Machine Learning with Python MTH786U/P 2023/24

Week 11: Semi-supervised classification with graphs

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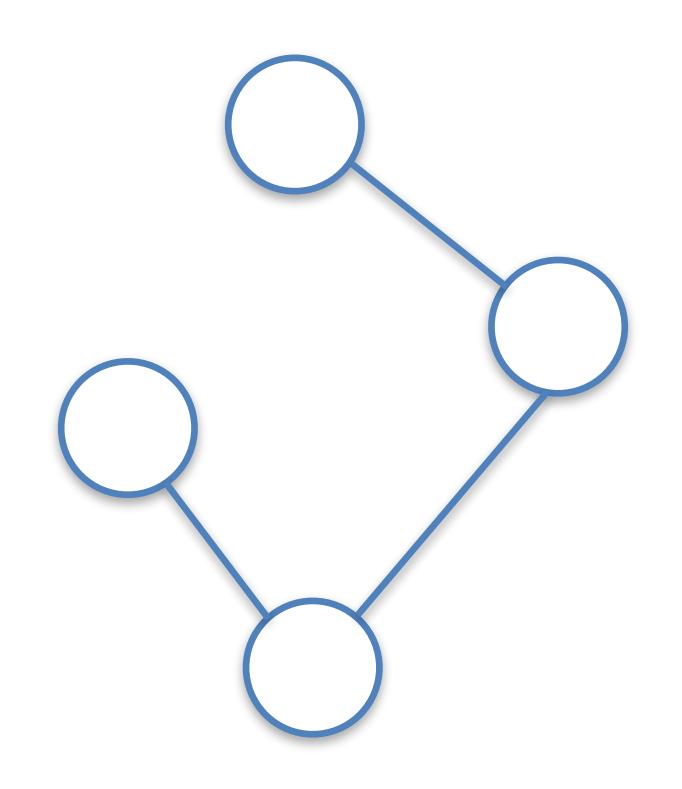
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$$E = \{x, y \mid (x, y) \in V^2 \land x \neq y\}$$
 are the *edges*



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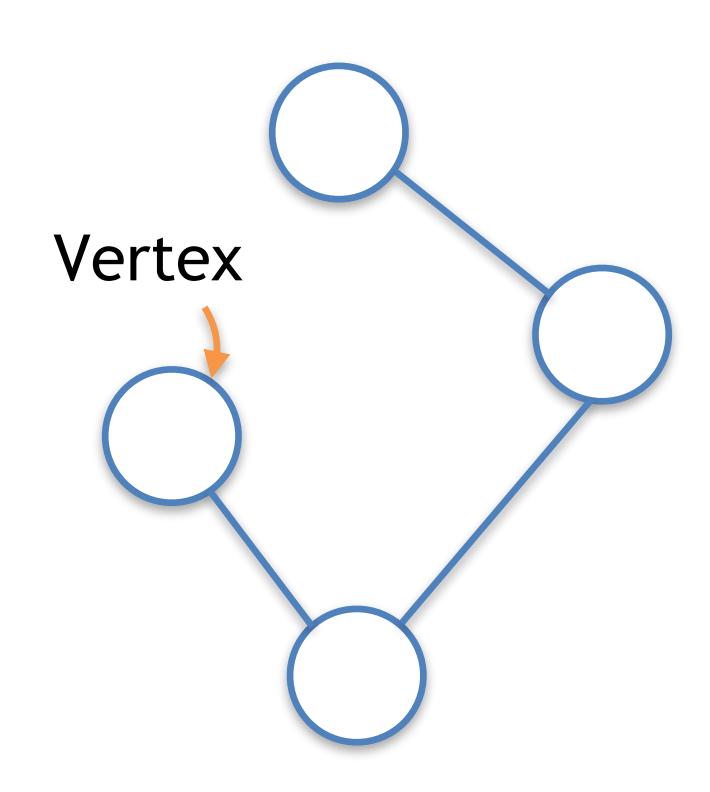
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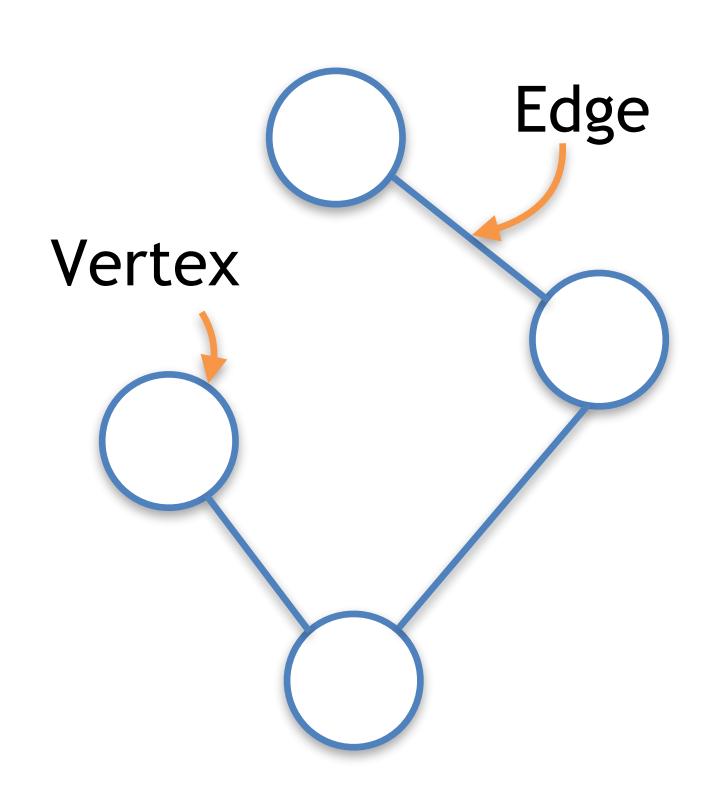
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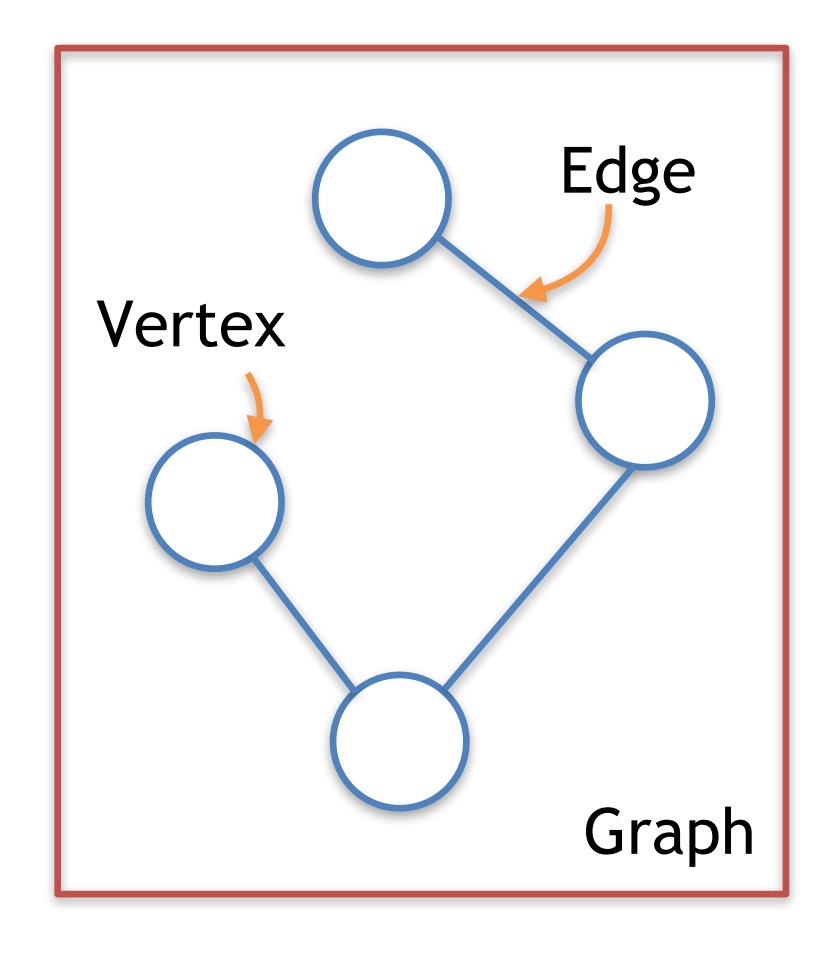
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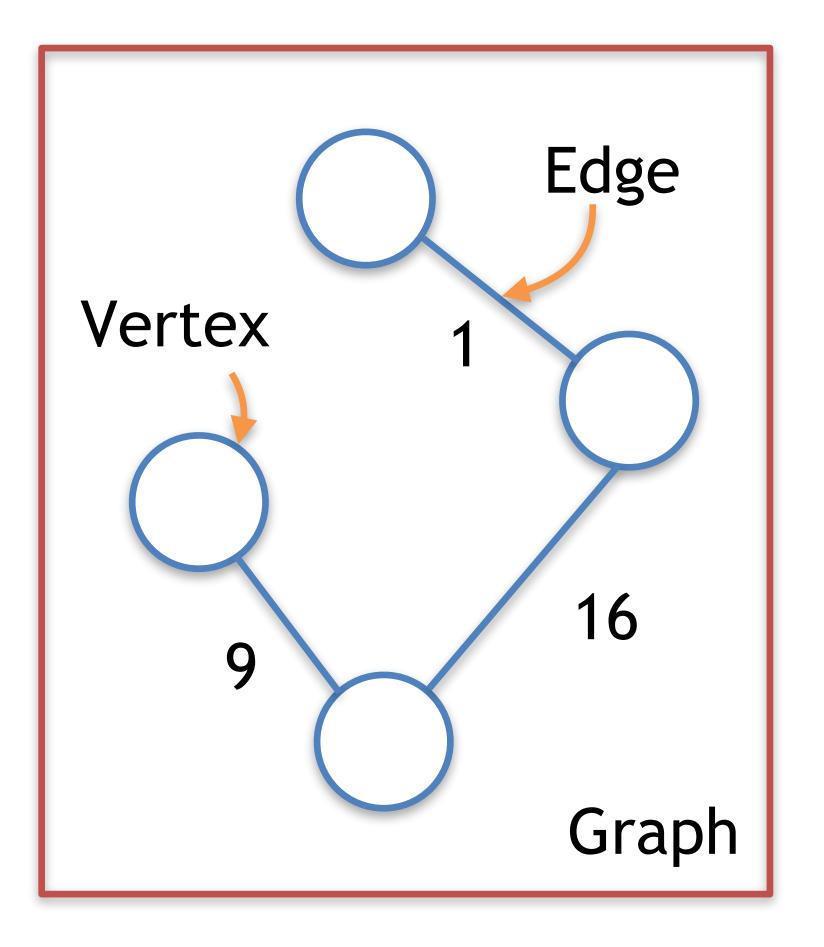


A weighted graph is a pair G = (V, E)

