Lecture 8B MTH6102: Bayesian Statistical Methods

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2023

Today's lecture

- Review
- Understand Markov Chain
- Understand Metropolis-Hastings
- Apply Metropolis-Hastings in Bayesian inference to generate samples from the posterior pdf.

- The Monte Carlo integration refers to the theory and practice of approximating integrals using random samples.
- Monte Carlo integration methods are sometimes referred to as stochastic integration methods because they are based on random sampling.

• Suppose that we wish to compute the following integral

$$I = \int_0^1 \frac{\sin(x(1-x))}{1+x+\sqrt{x}} \, dx.$$

 There does not appear to be any closed-form solution, so we can approximate the integral using Monte Carlo methods.

Example

• Plot of the function $h(x) = \frac{\sin(x(1-x))}{1+x+\sqrt{x}}$, $x \in [0,1]$,



• Using a deterministic numerical integration method in R based on adaptive quadrature of functions, I = 0.079.

>h=function(x) sin(x*(1-x))/(1+x+sqrt(x))
>integrate(h,lower=0,upper=1)
>0.07852747 with absolute error < 9.2e-06</pre>

Example

- **Goal:** Compute the integral *I* using Monte Carlo integration
- The integral, I, can be written as the expectation of h(X), where $X \sim U[0,1]$ and

$$h(x) = \frac{\sin(x(1-x))}{1+x+\sqrt{x}}, x \in [0,1].$$

• Because,

$$I = \int_0^1 \frac{\sin(x(1-x))}{1+x+\sqrt{x}} \cdot 1 \, dx = \int_0^1 h(x)f(x) \, dx = E(h(X)),$$

where $f(x) = 1, x \in [0, 1]$ is the U[0, 1] density.

 $I = IE_{f}(h(x)) = \int h(x) f(x) dx$ f does not need to be uniform but a well-mound In this case, you generate Ali, Xn~+ ond the Monte Carlo estimator 15

 $\int_{N} \sum_{i=1}^{N} h(X_i)$

 $X \sim U[0, 1].$

• Thus, we can generate IID observations X_1, \ldots, X_N from U[0, 1], and estimate I by $\hat{I} = \frac{1}{N} \sum_{i=1}^{N} h(X_i) = \frac{1}{N} \sum_{i=1}^{N} \frac{\sin(X_i(1 - X_i))}{1 + X_i + \sqrt{X_i}}.$ • \hat{I} is the Monte Carlo integration estimator of I = E(h(X)), • Then, the weak law of large numbers (WLLN) says

$$\hat{I} = \frac{1}{N} \sum_{i=1}^{N} h(X_i) \xrightarrow{P} I, \quad N \to \infty,$$

• As we use more samples N, \hat{I} should get more and more accurate.

$$\hat{T} = \frac{1}{N} \left(h(X_1) + \cdots + h(X_N) \right)$$



Bayesian inference

- Quite often a quantity of interest in statistics may be expressed as an integral that we wish to evaluate.
- For instance, in Bayesian analysis, one is often interested in the posterior mean of a particular continuous parameter θ PIXEA) =E(I(XGA)

$$\hat{\theta}_{\scriptscriptstyle B} = \int \theta \, p(\theta \mid y) \, d\theta,$$

• or in the posterior mean of transformed parameters $\psi = g(heta)$

$$\hat{\psi}_{B} = \int g(\theta) \, p(\theta \mid y) \, d\theta, \, = \mathcal{F}(g/\theta) / y$$

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or in the posterior probability,

$$P(\theta \le c) = \int_{-\infty}^{c} p(\theta \mid y) \, d\theta = \int_{-\infty}^{\infty} I(\theta \le c) \, p(\theta \mid y) \, d\theta = E(I(\theta \le c)).$$

- Suppose we observe iid data y_1, \ldots, y_n from Poisson (λ) .
- Let λ have the gamma(α, β) prior distribution, the conjugate prior distribution for the Poisson likelihood.

What is the posterior density, p(λ | y) of λ?
How would you estimate the posterior probability P(λ < c) by Monte Carlo integration, for some c > 0?

Solution

(Problem 2), the posterior density, p(7,1y), of 7 p(7/y)~ Gamma (a+Žyi, B+n), 770 15 2) We want to compute P(A<C) using Monte Carlo Integration. First, note that as $P(\lambda < c) = \int \overline{I(\lambda < c)} p(\lambda < d) d\lambda$ = IE(I(2 < c)) = TWe generate an IID sample $\Lambda^{(1)}_{i}, \Lambda^{(N)}_{i}$ From Gamma (a+Žyc, n+e)
$$\begin{split} & \bigwedge_{A} \sum_{i=1}^{N} \sum_{j=1}^{N} T(\Lambda^{(i)}, c) = \bigcup_{i=1}^{N} \sum_{j=1}^{N} h(\Lambda^{(i)}) \\ & = \bigwedge_{i=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} h(\Lambda^{(i)}) \\ & = \bigwedge_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} h(\Lambda^{(i)}) \\ & = \bigwedge_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} h(\Lambda^{(i)}) \\ & = \bigwedge_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N} \sum_{i=1}^{N} \sum_{j=1}^{N} \sum_{j=1}^{N}$$
thena

