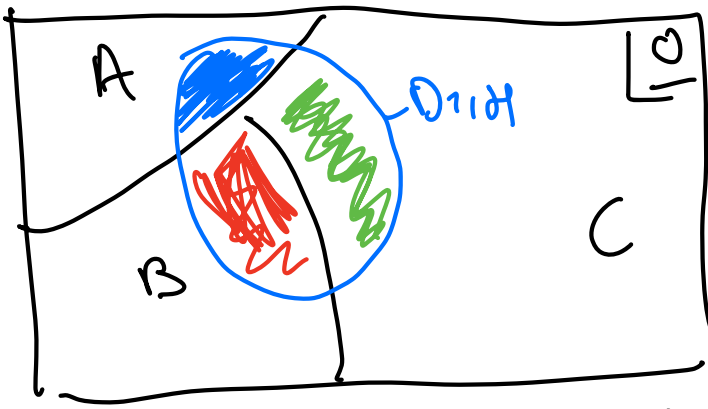
These are the prior probabilities of the hypotheses, before flipping the coin

Example: Three types of coins

- By the **law of total probability**, the **prior predictive probability** that the coin lands heads is

$$\underbrace{P(D_{1,H})}_{\text{prior predictive probability}} = P(D_{1,H} | A)P(A) + P(D_{1,H} | B)P(B) + \underbrace{P(D_{1,H} | C)P(C)}_{\text{prior predictive probability}} = 0.625$$

- **Prior predictive probabilities.** Assign a probability to an outcome of the experiment. They are computed **before we collect any data**.



The law of total probability states

$$P(D_{1, H}) = P(A)P(D_{1, H}|A) + P(B)P(D_{1, H}|B) + P(C)P(D_{1, H}|C)$$

weighted sum where the weights are the prior probabilities

Posterior predictive probabilities

Example: Three types of coins

- **Take data:** We flip the chosen coin once and it **lands heads**.
- We now have data, $D_{1,H}$ (first toss lands heads). Given the data $D_{1,H}$, we update the prior probabilities of the hypotheses to posterior probabilities.
- The Bayes updating table is

hypothesis	prior	likelihood	Bayes num.	posterior
H	$P(H)$	$P(D_{1,H} H)$	$P(D_{1,H} H)P(H)$	$P(H D_{1,H})$
A	0.5	0.5	0.25	0.4
B	0.25	0.6	0.15	0.24
C	0.25	0.9	0.225	0.36
Total	1		$P(D_{1,H}) = 0.625$	1

- $P(D_{1,H}) = P(D_{1,H} | A)P(A) + P(D_{1,H} | B)P(B) + P(D_{1,H} | C)P(C) = 0.625 = P(\text{data})$.

$$P(D_{112} | A) = 0.5$$

Example: Three types of coins

- **Posterior predictive probabilities.** Given $D_{1,H}$ has happened (flipped the coin once and got heads), what is the probability that our chosen coin will land heads if flipped second time?
- Let $D_{2,H}$ the event “heads second time”.
- We want to compute $P(D_{2,H} \mid D_{1,H})$, called the **posterior probability that the next toss lands heads.**

Example: Three types of coins

- We assume that $D_{1,H}$ and $D_{2,H}$ are independent **given** the chosen coin.
- By the law of total probability,

$$P(D_{2,H} | D_{1,H}) = P(D_{2,H} | A)P(A | D_{1,H}) + P(D_{2,H} | B)P(B | D_{1,H}) + P(D_{2,H} | C)P(C | D_{1,H}) = 0.668$$

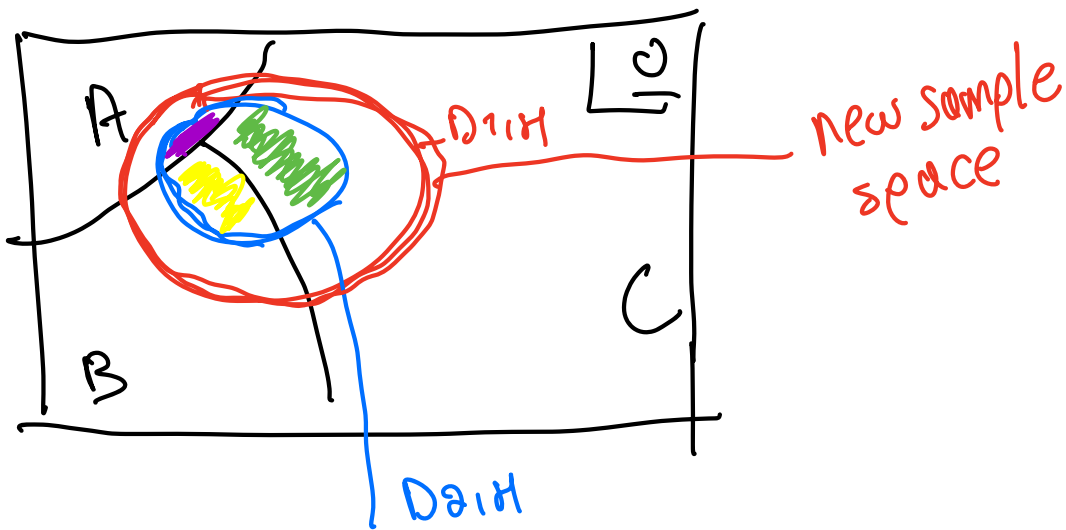
- We use the posterior probabilities $P(A | D_{1,H})$, $P(B | D_{1,H})$ and $P(C | D_{1,H})$ as weights in place of the prior probabilities, $P(A)$, $P(B)$ and $P(C)$
- The heads on the first toss increases the probability of heads in the second toss.