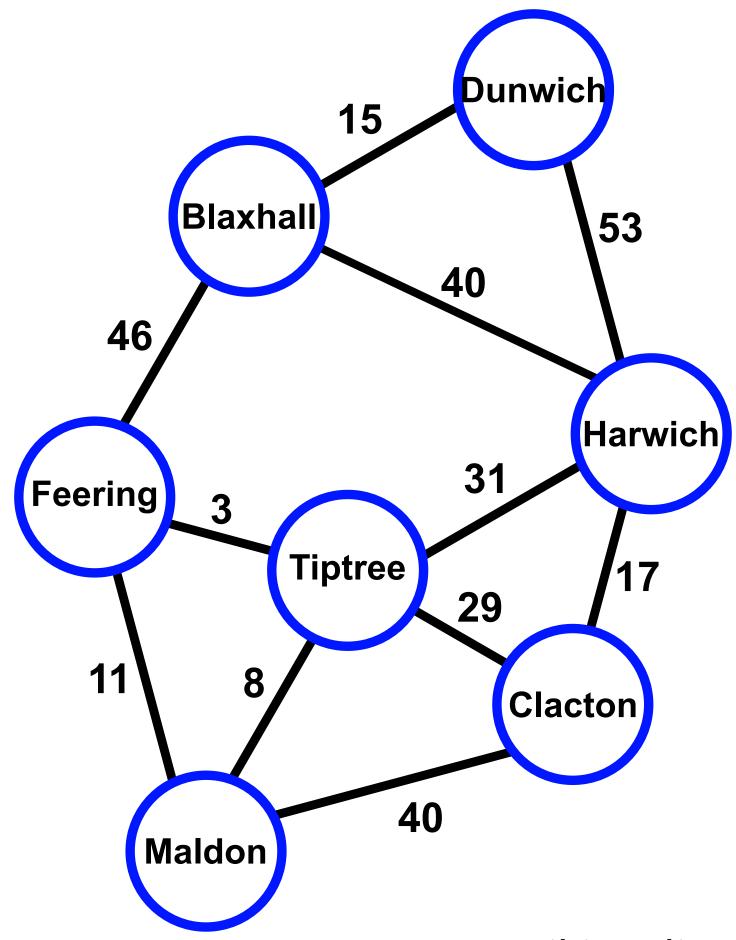
V are the vertices

$$E = \{x, y \mid (x, y) \in V^2 \land x \neq y\} \text{ are the edges}$$

A number called weight is assigned to each edge

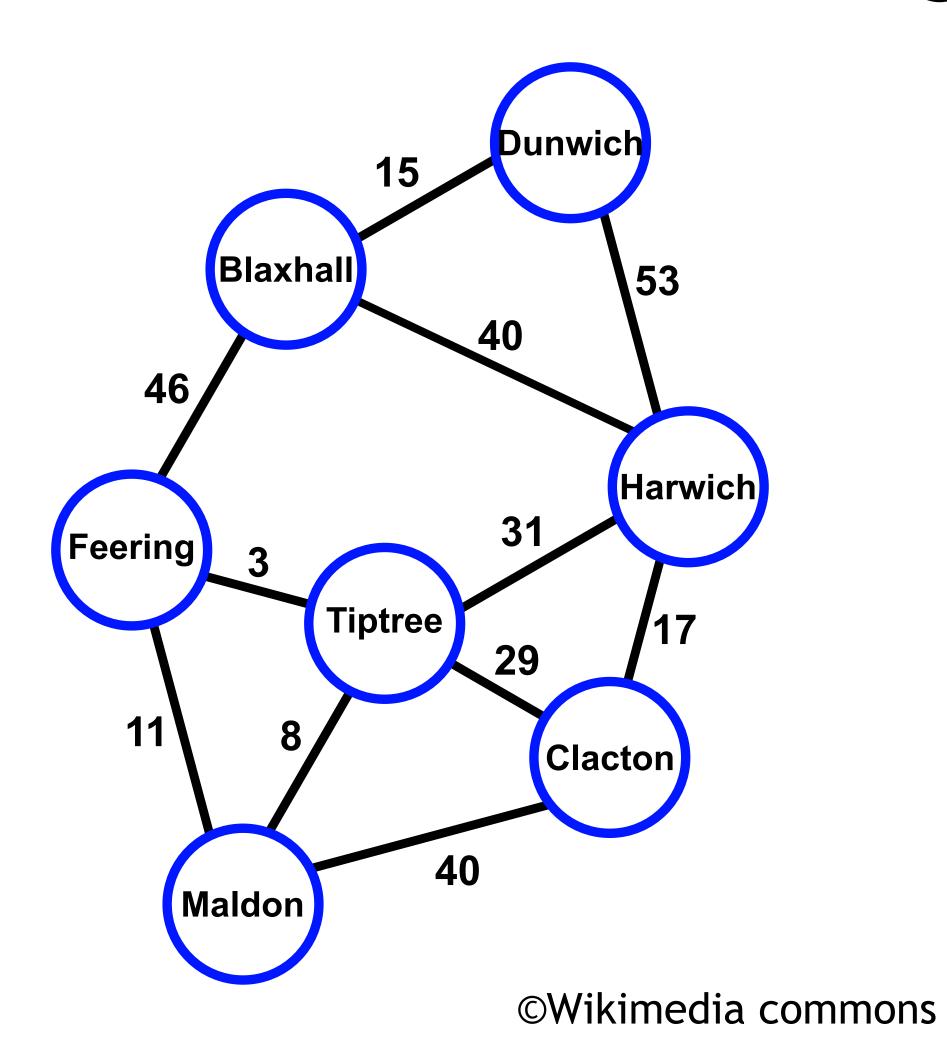


Example



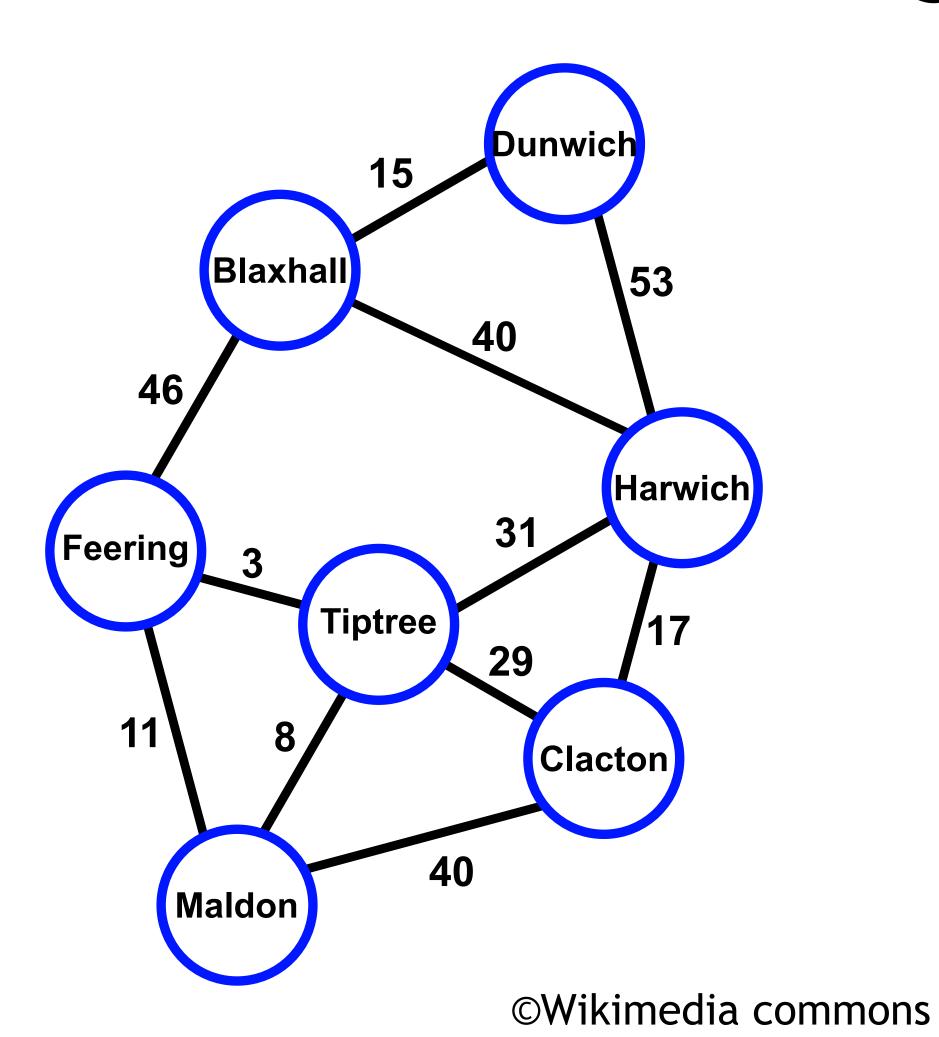
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Example



Vertices = towns

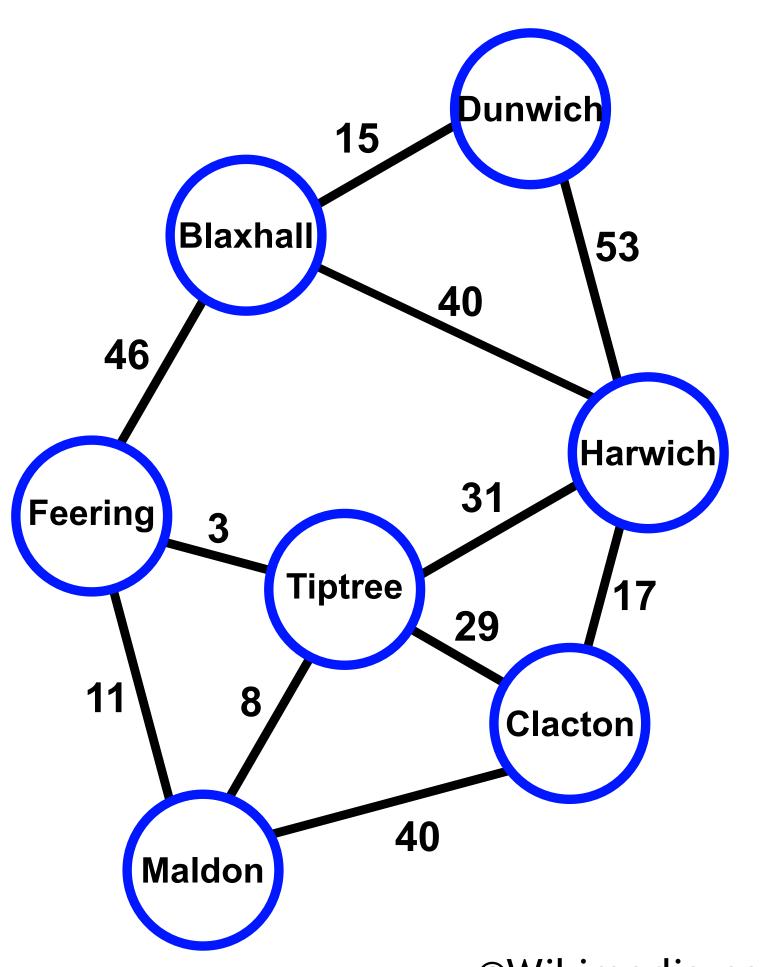
Example



Vertices = towns

Edges = town connections

Example



Vertices = towns

Edges = town connections

Weights = distances between towns

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Incidence matrix

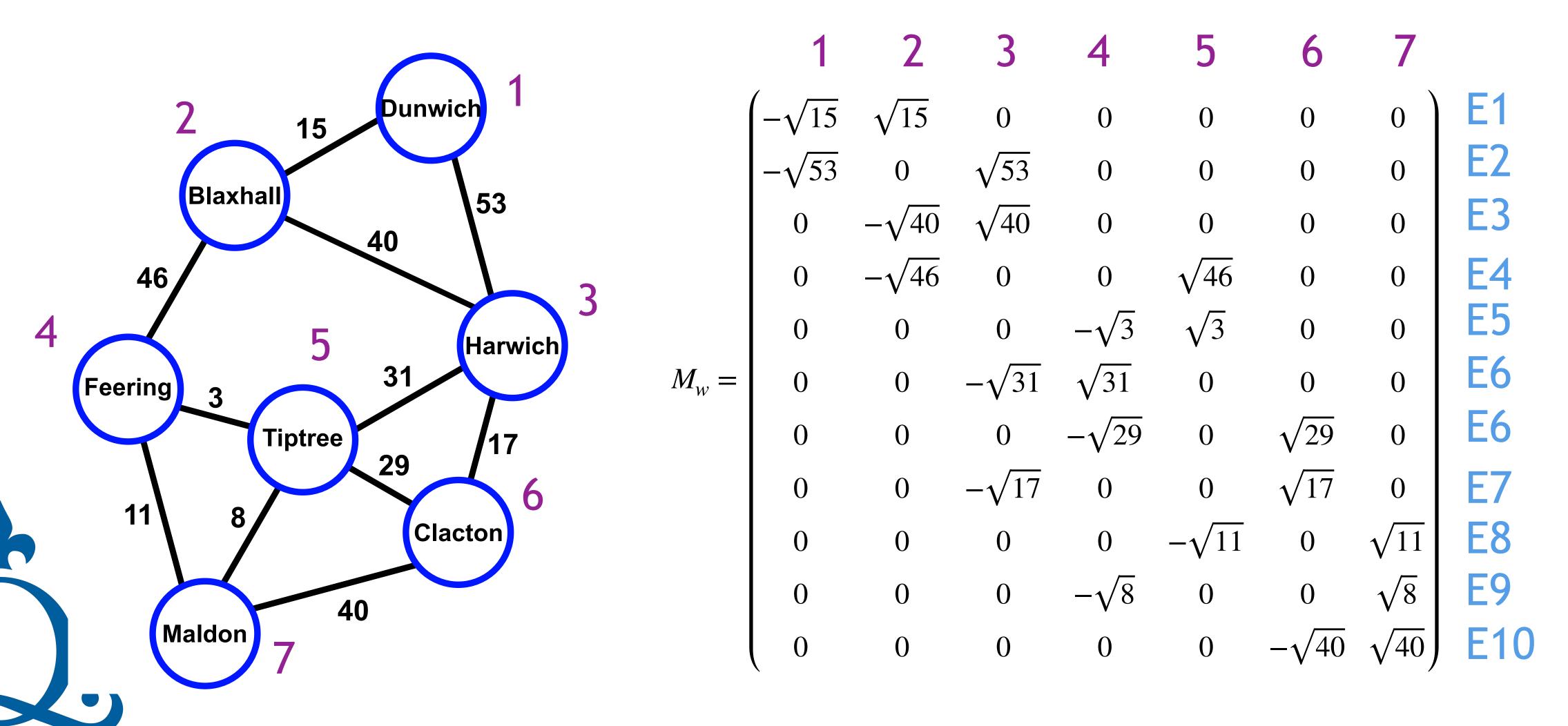
For a (weighted) graph (with weights w) we define a so-called *incidence matrix* $M_w \in \mathbb{R}^{|E| \times |V|}$, where |E| denotes the number of edges and |V| the number of vertices, as

$$(M_w)_{ev} := egin{cases} \sqrt{w_{ev}} & \text{if } v = i \\ -\sqrt{w_{ev}} & \text{if } v = j \\ 0 & \text{otherwise} \end{cases},$$

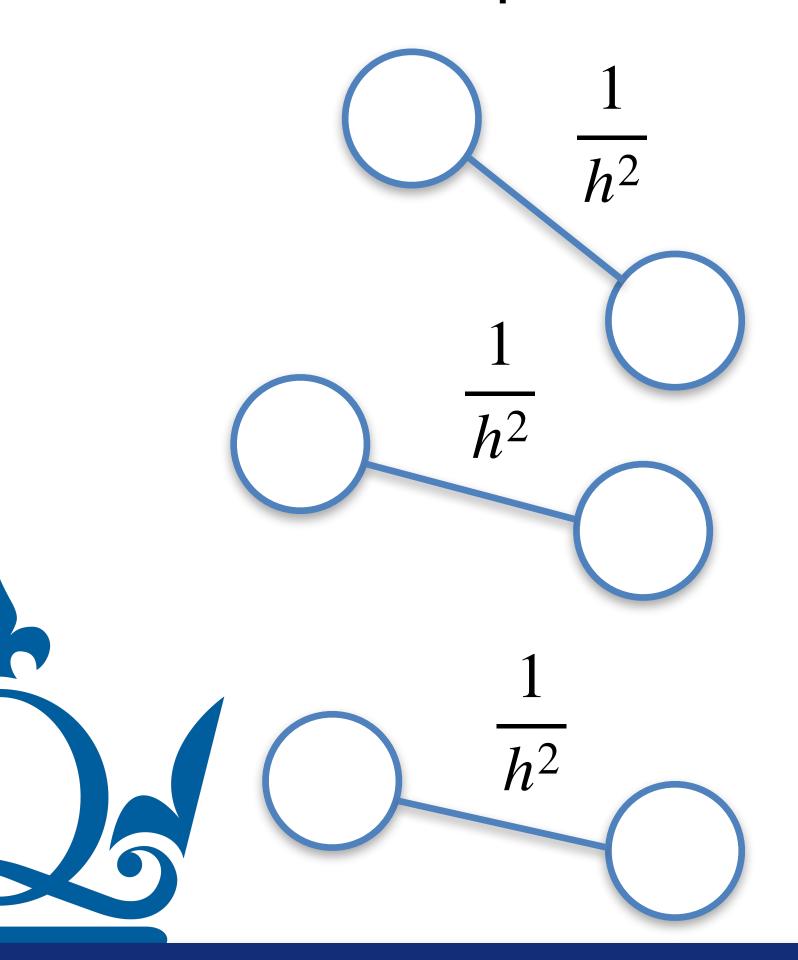


where every edge e = (i, j) connects vertices i and j, with i > j.