Board question: Binomial data/flat prior

• Let $k \sim \operatorname{binom}(n, q)$. • Assume flat prior on q. $\operatorname{Cov}[oi]$ • Let n = 860 and k = 441• R code below a=1 b=1 n=860 k=441 N = 10000beta.post.sample; rbeta(N, shape1=a+k, shape2=b+n-k) > gamma.sample=log((beta.post.sample/(1-beta.post.sample))) mean(gamma.sample) c(quantile(gamma.sample,0.025),quantile(gamma.sample,0.975))

• The first commond will contain a sample of 104 observations from the posterior density, beta (1+x, 1+n-x), soy 2(1), ..., 2(N) The second will contain a sample from $h(r) = \log \left(\frac{2}{1-r} \right) \left(\log of odds \right)$ $\frac{2h(2i)}{-2}$, $\frac{-2}{h(2N)}$ = gamma. sample • The estimator θ is the sample mean of $h(\ell_{7})_{\ell_{1}}$, $h(\ell_{7})_{\ell_{1}}$, h($\mathcal{O} = \frac{1}{N} \sum_{i=1}^{N} \frac{h(i_i)}{h(i_i)} = \frac{1}{N} \sum_{i=1}^{N} \frac{\log\left(\frac{i_i}{1-i_i}\right)}{\sum_{i=1}^{N} \frac{1}{1-i_i}}$ This is the Monte Corlo estimator of 8. Ois the posterior mean of h(2) $\Theta = IE\left(h(2)\right) = IE\left(IOg \frac{2}{1-2}\right) = \int IOg\left(\frac{2}{1-2}\right)p[2|x]dg$ $p[e|x] \sim beta(1+x, 1+n-x).$

Board question: Binomial data/flat prior

- When this code has run, what will beta.post.sample contain?
 What will gamma.sample contain?
- Describe the estimator $\hat{\theta}$ for a quantity θ (which you should also determine) that would be obtained by the following R commands
- gamma.sample=log((beta.post.sample/(1-beta.post.sample)))
 mean(gamma.sample)
- In statistical terms, what quantity will the last line of code output?
- See also, Question 3, final exam Jan 2023

• Monte Carlo integration estimates $E_f[h(X)]$ by directly sampling iid samples from the pdf f or from the posterior pdf in Bayesian inference

$$\hat{I} = \frac{1}{N} \sum_{i=1}^{N} h(X_i), \quad X_1, \dots, X_n \text{ iid } \sim f.$$

- **Question:** But what if we cannot sample directly from *f*?
 - f is not analytically tractable.
 - Then, simple Monte Carlo integration cannot be used.

- Markov Chain Monte Carlo (MCMC) is a set of methods that can generate a sample with pdf *f* without having to sample from *f* directly.
- Thus, MCMC can be used to generate samples from complicated probability distributions.
- At the price, however, of yielding **dependent** observations that are **approximately** from *f*.

Markov Chain Monte Carlo (MCMC)

Goal: f 15 density very complituted wont to generale a sample from f.

• The general **idea** of Markov Chain Monte Carlo (MCMC) methods is to construct a sequence of RV X_1, X_2, \ldots , called Markov chain, which (hopefully) converges to the distribution of interest f.

• However $X_1, X_2 \dots$ is NOT independent any more.

- But it can still be used to estimate quantities (e.g, mean) because there is a WLLN for Markov chains.
- Under certain conditions,

$$\hat{I} = \frac{1}{N} \sum_{i=1}^{N} h(X_i) \xrightarrow{P} E[h(X)] = I, \quad \text{as } N \to \infty.$$

$$\underbrace{\chi_{1, \dots, \chi_{N}}}_{IO} (Maxter Chains)$$

What is a Markov Chain?

Definition (Markov Chain). A Markov chain is a sequence X₁, X₂,... of random variables such that the probability distribution of X_i (pmf or pdf) only depends on the previous value X_{i-1}

• The process depends on the past only through the present.

present



• It can go off towards $-\infty$ or ∞ without limit.

- So you flip a coin move +1 steps if heads, move -1 steps if tails.
- At step i of this Markov chain, X_{i-1} is either increased or decreased by 1.
- Each possibility happens with probability $\frac{1}{2}$. $-\frac{10}{7/2}$ $\frac{10}{7/2}$ $\frac{10}{7/2}$

- The Metropolis-Hastings algorithm is a type of Markov chain Monte Carlo (MCMC) that works as follows.
- Let q(y|x) be a conditional density that we know how to sample from.
- q(y|x) is called the proposal distribution.
- The Metropolis-Hastings algorithm creates a Markov Chain (dependent observations) X₁, X₂,... as follows.