• A and B are independent if

$$\underline{P(A|B) = P(A)}$$

• Now, I have three events A, B, C. We know that C has happened, and given C the events A and B are independent.

$$P(\underline{A}|\underline{B}, \underline{C}) = P(A|C)$$



The law of total probability states

$$\begin{aligned}
 P(D_{2,H} | D_{1,H}) &= P(D_{2,H} | A, D_{1,H}) P(A | D_{1,H}) \\
 &+ P(D_{2,H} | B, D_{1,H}) P(B | D_{1,H}) \\
 &+ P(D_{2,H} | C, D_{1,H}) P(C | D_{1,H})
 \end{aligned}$$

Since $D_{1,H}$ and $D_{2,H}$ are conditionally given the chosen coin we have

$$P(D_{2,H} | D_{1,H}, A) = P(D_{2,H} | A)$$

$$P(D_{2,H} | D_{1,H}, B) = P(D_{2,H} | B)$$

$$P(D_{2,H} | D_{1,H}, C) = P(D_{2,H} | C)$$

Posterior predictive probabilities

- Posterior predictive probabilities give a prediction of a future outcome, after collecting data and updating prior to posterior.
- **Remember:**
 - Prior and posterior probabilities are for hypotheses/parameters.
 - Prior predictive and posterior predictive probabilities are for data.
 - Posterior predictive probabilities are used to predict **future data** when the experiment is performed again.

Predictive distributions: discrete prior, discrete data

- Discrete data: $y \sim p(y | \theta)$, with θ unknown
- Discrete likelihood: $p(y | \theta)$.
- Discrete hypothesis θ with values $\theta_1, \theta_2, \dots, \theta_K$.
- Prior pmf $p(\theta_i)$ of θ , $p(\theta_i) = p(\theta = \theta_i)$, $i = 1, \dots, K$.
- Posterior pmf $p(\theta_i | y) = p(\theta = \theta_i | y)$, $i = 1, \dots, K$.
- Let x : future data of the same experiment. We assume that x and y are independent given θ_i .
- By, the **law of total probability**, the **posterior predictive probability of x** is

$$p(x|y) = \sum_{i=1}^K p(x|\theta_i) p(\theta_i|y).$$

$$P(y) = \sum_{i=1}^K \underline{P(y|\theta_i)} \underline{P(\theta_i)}$$

$$P(x|y) = \sum_{i=1}^K P(x|\theta_i, y) P(\theta_i|y)$$

Because x and y are independent given θ_i

$$\underline{P(x|\theta_i, y)} = P(x|\theta_i)$$

so

$$P(x|y) = \sum_{i=1}^K P(x|\theta_i) \underline{P(\theta_i|y)}$$

We have that x and the observed data y are conditionally independent given θ . But x is generated from the same probability model $p(\cdot|\theta)$.

- Two R.V X and Y are independent if

$$\underline{f_{X|Y}(x|y) = f_X(x)}$$

- We RV (X, Y, Z) . Then, X and Y are conditionally independent given Z if

$$f_{X|Y}(x|y, z) = f_{X|Z}(x|z)$$

Board example

There are three type of coins in the drawer with probabilities 0.5, 0.6 and 0.9 of heads, respectively. Each coin is equally likely

Data: Pick one and toss 5 times. You get 1 head out of 5 tosses.

- (a) Compute the posterior probabilities for the type of coin
- (b) Compute the posterior predictive distributions of observing heads in a future toss.