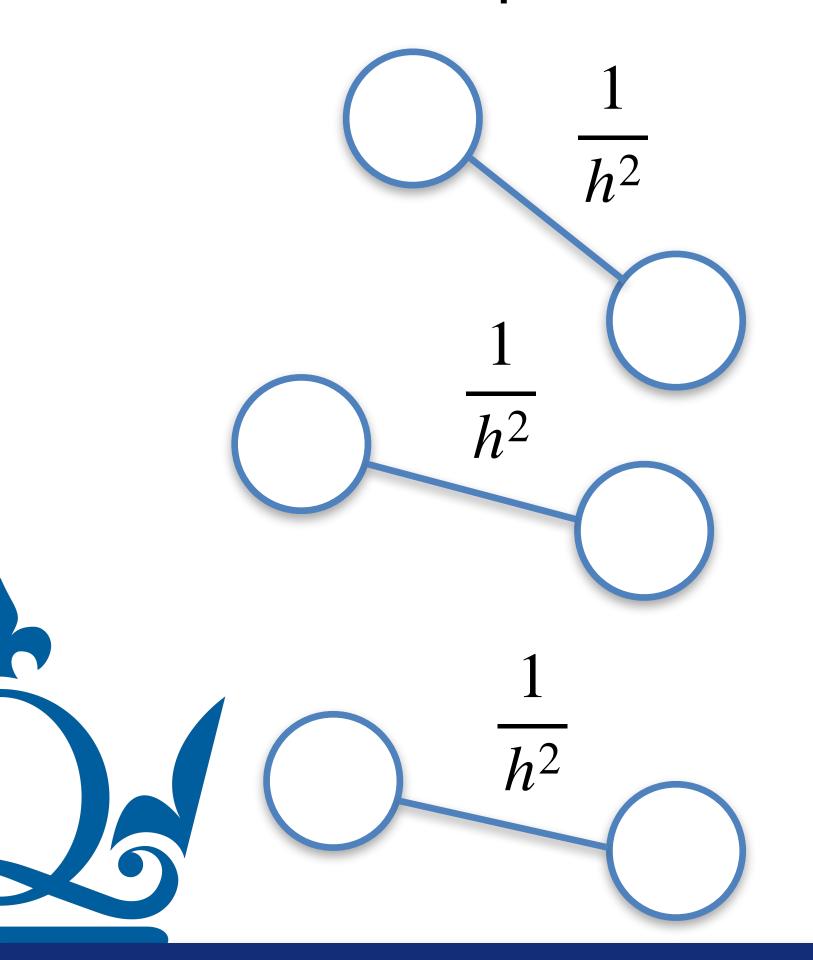
Incidence matrix



Another example: finite differences

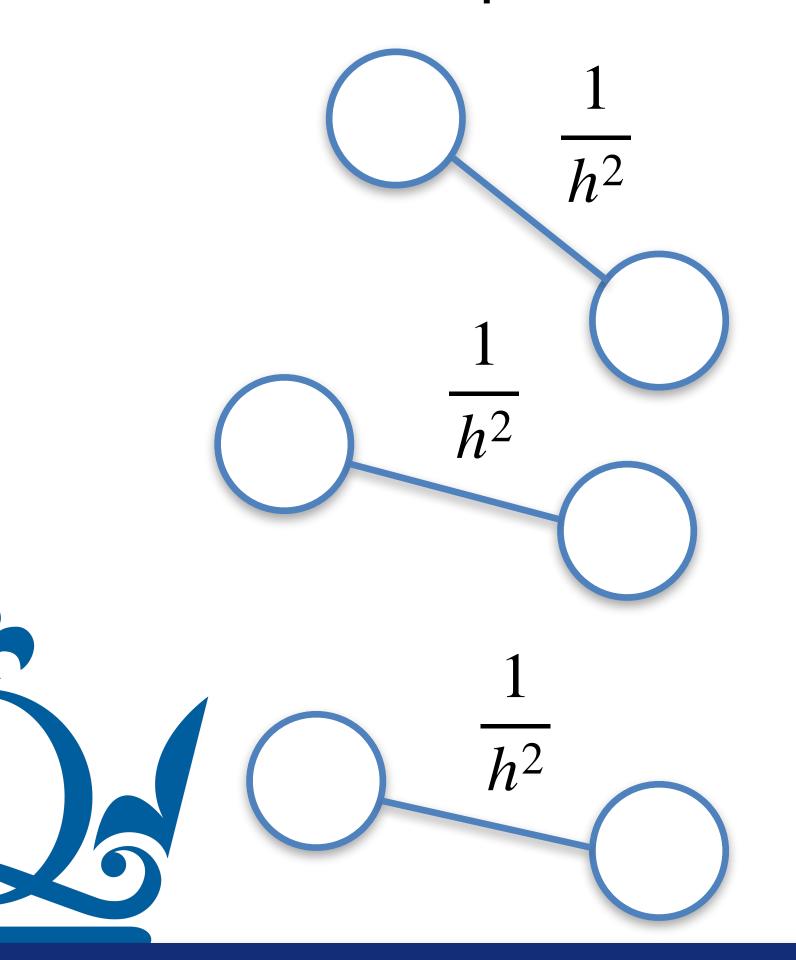


Another example: finite differences



Every vertex is connected only to one other vertex

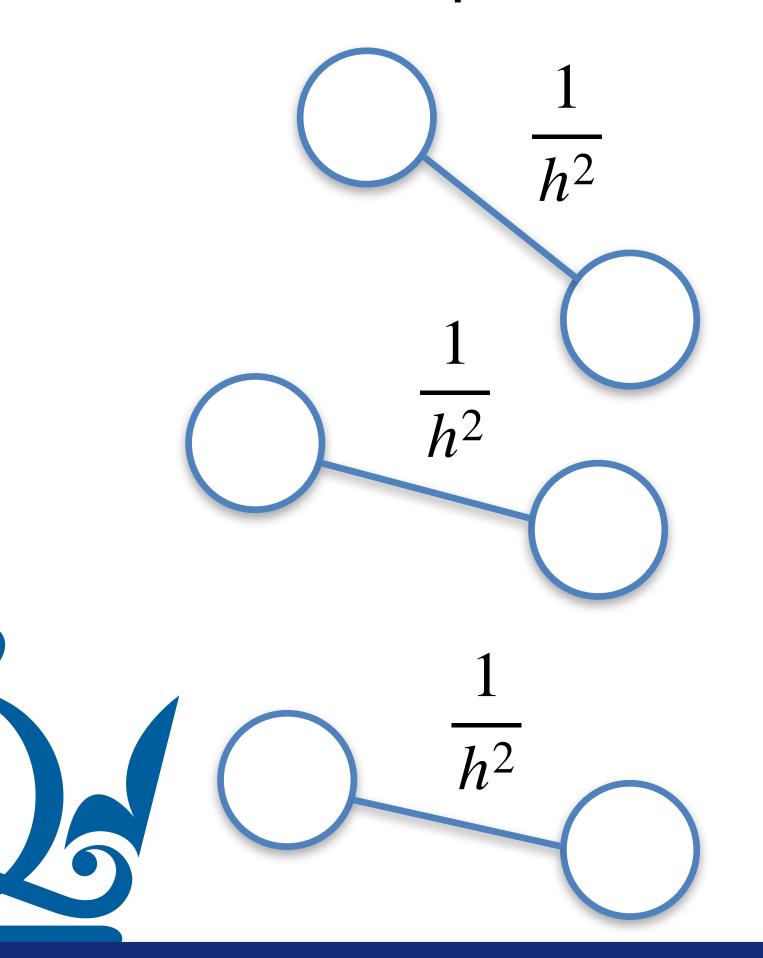
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The weight is a constant factor $(1/h)^2$

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Suppose every vertex represents $f(x_i)$:

$$f'(x_i) \approx \frac{f(x_{i+1}) - f(x_i)}{h}$$
 can be written as matrix-vector multiplication

$$\begin{pmatrix} f'(x_1) \\ f'(x_2) \\ \vdots \\ f'(x_d) \end{pmatrix} \approx \frac{1}{h} \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 \\ \vdots & & \ddots & & & \vdots \\ 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} f(x_1) \\ f(x_2) \\ \vdots \\ f(x_{d+1}) \end{pmatrix}$$

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This is our incidence matrix

Based on the finite difference approximation

$$M_{\frac{1}{h}} = \frac{1}{h} \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 \\ \vdots & & \ddots & & & \vdots \\ 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix},$$

it is natural to define second-order finite differences (or *Laplacians* in higher dimensions) as

$$L_{\frac{1}{h}} = M_{\frac{1}{h}}^{\mathsf{T}} M_{\frac{1}{h}}$$

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We can define the same for arbitrary graphs!

The graph-Laplacian $L_{\!\scriptscriptstyle W}\in\mathbb{R}^{|V|\times|V|}$ is defined as

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$$L_{w} = M_{w}^{\top} M_{w} = \begin{pmatrix} 68 & -15 & -53 & 0 & 0 & 0 & 0 \\ -15 & 101 & -40 & 0 & -46 & 0 & 0 \\ -53 & -40 & 141 & -31 & 0 & -17 & 0 \\ 0 & 0 & -31 & 71 & -3 & -29 & -8 \\ 0 & -46 & 0 & -3 & 60 & 0 & -11 \\ 0 & 0 & -17 & -29 & 0 & 86 & -40 \\ 0 & 0 & 0 & -8 & -11 & -40 & 59 \end{pmatrix}$$

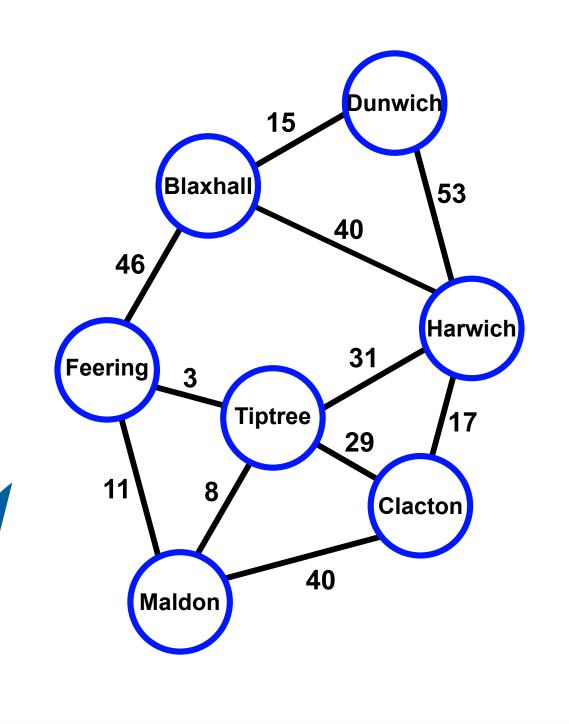
The graph-Laplacian $L_w \in \mathbb{R}^{|V| \times |V|}$ is defined also as

Degree matrix



Adjacency matrix

The graph-Laplacian $L_w \in \mathbb{R}^{|V| \times |V|}$ is defined also as $L_w = D_w - A_w$



$$D = \begin{pmatrix} 68 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 101 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 141 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 71 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 60 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 86 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 59 \end{pmatrix}$$

Degree matrix

$$A = \begin{pmatrix} 0 & 15 & 53 & 0 & 0 & 0 & 0 \\ 15 & 0 & 40 & 0 & 46 & 0 & 0 \\ 53 & 40 & 0 & 31 & 0 & 17 & 0 \\ 0 & 0 & 31 & 0 & 3 & 29 & 8 \\ 0 & 46 & 0 & 3 & 0 & 0 & 11 \\ 0 & 0 & 17 & 29 & 0 & 0 & 40 \\ 0 & 0 & 0 & 8 & 11 & 40 & 0 \end{pmatrix}$$

Adjacency matrix

Semi-supervised learning

We can use incidence matrices and graph-Laplacians to model and exploit similarities in a dataset

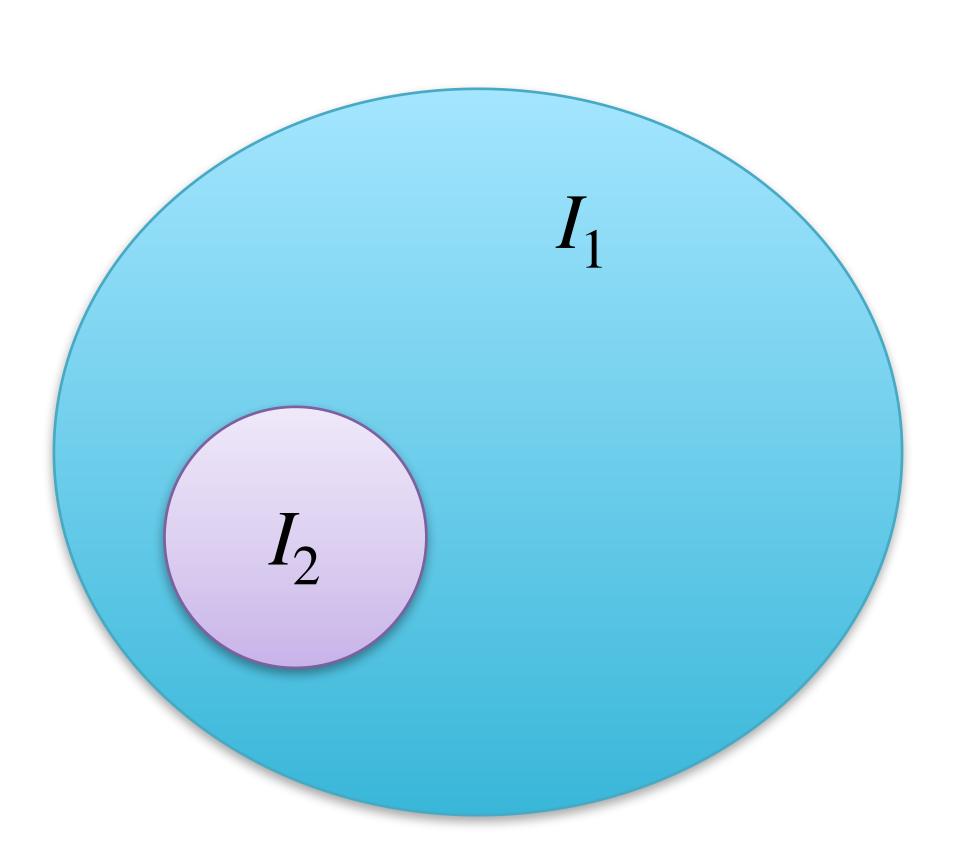


Suppose we are given data points $\{x_i\}_{i\in I_1}$ and pairs $\{(x_j,y_j)\}_{j\in I_2}$ with $I_2\subset I_1$;