Choose X_1 arbitrarily. Suppose we have generated X_1, \ldots, X_i . To generate X_{i+1} do the following:

Generate a proposal or candidate random value Y ~ q(y|X_i).
≥ Evaluate r ≡ r(X_i, Y) where

$$r(x,y) = \min \Big\{ \frac{f(y)}{f(x)} \frac{q(x|y)}{q(y|x)}, 1 \Big\}.$$

3 Generate $U \sim U(0,1)$. If $U \leq r$, set $X_{i+1} = Y$, otherwise set $X_{i+1} = X_i$.

- q is the proposal distribution: we propose new rv Y using the conditional distribution q(· | X_i) that depends on X_i (not on the past).
- MH accepts Y with probability $r \equiv r(X_i, Y) = \min\left\{\frac{f(Y)}{f(X_i)}\frac{q(X_i|Y)}{q(Y|X_i)}, 1\right\}$, called the acceptance probability.

- f is sometimes called the target distribution: this is what we are aiming for, i.e. we want to generate a sample with pdf f.
- In Bayesian inference, f would be the posterior distribution $p(\theta \mid y)$, and we want a sample of θ values from this posterior distribution.

Remarks:

- In general, to implement a random event that happens with probability r:
- Generate $u \sim \text{Uniform}(0, 1)$;
- Event happens if $u \leq r$.
- If U is a random variable, with $U\sim {\rm Uniform}(0,1),$ then U has cdf F(r)=r, so $P(U\leq r)=r.$

Remarks:

- A common choice for q(y|x) is $N(x, b^2)$ for some b > 0.
- This means that the proposal Y is a drawn from normal centered at the current value.

• By symmetry,
$$q(y|x) = q(x|y)$$

$$r(x,y) = \min\left\{\frac{f(y)}{f(x)}, 1\right\}.$$

Remarks:

• In the algorithm, f only appears in acceptance probability

$$r(X_i, Y) = \min\left\{1, \frac{f(Y)}{f(X_i)}\right\}.$$

The acceptance probability does not depend on the normalisation constant, i.e. if f(x) = cg(x), where c > 0 doesn't depend on x, then

$$r(X_i, Y) = \min\left\{1, \frac{g(Y)}{g(X_i)}\right\}.$$

 So we only need to know f up to a normalisation constant. Useful for Bayesian inference!

- **1** The Metropolis-Hastings algorithm generates a dependent sequence of observations X_1, X_2, \ldots .
- ② Since our procedure for generating X_{i+1} depends only on X_i , the conditional distribution of X_{i+1} given X_1, \ldots, X_i depends only on X_i .
- **3** Hence, the sequence X_1, X_2, \ldots is a Markov chain.

Output of the Metropolis-Hastings algorithm

- The chain X_1, X_2, \ldots has the property that: if $X_{i-1} \sim f$, then $X_i \sim f$.
- f is the equilibrium distribution or stationary of the chain.
- However, we don't start with $X_1 \sim f$ (because if we could, we wouldn't need this algorithm).
- But for large enough i, if some technical conditions are met, then each $X_i \sim f$ approximately.

Output of the Metropolis-Hastings algorithm

- **1** In practice, we only generate X_1, X_2, \ldots, X_N for some large N.
- ② Under some conditions, the empirical distribution of X_1, X_2, \ldots, X_N approximates f well if N is large.
- 3 Hence, we can approximate the integral $I = \int h(x)f(x) dx$ using the approximated X_1, X_2, \ldots, X_N , that is

$$\frac{1}{N}\sum_{i=1}^{N}h(X_i), \quad X_1, X_2, \dots, X_N \sim f(\text{approximately}),$$

and X_1, X_2, \ldots, X_N generated by MH.

Example: Metropolis-Hastings algorithm

• The Cauchy distribution has density

$$f(x) = \frac{1}{\pi(1+x^2)}$$

- Our goal is to simulate a Markov chain whose stationary distribution is f.
- Take q(y|x) to be $N(x, b^2)$ for some b > 0.
- Then,

$$r(x,y) = \min\left\{\frac{1+x^2}{1+y^2}, 1\right\}.$$

• Let $r = r(X_i, Y)$. Generate $U \sim U(0, 1)$. If $U \leq r$, set $X_{i+1} = Y$, otherwise set $X_{i+1} = X_i$.

Example: Metropolis-Hastings algorithm

• Figure below shows the chains of length N = 1000 using b = 1



Example: Metropolis-Hastings algorithm

- Figure: Histogram of chains and the plot of the Cauchy density (red)
- The distribution of chain converges to the desired Cauchy distribution.