Solution

Data: $y = 1 \sim \text{binomial}(5, \theta)$ where $\theta \in \{0.5, 0.6, 0.9\}$

• Prior pmf

$$P(\theta = 0.5) = 1/3$$

$$P(\theta = 0.6) = 1/3$$

$$P(\theta = 0.9) = 1/3$$

• Likelihood: $p(y=1|\theta) = \binom{5}{1} \theta^1 (1-\theta)^4$
 $= 5\theta(1-\theta)^4, \theta \in \{0.5, 0.6, 0.9\}$

$$p(y=1|\theta) = \begin{cases} 0.15625, & \theta = 0.5 \\ 0.0768, & \theta = 0.6 \\ 0.00045, & \theta = 0.9 \end{cases}$$

• Posterior probabilities, $p(\theta | y=1)$
 $\theta \in \{0.5, 0.6, 0.9\}$. By Bayes' theorem,

$$p(\theta | y=1) = \frac{p(y=1|\theta) p(\theta)}{p(y=1)}, \theta \in \{0.5, 0.6, 0.9\}$$

parameters	prior	likelihood	Bayes num.	posterior prob.
$\theta = 0.5$	7/3	0.15625	0.0521	0.669
$\theta = 0.6$	7/3	0.0768	0.0256	0.324
$\theta = 0.9$	7/3	0.00045	0.00015	0.00193
Total	1		$P(y=1)$ $= 0.07785$	↑

$$P(y=1) = \int_{\theta \in \{0.5, 0.6, 0.9\}} p(y=1|\theta) p(\theta)$$

Board example

- Does the order of the 1 head and 4 tails affect the posterior distribution of the coin type?
 - (a) Yes
 - (b) No.

- Does the order of the 1 head and 4 tails affect the posterior predictive distribution of the next flip?
 - (a) Yes
 - (b) No.

Board example

- Suppose that y is the number of expensive goods in a shop over 24 days. So $y \sim \text{Poisson}(24\theta)$ where $\theta = 1/2$, $\theta = 1/4$ or $\theta = 1/8$.
- Suppose the prior pmf is

$$p(\theta = 1/2) = p(1/2) = 0.2, \quad p(\theta = 1/4) = p(1/4) = 0.5, \\ p(\theta = 1/8) = p(1/8) = 0.3.$$

- We observe $y = 10$ expensive goods were sold in the last 24 days.
 - 1 Compute the posterior pmf for θ .
 - 2 Compute the posterior predictive distribution that $x = 10$ number of goods will be sold in the next 24 days.

Predictive distributions: continuous prior, discrete data

- Continuous parameter θ in the range $[a, b]$.
- Prior: $p(\theta)$, $\theta \in [a, b]$.
- Discrete data, y . Likelihood $p(y|\theta)$.
- By, the **law of total probability**, the **prior predictive probability of y** is

$$p(\text{data}) = p(y) = \int_a^b p(y|\theta) p(\theta) d\theta,$$

where the integral is computed over the entire range of θ .

- **Note:** $p(y)$ is a probability mass function, i.e., $p(y) = P(Y = y)$

Predictive distributions: continuous prior, discrete data

- Posterior: $p(\theta|y)$
- x : future data of the same experiment. We assume that x and y are independent given θ
- By, the **law of total probability**, the **posterior predictive probability of x** is

$$p(x|y) = \int_a^b p(x|\theta) p(\theta|y) d\theta.$$

Example

We have a coin with unknown probability θ of heads.

Prior: $p(\theta) = 2\theta, \theta \in [0, 1]$.

- Find the prior predictive probability of throwing heads on the first toss.
- Suppose the first flip was heads. Find the posterior predictive probabilities of both heads and tails on the second flip.

Example: beta prior/ binomial data

- Data, $k \sim \text{binomial}(n, q)$
- Prior, $q \sim \text{beta}(\alpha, \beta)$.
 - Find the posterior predictive probability to observe success on the next Bernoulli trial.
 - Find the posterior predictive probability to observe a new outcome x on the next Bernoulli trial.

Board example

Data: 10 patients have 6 successes. $\theta \sim \text{beta}(5, 5)$

- Find the posterior distribution of θ .
- Find the posterior predictive probability of success with the next patient.

Posterior predictive distribution: continuous prior, continuous data

- Continuous parameter θ in the range $[a, b]$.
- Prior pdf: $p(\theta)$, $\theta \in [a, b]$.
- Continuous data, y . Likelihood $p(y|\theta)$.
- The **prior predictive pdf of y** is

$$p(y) = \int_a^b p(y|\theta) p(\theta) d\theta,$$

where the integral is computed over the entire range of θ .

- **Note:** $p(y)$ is a pdf.