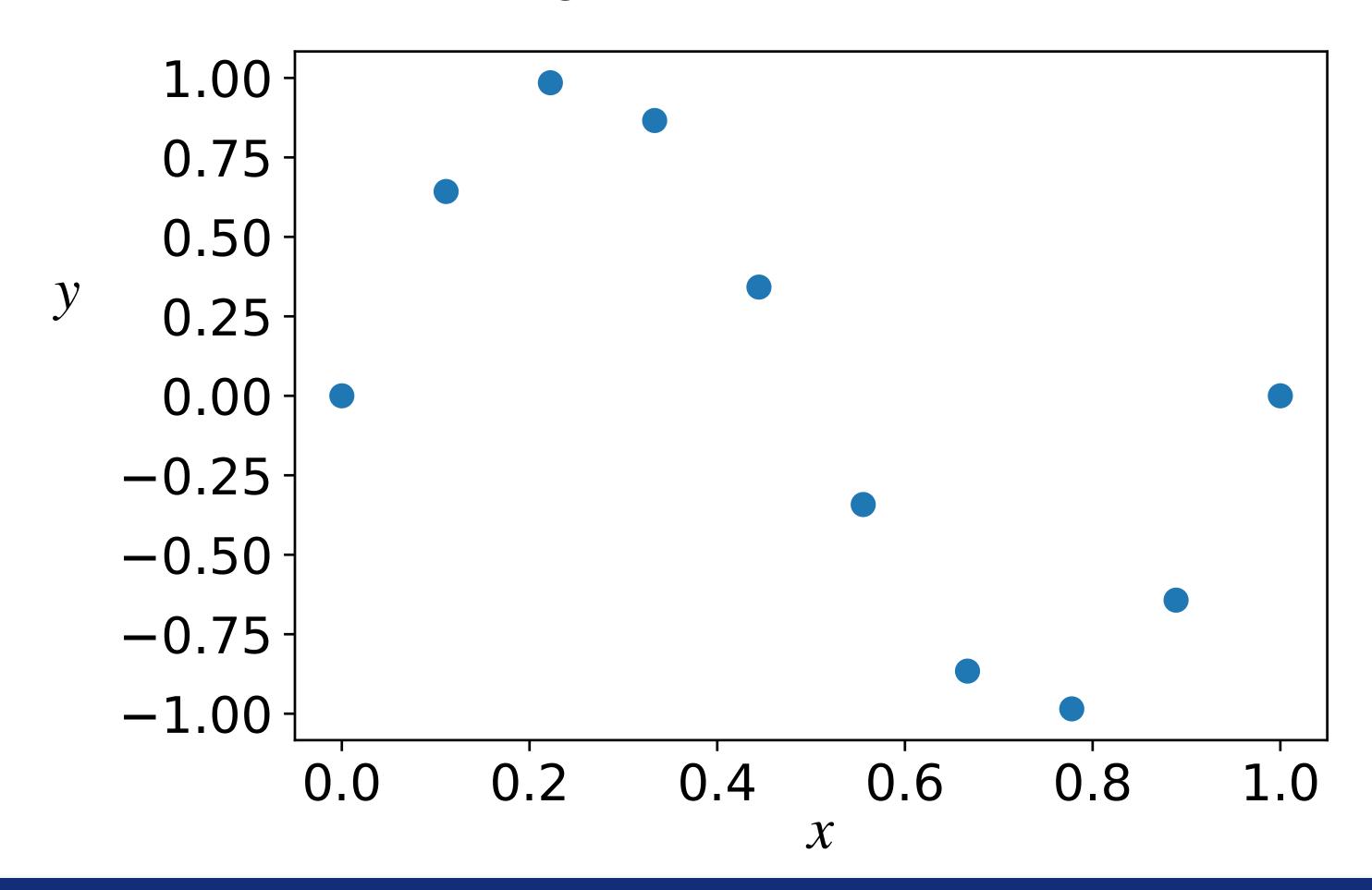
How do we find $\{(x_i, y_i)\}_{i \in I_1}$?



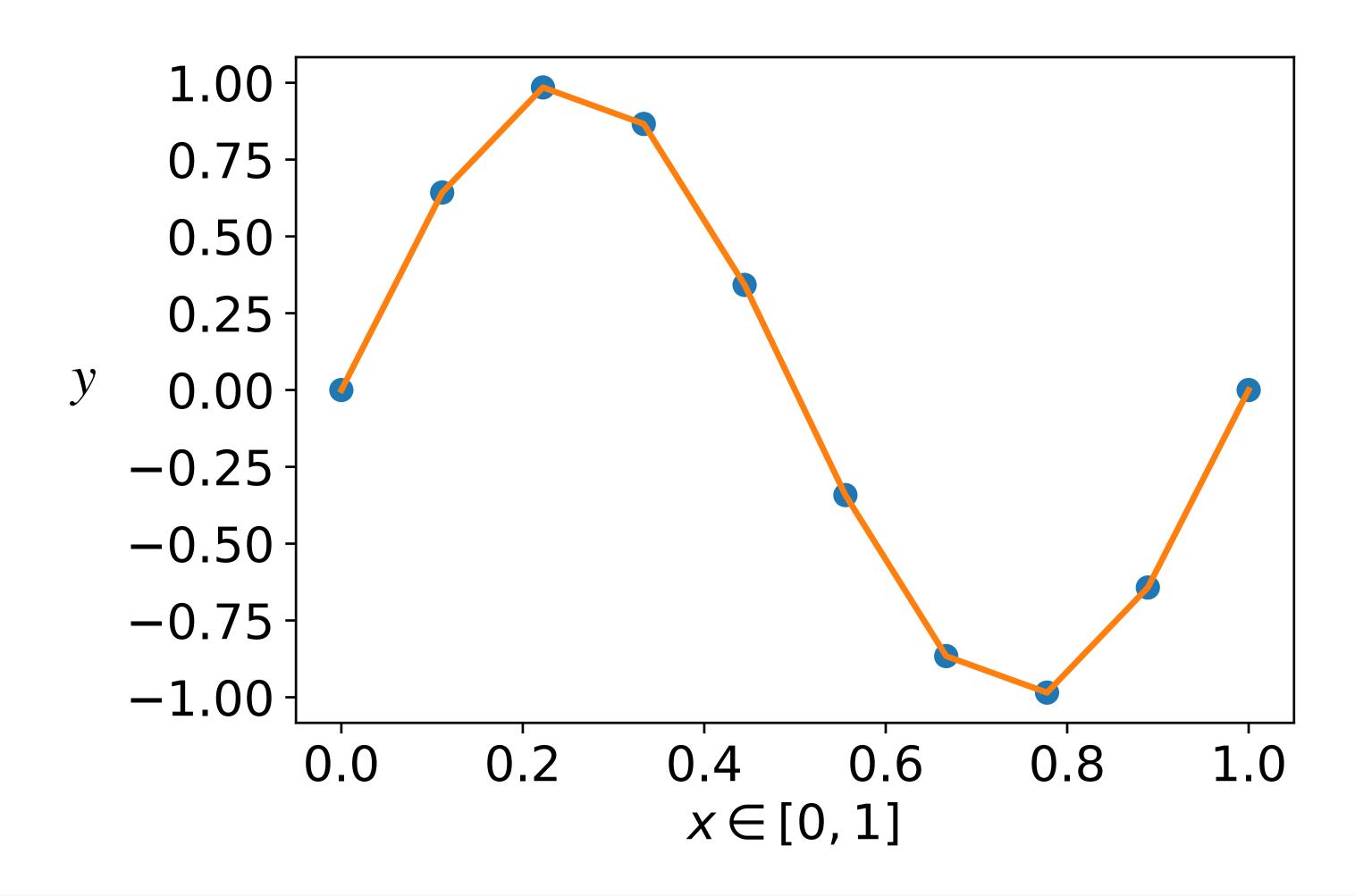
For each x_i in I_2 we know the correspondent y_i



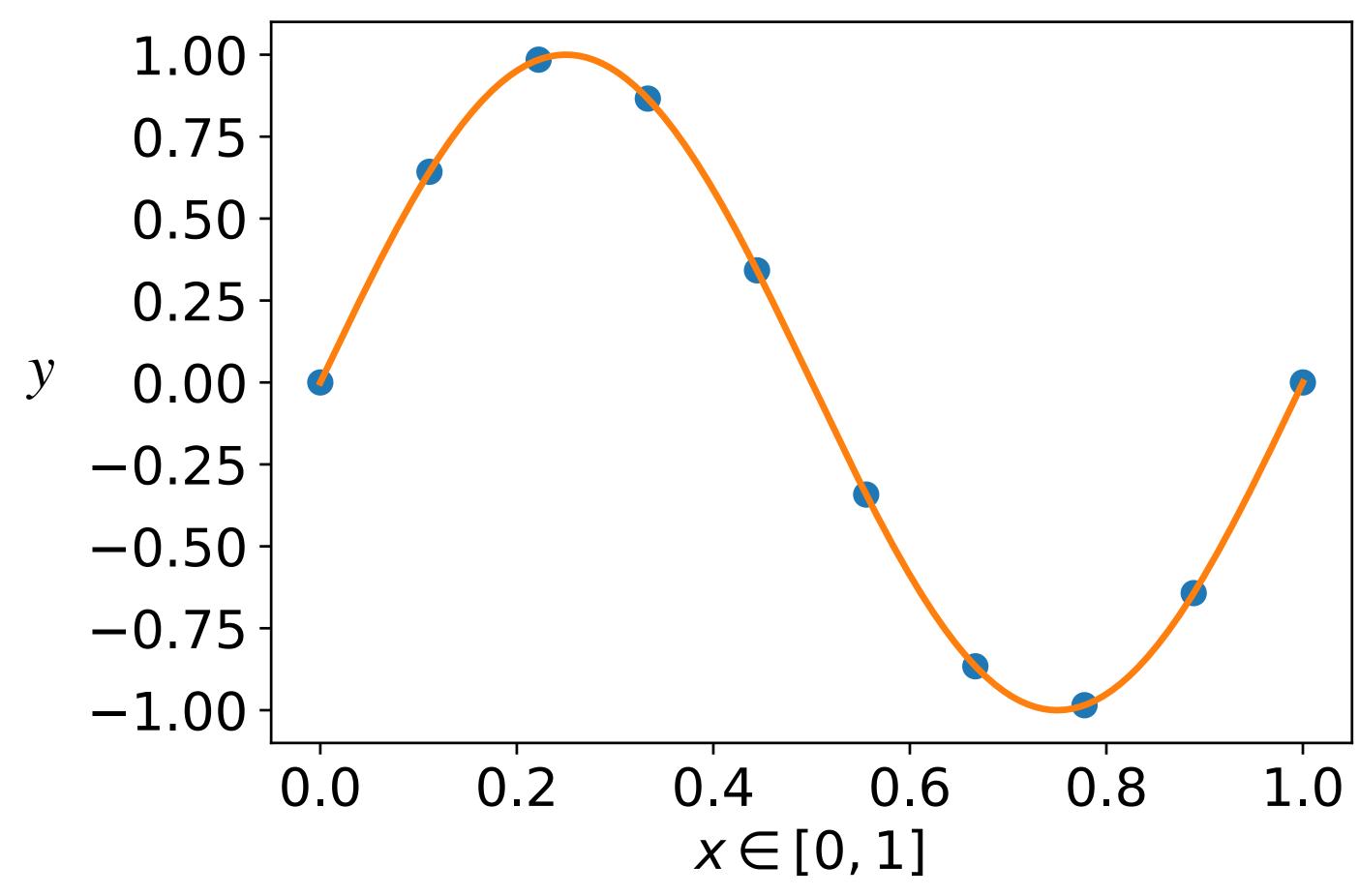
In general we don't know the underling function, how can we connect the dots?



Linear interpolation



Smoother interpolation



One way of formulating this problem mathematically uses the ideas of optimization:

$$\min_{\{y_i\}_{i\in I_1}} E(\mathbf{y})$$

$$\min_{\{y_i\}} E(\mathbf{y}) \qquad \text{subject to} \qquad (\mathbf{P}_{I_2}\mathbf{y})_j = y_j \qquad \forall j \in I_2$$



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How to choose E to interpolate?

We cannot use the MSE! Since, we miss the ground truth for the new y



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$$E(\mathbf{y}) = \left\| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \right\|^2$$

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Proposal:

$$(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{L}} \mathbf{y} \|^2 \qquad \text{wi}$$

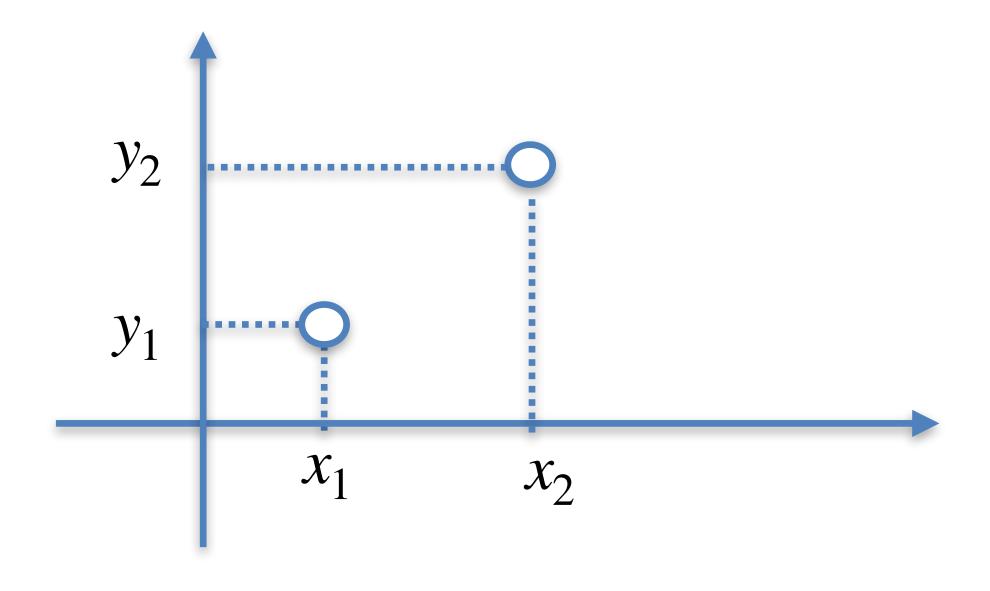
$$E(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \|^{2} \qquad \text{with} \qquad \mathbf{M}_{\frac{1}{h}} = \frac{1}{h} \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 \\ \vdots & & \ddots & & & \vdots \\ 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix},$$