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- Let f be the posterior pdf, $p(\theta \mid y)$: this is the distribution we want to sample from.
- Let $q(\psi|\theta_i)$ be a pdf for the proposal ψ which is symmetric in ψ and θ , e.g., normal $N(\theta_i, b^2)$.
- The algorithm constructs a Markov chain $\theta_1, \theta_2, \ldots$, where the θ_i are continuous rvs (in our applications).

- q is called the proposal distribution: it is used to generate the next possible point in the Markov chain.
- q is often taken as a normal distribution centred on the current point

$$\psi_i \sim N(\theta_i, b^2)$$
, for some $b > 0$.

• The normal pdf is symmetric in θ and $\psi,$ as required by the algorithm

$$q(\psi \mid \theta) = \frac{1}{\sqrt{2\pi}b} e^{-\frac{(\psi - \theta)^2}{2b^2}} = \frac{1}{\sqrt{2\pi}b} e^{-\frac{(\theta - \psi)^2}{2b^2}} = q(\theta \mid \psi).$$

The algorithm constructs a Markov chain $\theta_1, \theta_2, \ldots$ as follows:

- Start with arbitrary θ_1 .
- For each i > 1, generate ψ_i from distribution $q(\psi \mid \theta_i)$.

• Let
$$r = \min\left\{1, \frac{p(\psi \mid y)}{p(\theta_i \mid y)}\right\}$$

Set

$$\theta_{i+1} = \begin{cases} \psi & \text{with probability } r \\ \theta_i & \text{with probability } 1 - r \end{cases}$$

In Bayesian inference, the posterior density is

 $p(\theta \mid y) \propto p(\theta) p(y \mid \theta)$

• It's difficult to find the normalizing constant

$$\int p(\theta) \ p(y \mid \theta) \ d\theta$$

- We don't need to find this, we just put $g(\theta) = p(\theta) p(y \mid \theta)$, use g in the algorithm (where we have f), and we will get an approximate sample from $p(\theta \mid y)$.
- The Markov chain $\theta_1, \theta_2, \ldots$ is this sample.

Define $g(\theta) = p(\theta) p(y | \theta)$, the non-normalized posterior density. Generate a Markov chain $\theta_1, \theta_2, \ldots$ as follows:

- Choose some b > 0.
- Start with θ_1 , where $g(\theta_1) > 0$.
- For each i > 1:
 - Generate $\psi \sim N(\theta_i, b^2)$.

• Let

$$r = \min\left\{1, \frac{g(\psi)}{g(\theta_i)}\right\}.$$

• Set

$$heta_{i+1} = egin{cases} \psi & \mbox{with probability } r \ heta_i & \mbox{with probability } 1 - r \end{cases}$$

- We usually do the computations using the log of the posterior density.
- The likelihood is typically a product of many terms.

$$p(y \mid \theta) = \prod_{i=1}^{n} p(y_i \mid \theta)$$

- Due to finite accuracy of computers, if we multiply these together for a large dataset, the result is inaccurate.
- So calculate

$$\log (p(y \mid \theta)) = \sum_{i=1}^{n} \log (p(y_i \mid \theta))$$

- Define $\mathcal{L}(\theta) = \log (p(\theta) p(y | \theta)) = \log (p(\theta)) + \log (p(y | \theta))$, the log of the posterior density (up to a constant).
- To work on the log scale, the part of the algorithm with the acceptance probability changes.

Define

$$\delta = \min\left(0, \mathcal{L}(\psi) - \mathcal{L}(\theta_{i-1})\right)$$

• Generate
$$u \sim \text{Uniform}(0, 1)$$

Set

$$\theta_i = \begin{cases} \psi & \text{ if } \log(u) \leq \delta \\ \theta_{i-1} & \text{ otherwise} \end{cases}$$

- Y_1, \ldots, Y_n iid from $N(\theta, \sigma^2)$ where σ^2 is known.
- $\theta \sim N(\mu,\tau^2)$ with τ^2 known,
- Apply the Metropolis-Hastings algorithm to simulate from the posterior $p(\theta|y_1, \ldots, y_n)$ after observing Y = y

Metropolis-Hastings algorithm for Bayesian inference

- Metropolis-Hastings algorithm generates a dependent sequence $\theta^{(1)}, \ldots, \text{ of } \theta$ values.
- Under mild conditions, the empirical distribution of $\theta^{(i)}$, i = 1, 2, ... will approximate well the posterior.

• We can view $\theta^{(i)}$, i = 1, 2, ... as a sample from the posterior $p(\theta|y)$.

- Hence, we can approximate posterior means, quantiles and other posterior quantities of interest using $\{\theta^{(1)}, \ldots, \theta^{(N)}\}$ for large N.
- However, our approximation to these quantities will depend on how well our simulated sequence actually approximates $p(\theta \mid y)$.