Posterior predictive distribution: continuous prior, continuous data

- Posterior pdf: $p(\theta|y)$
- x : future data of the same experiment.
- The posterior predictive probability of x is

$$p(x|y) = \int_a^b p(x|y, \theta) p(\theta|y) d\theta.$$

- As usual, we usually assume x and y are conditionally independent given θ . That is, $p(x|y, \theta) = p(x|\theta)$.
- In this case,

$$p(x|y) = \int_a^b p(x|\theta) p(\theta|y) d\theta.$$

Posterior predictive distribution

The posterior predictive distribution for x given the observed data y is

$$p(x | y) = \int p(x | \theta) p(\theta | y) d\theta$$

- This is the probability distribution for unobserved or future data x .
- This distribution includes two types of uncertainty:
 - the uncertainty remaining about θ after we have seen y ;
 - the random variation in x .

Board example: Exponential data/Gamma prior

- The time until failure for a type of light bulb is exponentially distributed with parameter $\theta > 0$, where θ is unknown.
 - We observe n bulbs, with failure times t_1, \dots, t_n .
 - We assume a $\text{Gamma}(\alpha, \beta)$ prior distribution for θ , where $\alpha > 0$ and $\beta > 0$ are known.
- 1 Determine the predictive posterior distribution for future data x

Finding the posterior predictive distribution

$$p(x | y) = \int p(x | \theta) p(\theta | y) d\theta$$

- In conjugate examples, one can usually derive $p(x | y)$.
- It is generally easier to find the mean and variance of $p(x | y)$ than deriving the full distribution.

Conditional mean and variance in general

- Suppose that X and W are general random variables.
- Then

$$E(X) = E(E(X | W)) \quad \text{law of iterated expectation}$$

and

$$\text{Var}(X) = \text{Var}(E(X | W)) + E(\text{Var}(X | W)) \quad \text{law of total variance}$$

- In Bayesian inference, we replace W with parameters and X with the new data we would like to predict.

Mean and variance of posterior predictive distribution

- For new data x and parameter(s) θ

$$E(x) = E(E(x | \theta))$$

$$Var(x) = Var(E(x | \theta)) + E(Var(x | \theta))$$

Mean and variance of posterior predictive distribution

- Add conditioning on observed data y , since we want *posterior* predictions

$$E(x | y) = E(E(x | \theta, y)) \quad \text{law of iterated expectation}$$

$$\text{Var}(x | y) = \text{Var}(E(x | \theta, y)) + E(\text{Var}(x | \theta, y)) \quad \text{law of total variance}$$

- These are the **posterior predictive mean** and **posterior predictive variance** of x , respectively.

Example: beta prior, binomial data

- Data, $k \sim \text{binomial}(n, q)$
- Prior, $q \sim \text{beta}(\alpha, \beta)$.
- New data, $x \sim \text{binomial}(m, q)$, m is known.

(1) Find the posterior predictive mean and variance of x

Using simulation (Monte Carlo)

- Suppose we know the posterior distribution $p(\theta | y)$, or we have a sample from it.
- Then it is easy to use simulation to generate a sample from the posterior predictive distribution of a new data-point x .
- Because we know the distribution of x for any given value of θ : it's the same as the distribution of the original data y .

Simulating the posterior predictive distribution

- Suppose that we have a sample from the posterior distribution

$$\theta_1, \theta_2, \dots, \theta_M$$

- We can simulate the posterior predictive distribution $p(x | y)$.
- We just generate

$$x_j \text{ from } p(x | \theta_j, y) = p(x | \theta_j), \quad j = 1, 2, \dots, M$$

- Then

$$x_1, x_2, \dots, x_M$$

is a sample from the posterior predictive distribution $p(x | y)$.

- (Since

$$(x_1, \theta_1), (x_2, \theta_2), \dots, (x_M, \theta_M)$$

is a sample from $p(x, \theta | y) = p(\theta | y) p(x | \theta, y)$).

Simulating the posterior predictive distribution

- When do we have a sample from $p(\theta | y)$?
- Almost always, because we use MCMC to make inferences about θ .
- Or in simpler conjugate cases, we can directly generate an independent sample from $p(\theta | y)$.
- The latter is an example of simple Monte Carlo.

Using the the posterior predictive sample

- Suppose we have generated a sample from the posterior predictive distribution x_1, x_2, \dots, x_M .
- We can summarize the sample for whatever interests us:
 - Posterior predictive mean, median, variance - just summarize sample x_1, x_2, \dots, x_M
 - Prediction intervals, e.g. with 95% probability, x will be in some interval- just take the 0.025 and 0.975 sample quantiles of the sample x_1, x_2, \dots, x_M .
 - Posterior predictive probability that $x = 0$ - just count what proportion of sample are 0.
 - Posterior predictive probability that $x > c$, for some c - count what proportion of sample are $> c$.