A simple example might help us understand why this is a good idea

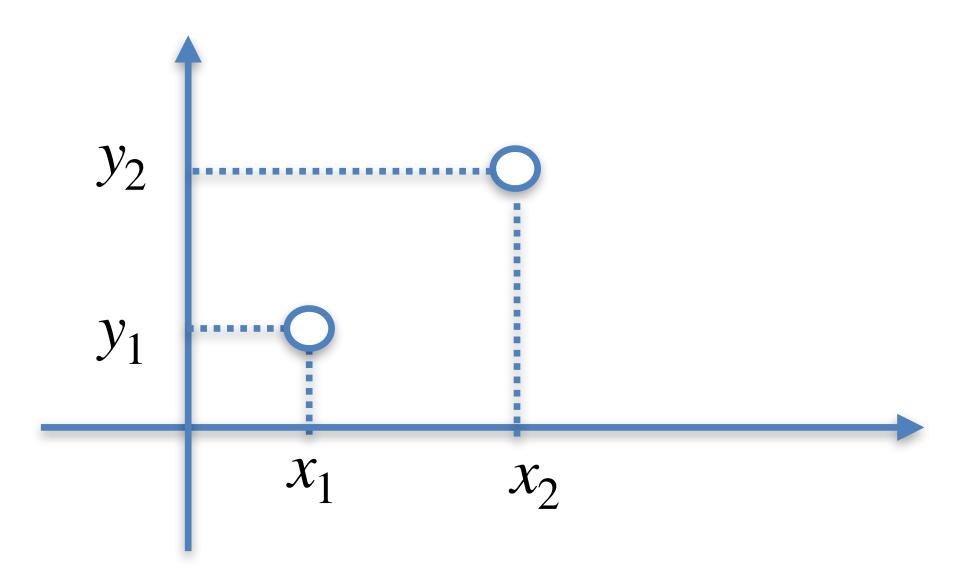


Imagine that we are given these two points





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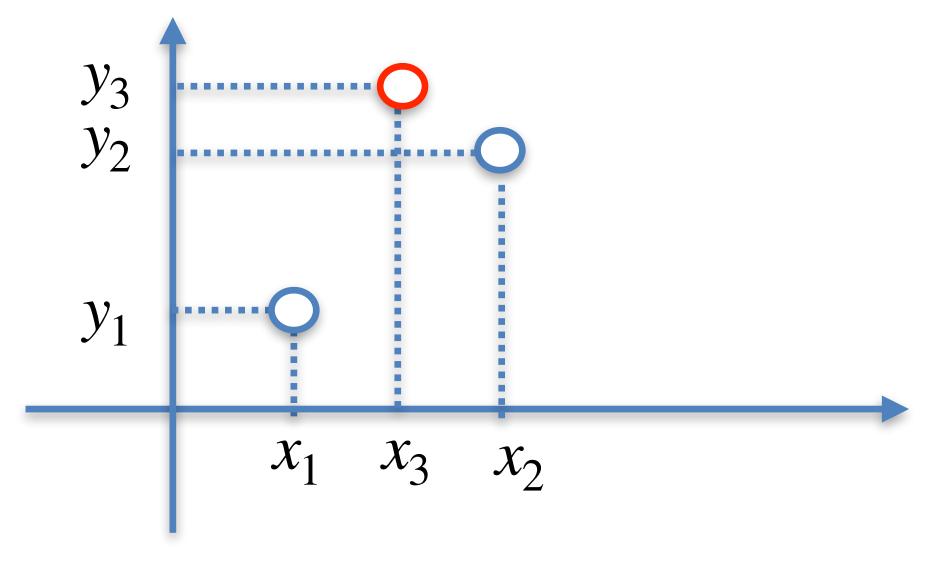


We would add another point, between x_1 and x_3 , thus interpolating

The goal is to find y_3 (in interpolation x_3 is in the middle between the other two points)



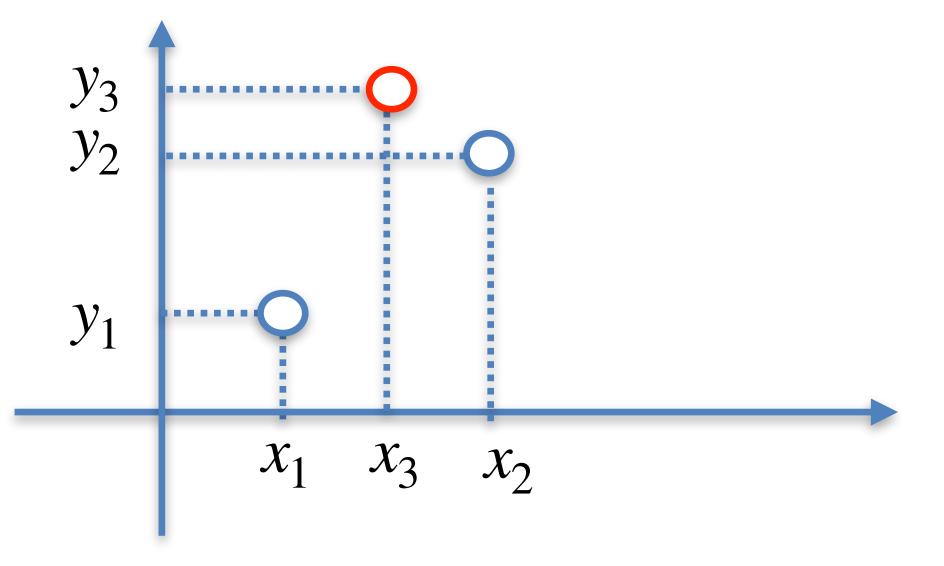
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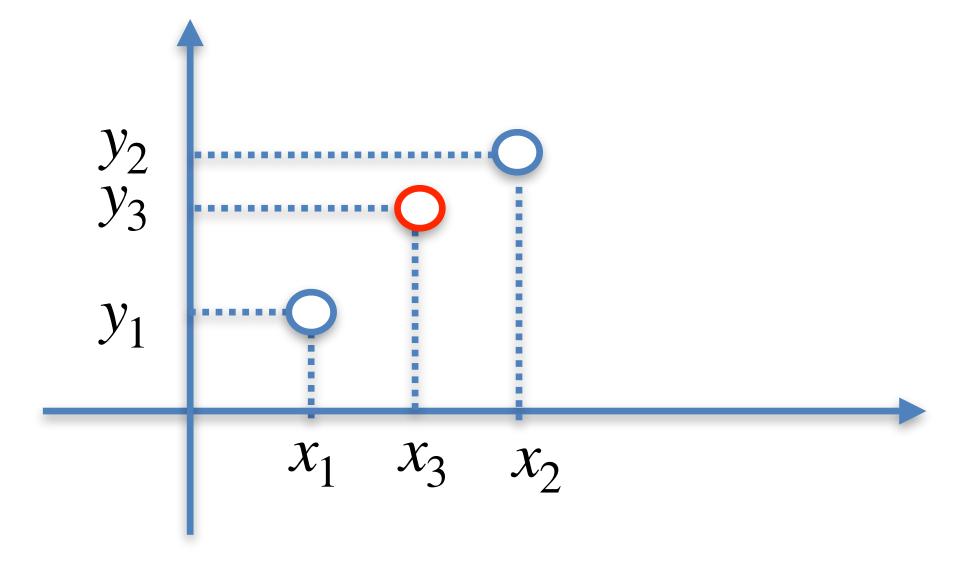




Is it here?

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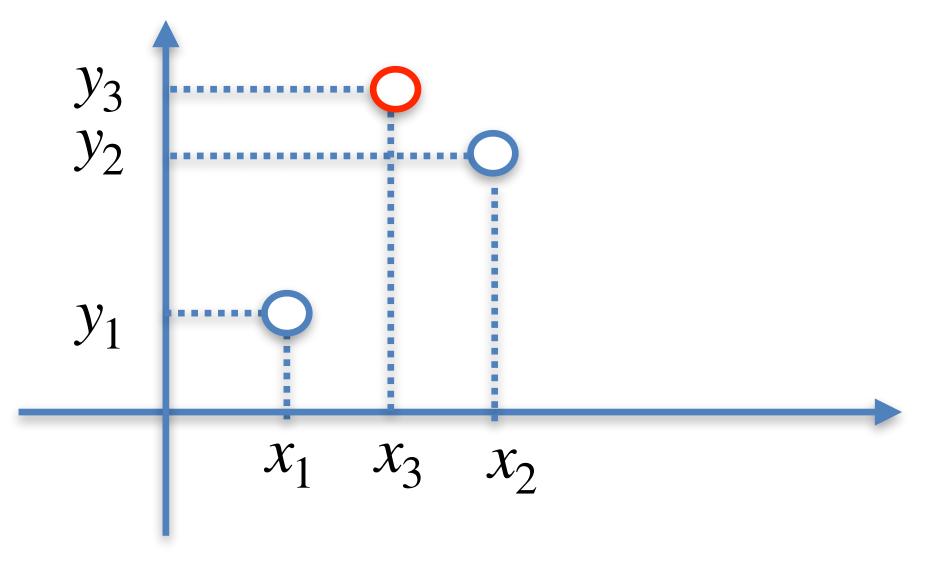


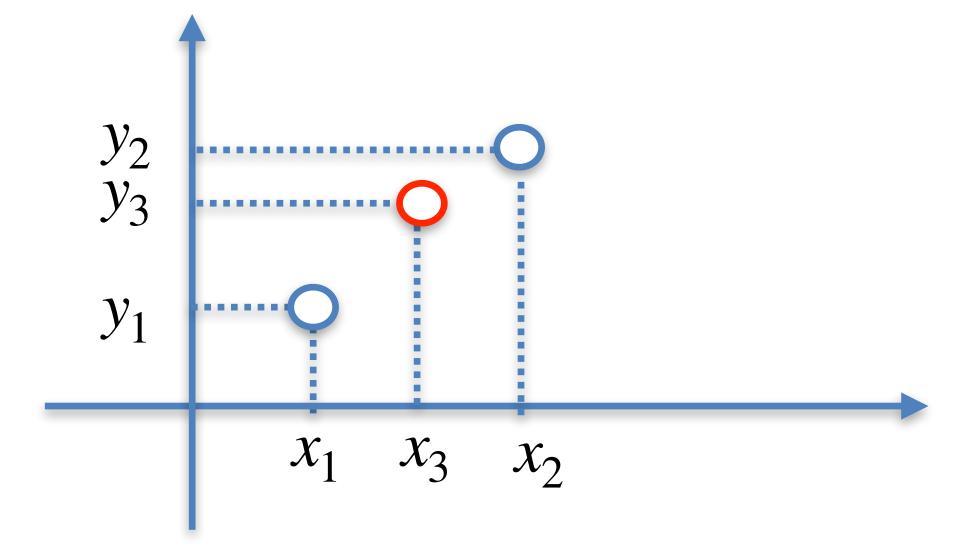


Is it here?

Or here?

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Is it here?

Or here?

Hence,
$$y_3 = ?$$

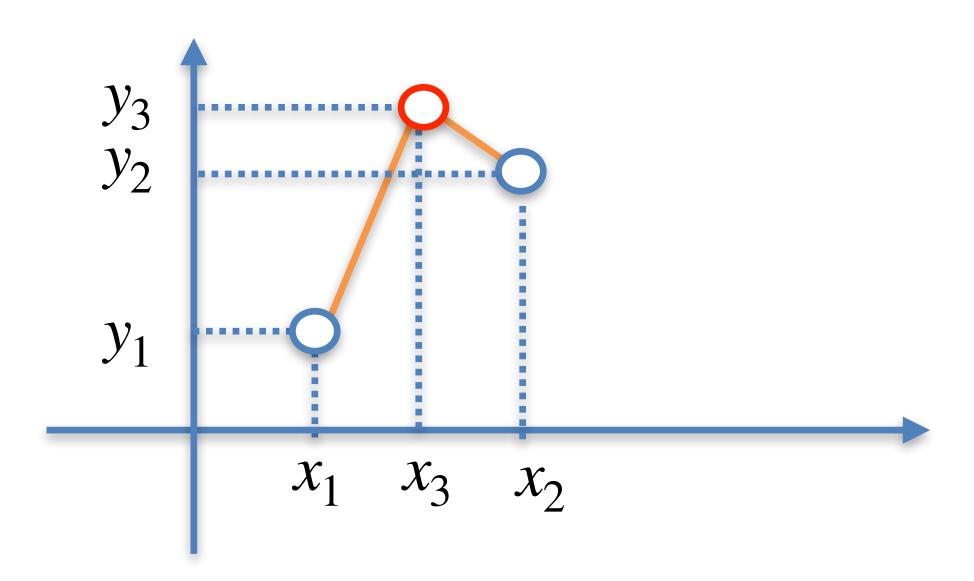
We can now see how using the incidence matrix and minimising E might help



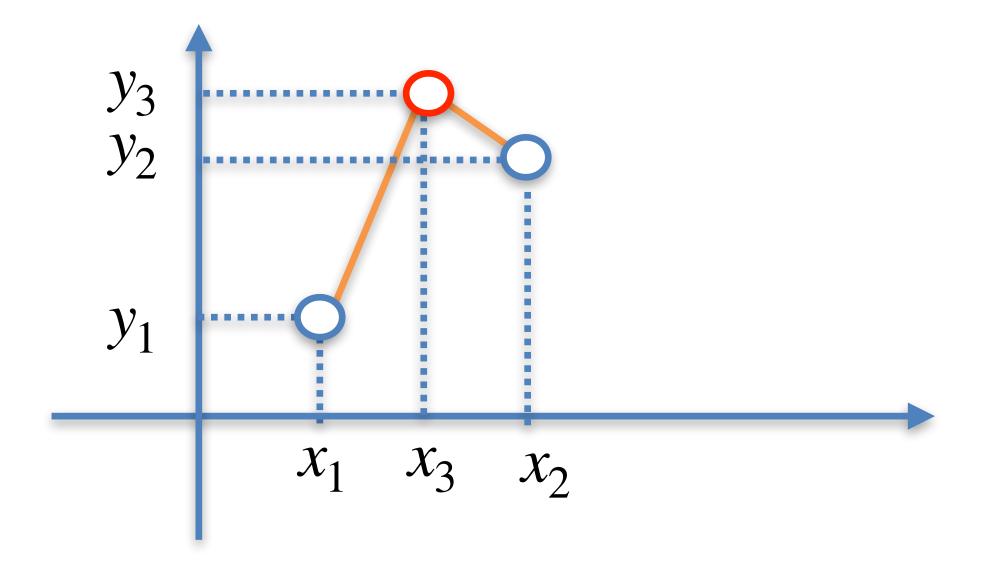
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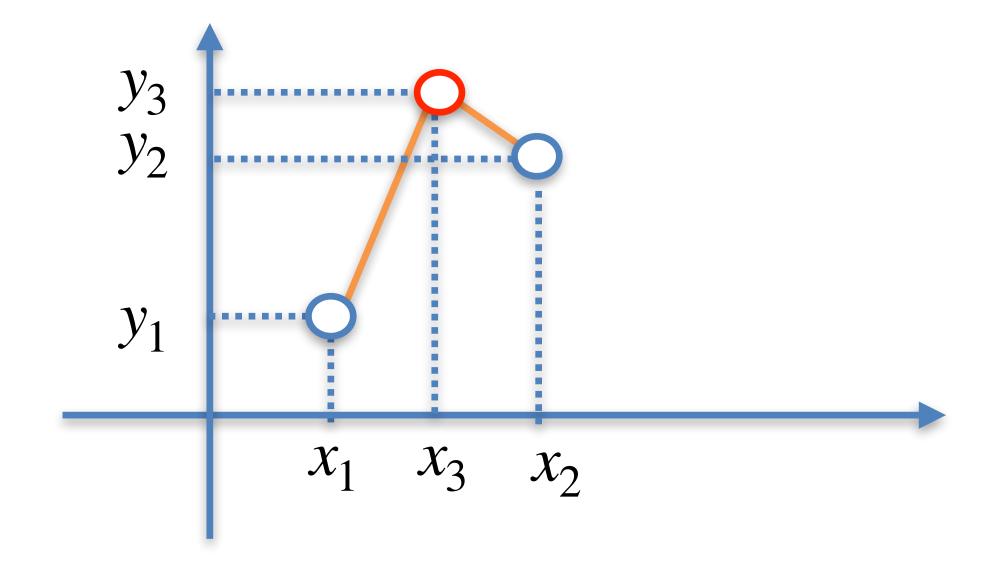


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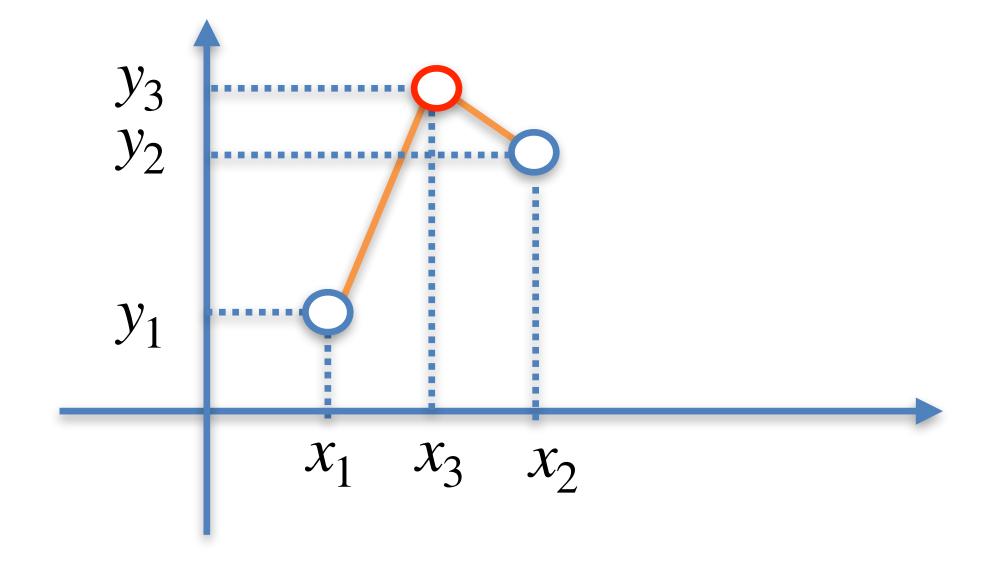
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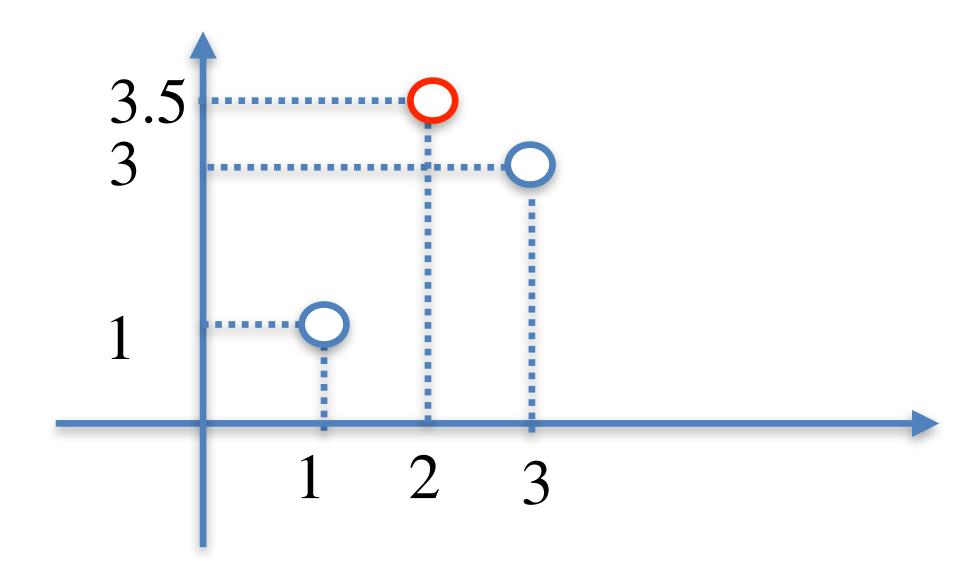
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Hence, the proposed energy function becomes

$$E(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \|^2 = \frac{1}{h^2} [(y_3 - y_1)^2 + (y_2 - y_3)^2]$$

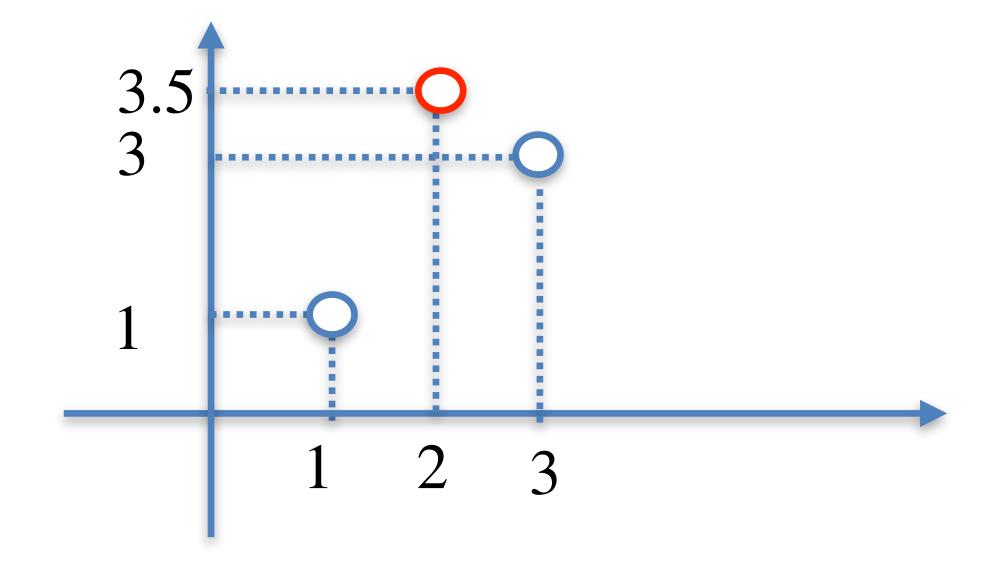
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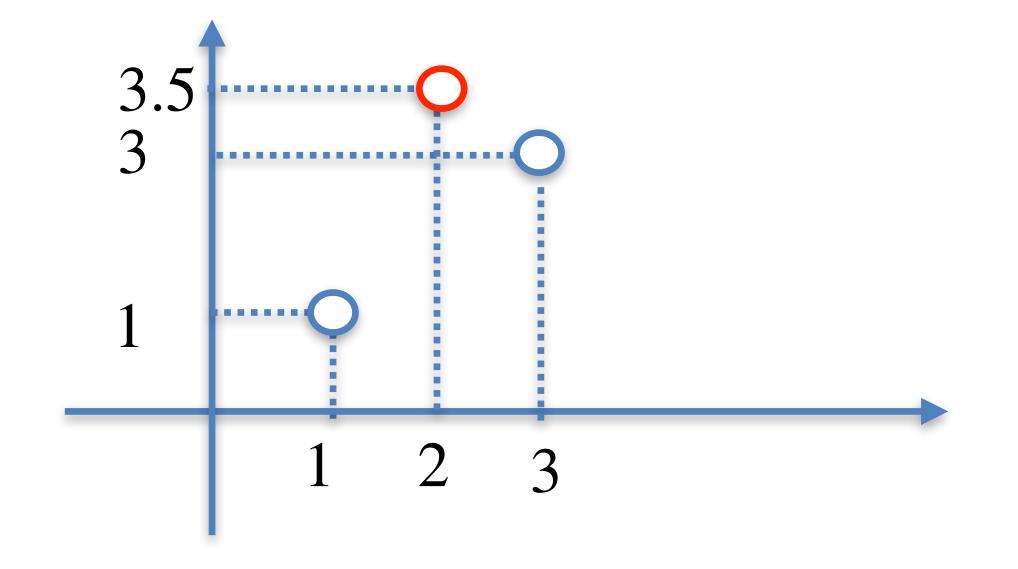




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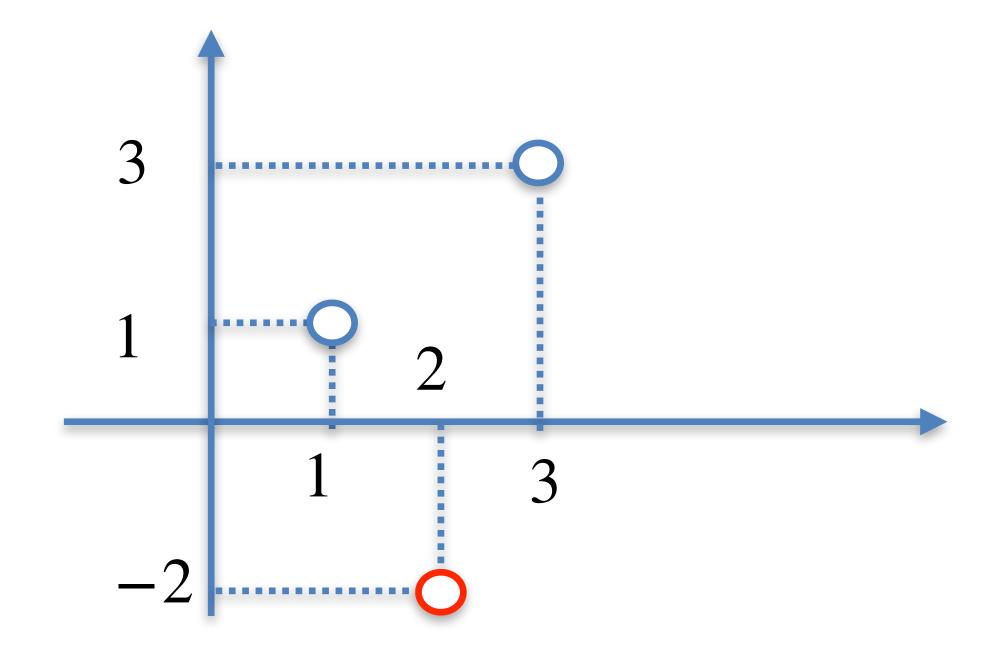
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$$E(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \|^2 \sim \frac{25}{4} + \frac{1}{4} = \frac{13}{2}$$





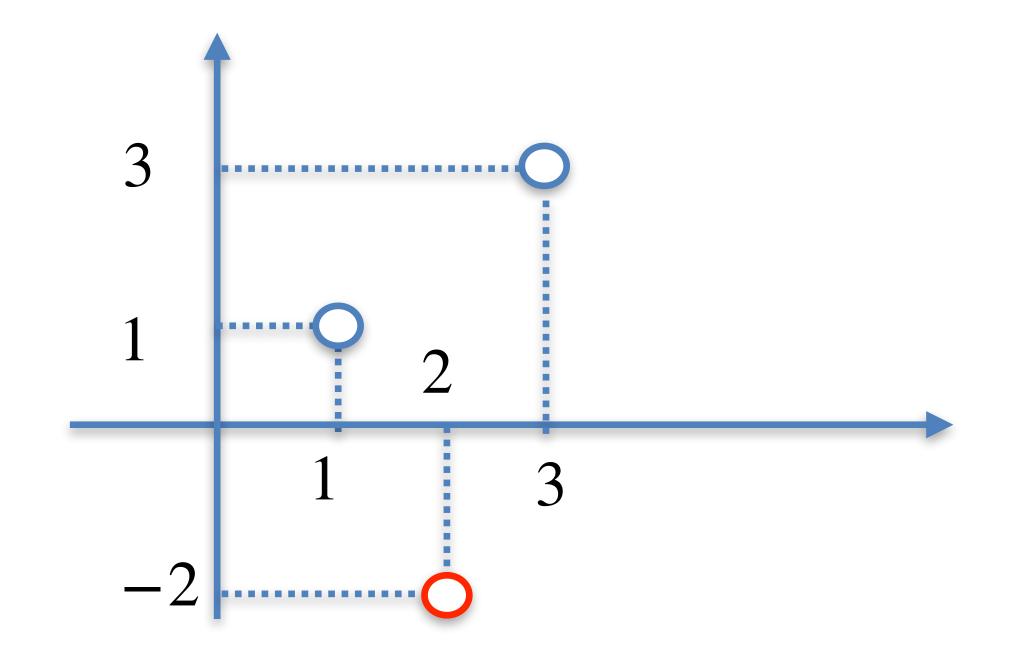
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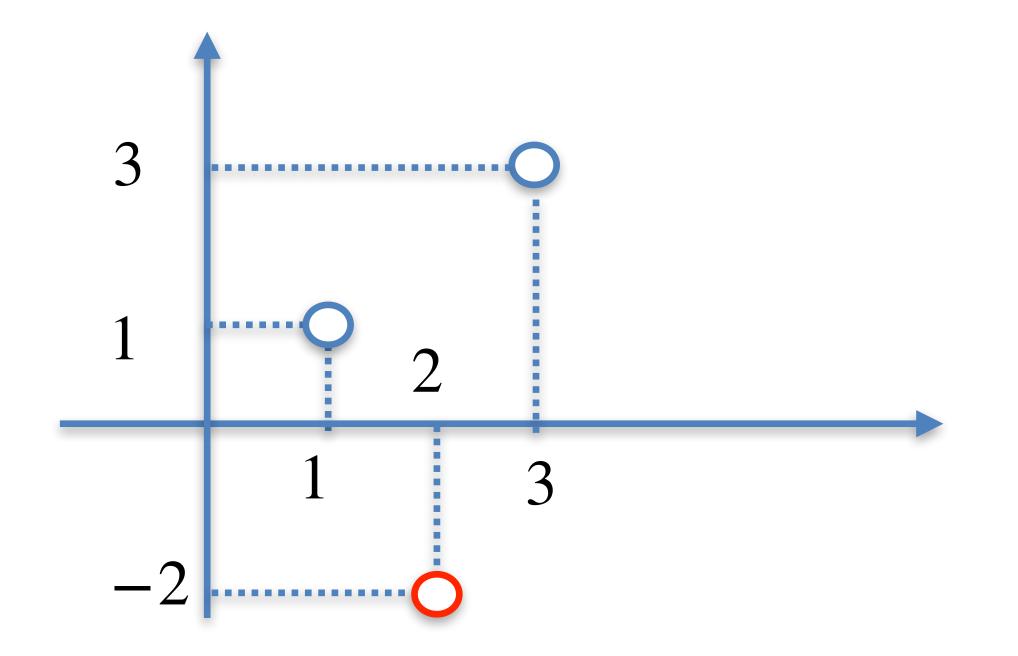




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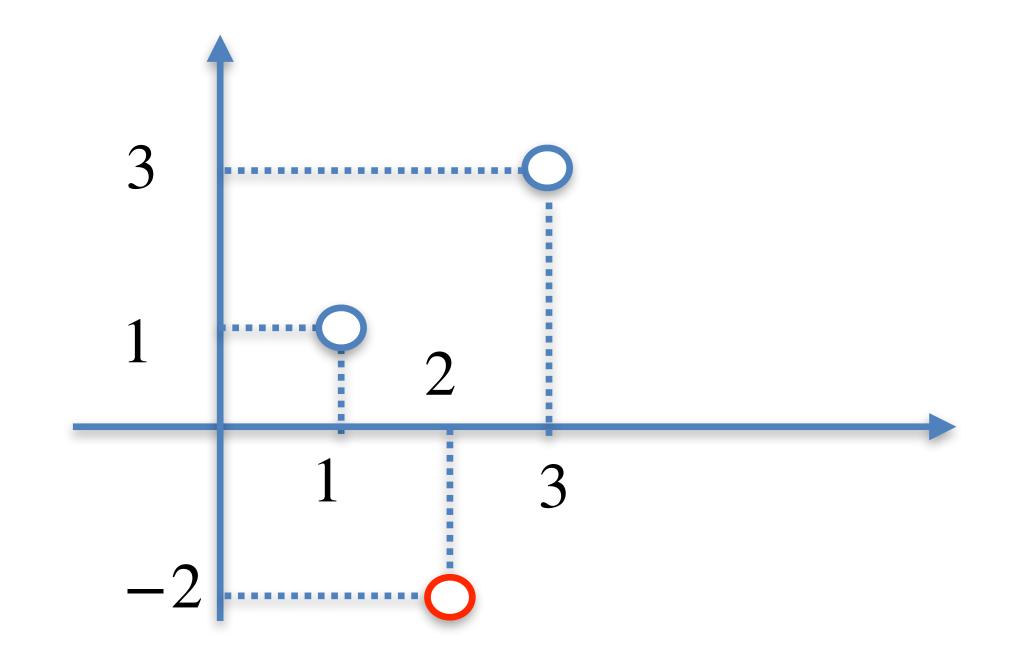




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What is the minimum value?

The min can be found getting the derivative and setting to zero!



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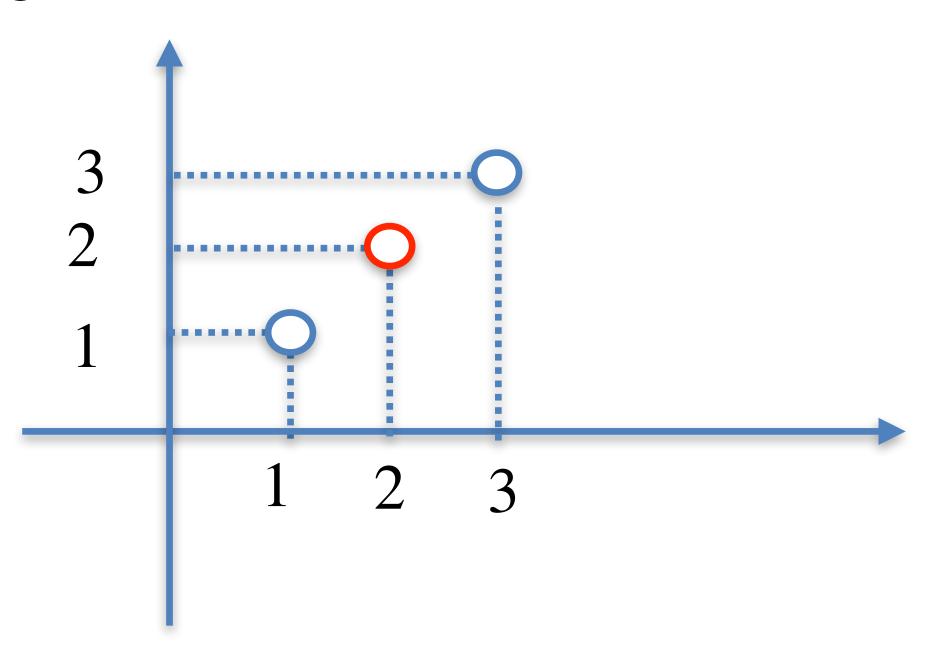


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$$\nabla E(\mathbf{y_3}) = 2(y_3 - y_1) - 2(y_3 - y_2) = 0$$

$$y_3 = \frac{y_1 + y_2}{2}$$



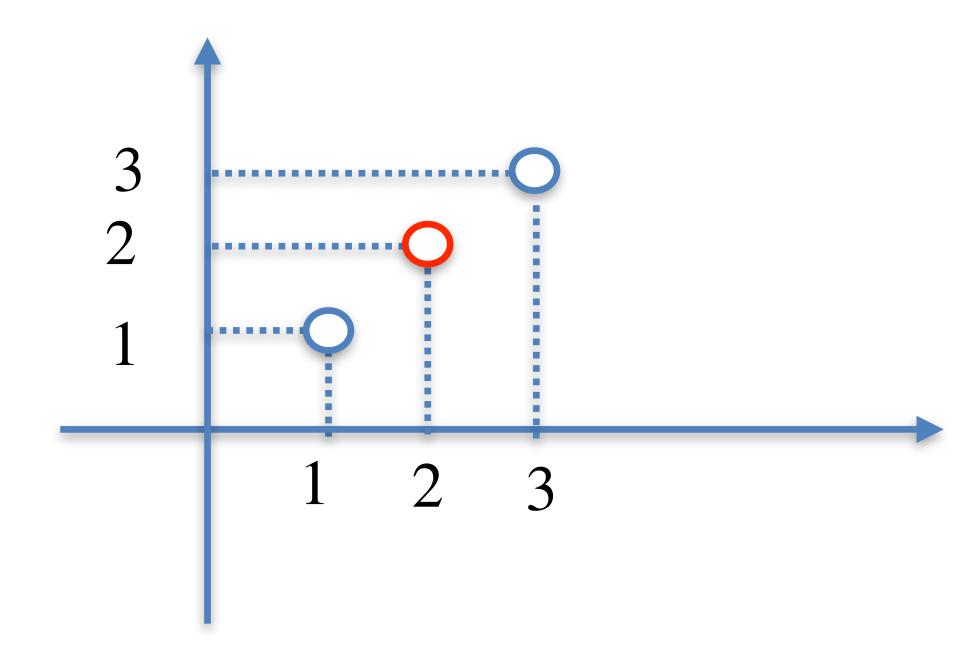


The min can be found getting the derivative and setting to zero!

$$E(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \|^2 = \frac{1}{h^2} [(y_3 - y_1)^2 + (y_2 - y_3)^2]$$

$$\nabla E(\mathbf{y_3}) = 2(y_3 - y_1) - 2(y_3 - y_2) = 0$$

$$y_3 = \frac{y_1 + y_2}{2}$$





The min is, not surprisingly, the point laying in the middle between the two! This is why it is called interpolation!

So, it looks like that this energy function does the job!

$$E(\mathbf{y}) = \| \mathbf{M}_{\frac{1}{h}} \mathbf{y} \|^{2} \qquad \text{with} \qquad \mathbf{M}_{\frac{1}{h}} = \frac{1}{h} \begin{pmatrix} -1 & 1 & 0 & \dots & 0 & 0 \\ 0 & -1 & 1 & \dots & 0 & 0 \\ \vdots & & \ddots & & & \vdots \\ 0 & 0 & \dots & 0 & -1 & 1 \end{pmatrix},$$



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How can we use this to solve the problem in general?

We can write
$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \underbrace{\mathbf{P}_{I_2} \mathbf{v}}_{= \text{known}}$$
 .



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Thus we split the vector \mathbf{y} in two parts, the first of unknown the second of known



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Thus we split the vector \mathbf{y} in two parts, the first of unknown the second of known

The two P are projectors



$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v}$$



$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ ? \\ ? \\ ? \end{pmatrix}$$

$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ ? \\ ? \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} y_1 \\ y_2 \\ ? \\ ? \\ ? \\ ? \end{pmatrix} \qquad \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ? \\ ? \\ ? \\ ? \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ ? \\ ? \\ ? \end{pmatrix} \qquad \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\mathbf{y} = \mathbf{P}_{I_{1} \setminus I_{2}} \mathbf{w} + \mathbf{P}_{I_{2}} \mathbf{v}$$

$$\begin{pmatrix}
0 & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0 \\
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{pmatrix}
\begin{pmatrix}
? \\
? \\
? \\
?
\end{pmatrix} = \begin{pmatrix}
0 \\
0 \\
? \\
? \\
?
\end{pmatrix}$$

$$\mathbf{w} \in \mathbb{R}^{3} \to \mathbf{P}_{I_{1} \setminus I_{2}} \mathbf{w} \in \mathbb{R}^{6}$$

$$\begin{pmatrix}
1 & 0 \\
0 & 1 \\
0 & 0 \\
0 & 0 \\
0 & 0
\end{pmatrix}
\begin{pmatrix}
y_{1} \\
y_{2} \\
0 \\
0 \\
0
\end{pmatrix}$$

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$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\mathbf{w} \in \mathbb{R}^3 \to \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} \in \mathbb{R}^6$$

$$\mathbf{v} \in \mathbb{R}^2 \to \mathbf{P}_{I_2} \mathbf{v} \in \mathbb{R}^6$$

Now, from
$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v}$$
.
$$= \text{known}$$



Now, from
$$\mathbf{y} = \mathbf{P}_{I_1 \setminus I_2} \mathbf{w} + \underbrace{\mathbf{P}_{I_2} \mathbf{v}}_{= \text{known}}$$
.

The missing indices can be computed via

$$\min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{M}_{\frac{1}{h}} \left(\mathbf{P}_{I_1\setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v} \right) \right\|^2$$



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This is a least-squares problem, for which we know the solution. Indeed we can rewrite



$$\min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{M}_{\frac{1}{h}} \left(\mathbf{P}_{I_1\setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v} \right) \right\|^2$$

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$$\min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{M}_{\frac{1}{h}} \left(\mathbf{P}_{I_1\setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v} \right) \right\|^2$$

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Matrices are different but the form is the same of the usual MSE (except for the +!!)

The solution is then the normal equation with a minus on the right hand side

$$\min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{M}_{\frac{1}{h}} \left(\mathbf{P}_{I_1\setminus I_2} \mathbf{w} + \mathbf{P}_{I_2} \mathbf{v} \right) \right\|^2 = \min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{M}_{\frac{1}{h}} \mathbf{P}_{I_1\setminus I_2} \mathbf{w} + \mathbf{M}_{\frac{1}{h}} \mathbf{P}_{I_2} \mathbf{v} \right\|^2 = \min_{\{w_i\}_{i\in I_1\setminus I_2}} \left\| \mathbf{X} \mathbf{w} + \mathbf{r} \right\|^2$$



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$$\mathbf{X}^{\mathsf{T}}\mathbf{X}\hat{\mathbf{w}} = -\mathbf{X}^{\mathsf{T}}\mathbf{r}$$



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$$\mathbf{X}^{\mathsf{T}}\mathbf{X} = \mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}} \mathbf{P}_{I_1 \setminus I_2} = \mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_{\frac{1}{h}} \mathbf{P}_{I_1 \setminus I_2}$$

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$$\mathbf{X}^{\mathsf{T}}\mathbf{X}\hat{\mathbf{w}} = -\mathbf{X}^{\mathsf{T}}\mathbf{r}$$

$$\mathbf{X}^{\mathsf{T}}\mathbf{X} = \mathbf{P}_{I_1 \backslash I_2}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}} \mathbf{P}_{I_1 \backslash I_2} = \mathbf{P}_{I_1 \backslash I_2}^{\mathsf{T}} \mathbf{L}_{\frac{1}{h}} \mathbf{P}_{I_1 \backslash I_2}$$



$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_{\frac{1}{h}} \mathbf{P}_{I_1 \setminus I_2} \hat{\mathbf{w}} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}}^{\mathsf{T}} \mathbf{M}_{\frac{1}{h}} \mathbf{P}_{I_2} \mathbf{v} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_{\frac{1}{h}} \mathbf{P}_{I_2} \mathbf{v},$$

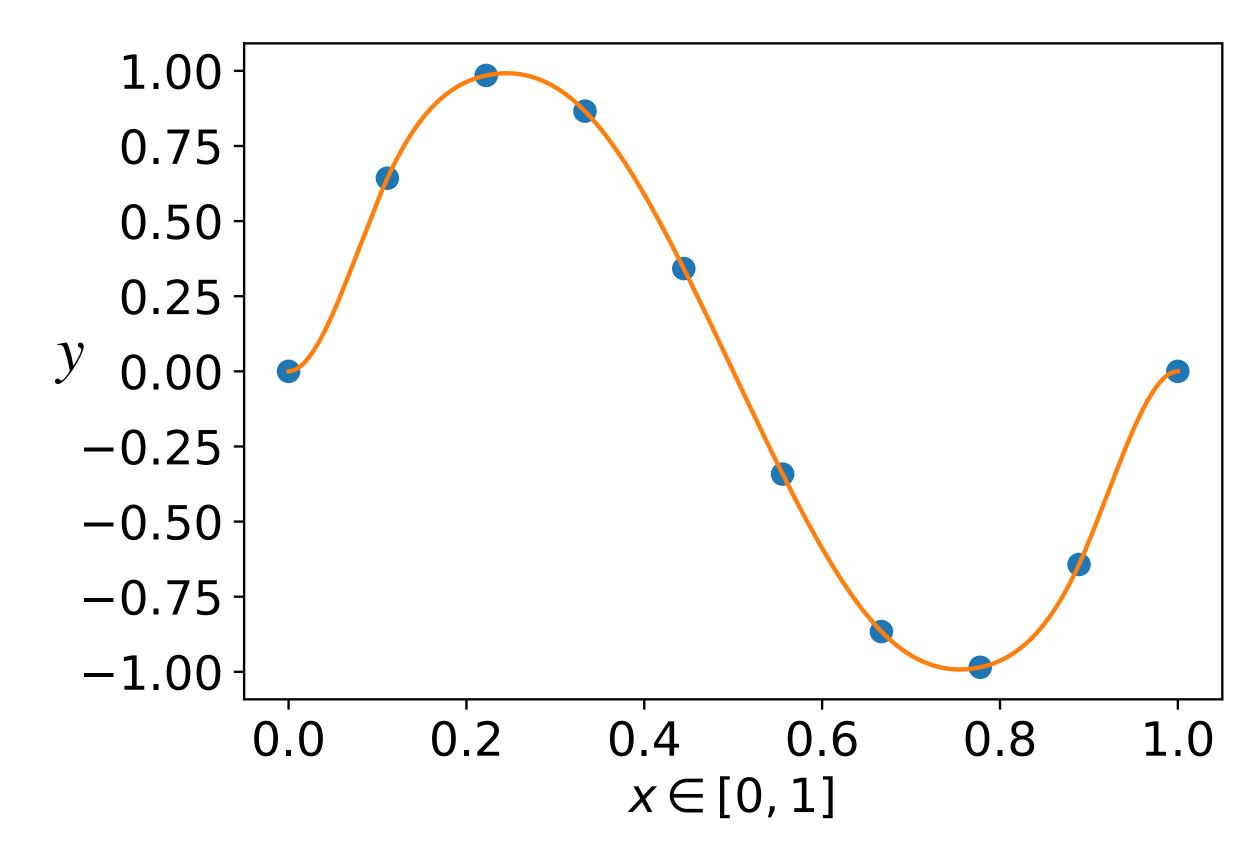
$$\underbrace{\phantom{\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}}} \hat{\mathbf{w}}_{I_1 \setminus I_2} \mathbf{v},$$

$$\underbrace{\phantom{\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}}} \hat{\mathbf{w}}_{I_1 \setminus I_2} \hat{\mathbf{w}}_{I_1$$

Example

 I_1 has 10000 points

 I_2 has 10 points



"Training" set is very small, and since we don't know the ground truth for the others this a semi-supervised problem

Applications

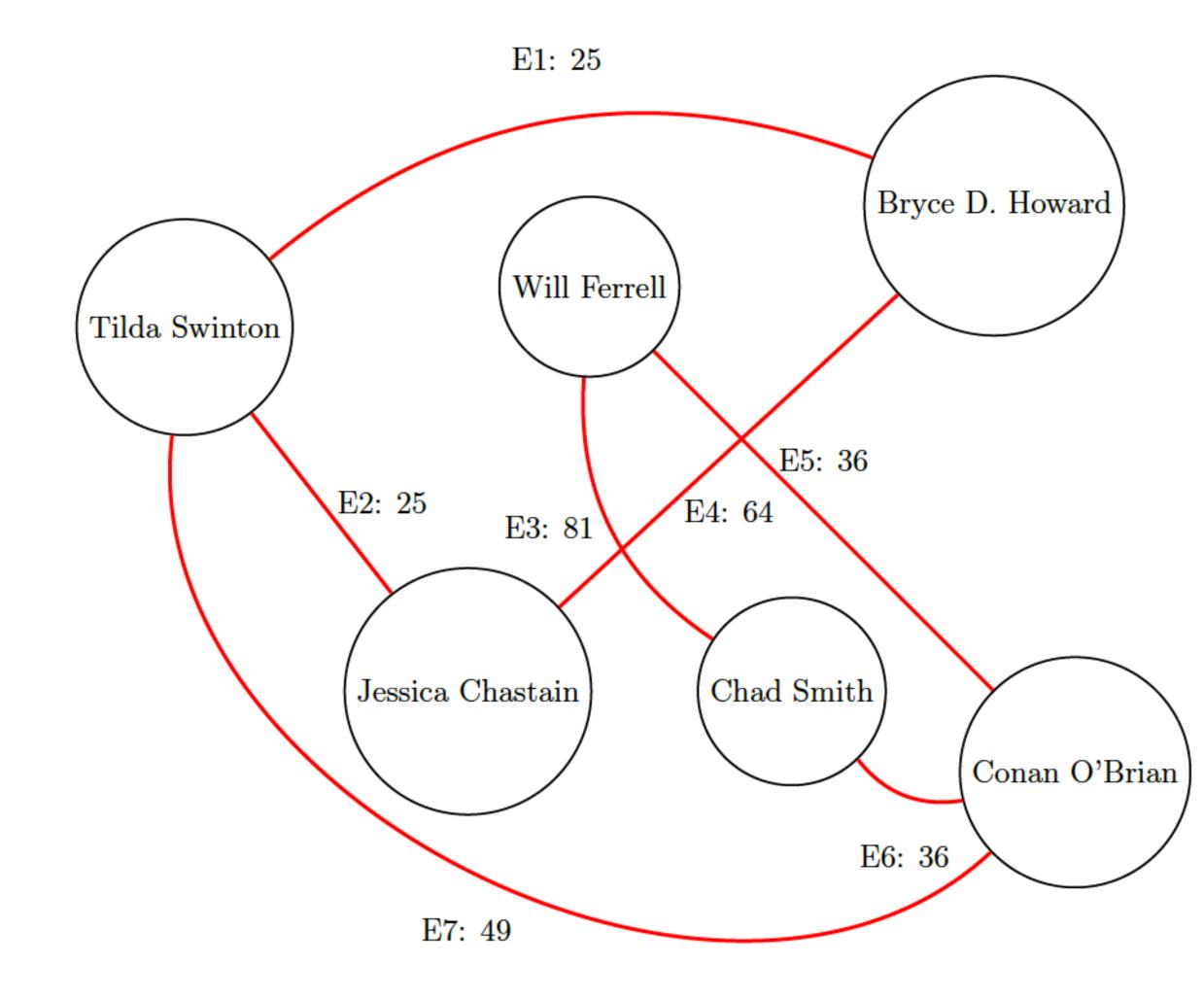
The advantages of using this formulation is that it can be applied to points like we just did, but also to data point for which you can define a similarity



Incidence matrix

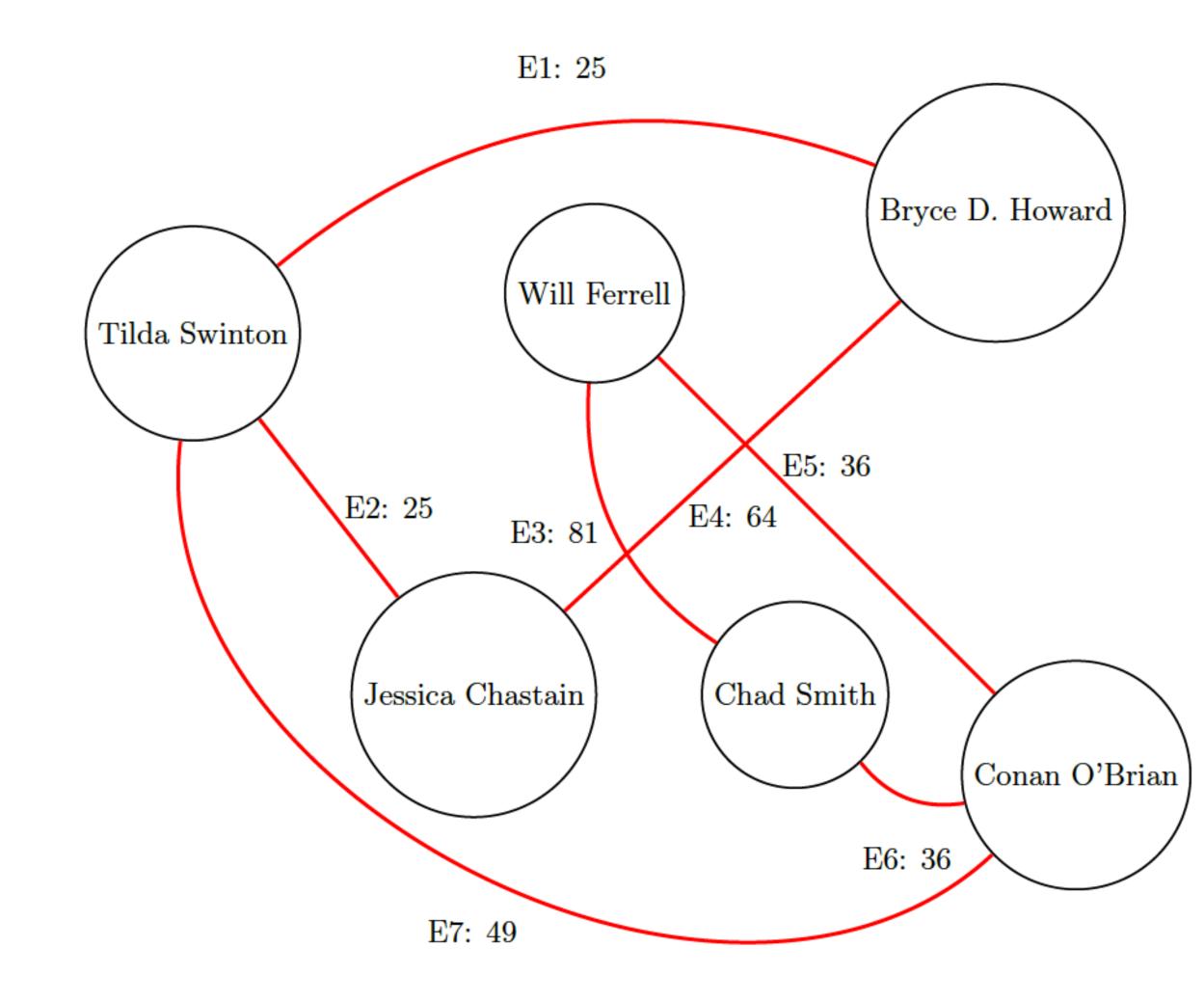
/ E1	-5	0	0	0	5	0	
E2	0	0	0	-5	5	0	
E3	0	-9	0	0	0	9	l
E4	-8	0	0	8	0	0	l
E5	0	0	-6	0	0	6	l
E6	0	-6	6	0	0	0	
E7	0	0	-7	0	7	0	
	B. D. Howard	C. Smith	C. O' Brian	J. Chastain	T. Swinton	W. Ferrell	





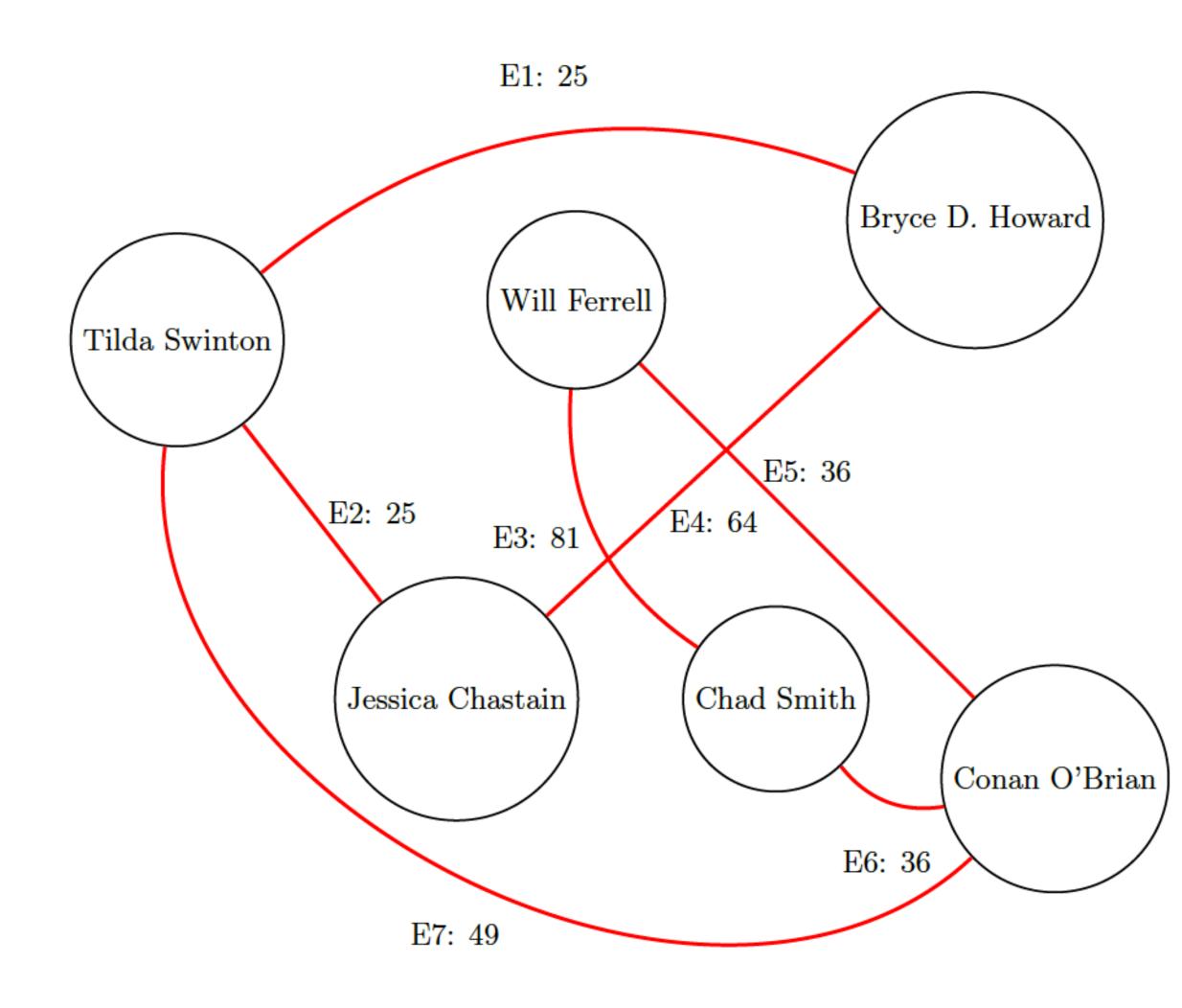
Laplacian matrix

$$L_w = M_w^{\top} M_w = \begin{pmatrix} 89 & 0 & 0 & -64 & -25 & 0 \\ 0 & 117 & -36 & 0 & 0 & -81 \\ 0 & -36 & 121 & 0 & -49 & -36 \\ -64 & 0 & 0 & 89 & -25 & 0 \\ -25 & 0 & -49 & -25 & 99 & 0 \\ 0 & -81 & -36 & 0 & 0 & 117 \end{pmatrix}.$$



The task is: knowing the biological sex of a small set of actors, and using their similarity, predict the biological sex of the others





Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$



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$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

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2x1

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



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Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

6x6 6x2 2x1

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

4x6 6x6 6x2 2x1

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$6x4 4x1 4x6 6x6 6x2 2x1$$

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



Assume that we know that Jessica Chastain is female (label 1) and Will Ferrel male (label 0)

$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$



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$$\mathbf{y}_{known} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$





$$\mathbf{P}_{I_2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Projects 2D vector in to 6D

$$\mathbf{P}_{I_2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Projects 2D vector in to 6D

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Projects 6D vector in to 4D selecting the unknown targets

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_1 \setminus I_2} \mathbf{y}_{unknown} = -\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} \mathbf{L}_w \mathbf{P}_{I_2} \mathbf{y}_{known},$$

$$\mathbf{P}_{I_2} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\mathbf{P}_{I_1 \setminus I_2}^{\mathsf{T}} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

Projects 2D vector in to 6D

Projects 6D vector in to 4D selecting the unknown targets

Easy to find the solution

$$\begin{pmatrix} 89 & 0 & 0 & -25 \\ 0 & 117 & -36 & 0 \\ 0 & -36 & 121 & -49 \\ -25 & 0 & -49 & 99 \end{pmatrix} \tilde{v} = \begin{pmatrix} 64 \\ 0 \\ 0 \\ 25 \end{pmatrix}.$$

$$\hat{v} = \begin{pmatrix} 0.8912 & 0.0840 & 0.2732 & 1 & 0.6128 & 0 \end{pmatrix}^{\mathsf{T}}$$
.



We can then impose a simple threshold >0.5 -> 1 <0.5 ->0