

1. (1 point) Library/WHFreeman/Holt_linear_algebra/Chaps_1-4/2.61.pg

Let \mathbf{u}_4 be a linear combination of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$.
Select the best statement.

- A. $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$.
- B. There is no obvious relationship between $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ and $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$.
- C. We only know that $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} \subseteq \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$.
- D. $\text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \text{span}\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ when \mathbf{u}_4 is a scalar multiple of one of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$.
- E. none of the above

2. (1 point) Library/WHFreeman/Holt_linear_algebra/Chaps_1-4/2.3.50.pg

Let \mathbf{u}_4 be a linear combination of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$.
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a linearly dependent set of vectors unless one of $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is the zero vector.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is never a linearly dependent set of vectors.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly dependent or linearly independent set of vectors depending on the vectors chosen.
- D. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is always a linearly dependent set of vectors.
- E. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ could be a linearly dependent or linearly independent set of vectors depending on the vector space chosen.
- F. none of the above

3. (1 point) Library/TCNJ/TCNJ_LinearIndependence/problem1.pg
Suppose $S = \{r, u, d\}$ is a set of linearly independent vectors.

If $x = 2r + 2u + 5d$, determine whether $T = \{r, u, x\}$ is a linearly independent set.

1. Is T linearly independent or dependent?

If T is dependent, enter a non-trivial linear relation below. Otherwise, enter 0's for the coefficients.

$$\underline{\hspace{1cm}} r + \underline{\hspace{1cm}} u + \underline{\hspace{1cm}} x = 0.$$

4. (1 point) Library/WHFreeman/Holt_linear_algebra/Chaps_1-4/2.3.47.pg

Let $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ be a linearly independent set of vectors.
Select the best statement.

- A. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ could be a linearly independent or linearly dependent set of vectors depending on the vectors chosen.
- B. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is never a linearly independent set of vectors.
- C. $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is always a linearly independent set of vectors.
- D. none of the above

5. (1 point) Library/Rochester/setLinearAlgebra8VectorSpaces/ur_la_8_5.pg

Find the dimensions of the following linear spaces.

- (a) $\mathbb{R}^{6 \times 2}$ ____
- (b) P_4 ____
- (c) The space of all diagonal 3×3 matrices ____

6. (1 point) Library/Rochester/setLinearAlgebra10Bases/ur_la_10_34.pg

The set

$$B = \left\{ \begin{bmatrix} -1 & -2 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ 0 & -2 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 2 \end{bmatrix} \right\}$$

is a basis of the space of upper-triangular 2×2 matrices.

Find the coordinates of $M = \begin{bmatrix} -7 & -3 \\ 0 & -8 \end{bmatrix}$ with respect to this basis.

$$[M]_B = \begin{bmatrix} \text{---} \\ \text{---} \\ \text{---} \end{bmatrix}$$

7. (1 point) Library/Rochester/setLinearAlgebra15TransfOfLinSpaces/ur_la_15_1.pg

Which of the following transformations are linear? Select all of the linear transformations. There may be more than one correct answer. Be sure you can justify your answers.

- A. $T(A) = \begin{bmatrix} 4 & 3 \\ -2 & 6 \end{bmatrix} A$ from $\mathbb{R}^{2 \times 4}$ to $\mathbb{R}^{2 \times 4}$
- B. $T(A) = A^T$ from $\mathbb{R}^{4 \times 6}$ to $\mathbb{R}^{6 \times 4}$

- C. $T(A) = A \begin{bmatrix} 2 & -5 \\ 6 & 4 \end{bmatrix} - \begin{bmatrix} 2 & 5 \\ 6 & 8 \end{bmatrix}$ A from $\mathbb{R}^{2 \times 2}$ to $\mathbb{R}^{2 \times 2}$
- D. $T(A) = \det(A)$ from $\mathbb{R}^{6 \times 6}$ to \mathbb{R}
- E. $T(A) = A \begin{bmatrix} -7 & 1 \\ 4 & 9 \end{bmatrix}$ from \mathbb{R} to $\mathbb{R}^{2 \times 2}$
- F. $T(A) = A + I_4$ from $\mathbb{R}^{4 \times 4}$ to $\mathbb{R}^{4 \times 4}$

8. (1 point) Library/Hope/Multi1/04-01-Linear-transformations/Lin_trans_05.pg

Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ be defined by $f(\langle x, y \rangle) = 4x - 6y + 2$. Is f a linear transformation?

- (1) $f(\langle x_1, y_1 \rangle + \langle x_2, y_2 \rangle) = \underline{\hspace{2cm}}$. (Enter x_1 as $x1$, etc.)
 $f(\langle x_1, y_1 \rangle) + f(\langle x_2, y_2 \rangle) = \underline{\hspace{2cm}} + \underline{\hspace{2cm}}$.
 Does $f(\langle x_1, y_1 \rangle + \langle x_2, y_2 \rangle) = f(\langle x_1, y_1 \rangle) + f(\langle x_2, y_2 \rangle)$ for all $\langle x_1, y_1 \rangle, \langle x_2, y_2 \rangle \in \mathbb{R}^2$?

- choose
- Yes, they are equal
- No, they are not equal

- (2) $f(c\langle x, y \rangle) = \underline{\hspace{2cm}}$.
 $c(f(\langle x, y \rangle)) = \underline{\hspace{2cm}}$ ($\underline{\hspace{2cm}}$).
 Does $f(c\langle x, y \rangle) = c(f(\langle x, y \rangle))$ for all $c \in \mathbb{R}$ and all $\langle x, y \rangle \in \mathbb{R}^2$?

- choose
- Yes, they are equal
- No, they are not equal

- (3) Is f a linear transformation?

- choose
- f is a linear transformation
- f is not a linear transformation

9. (1 point) Library/Rochester/setLinearAlgebra14TransfOfRn/ur_la_14_10.pg

Consider a linear transformation T from \mathbb{R}^3 to \mathbb{R}^2 for which

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 8 \\ 7 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad T\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Find the matrix A of T .

$$A = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \end{bmatrix}$$

10. (1 point) Library/Rochester/setLinearAlgebra15TransfOfLinSpaces/ur_la_15_7.pg

Find the matrix A of the linear transformation $T(f(t)) = 9f'(t) + 6f(t)$ from P_2 to P_2 with respect to the standard basis for P_2 , $\{1, t, t^2\}$.

$$A = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \\ _ & _ & _ \end{bmatrix}$$

11. (1 point) Library/Rochester/setLinearAlgebra11Eigenvalues/ur_la_11_9.pg

Suppose A is an invertible $n \times n$ matrix and \vec{v} is an eigenvector of A with associated eigenvalue -4 . Convince yourself that \vec{v} is an eigenvector of the following matrices, and find the associated eigenvalues.

- (1) The matrix A^2 has an eigenvalue $\underline{\hspace{2cm}}$.
- (2) The matrix A^{-1} has an eigenvalue $\underline{\hspace{2cm}}$.
- (3) The matrix $A - 9I_n$ has an eigenvalue $\underline{\hspace{2cm}}$.
- (4) The matrix $-7A$ has an eigenvalue $\underline{\hspace{2cm}}$.

12. (1 point) Library/Rochester/setLinearAlgebra11Eigenvalues/ur_la_11_8.pg

Find the eigenvalues and eigenvectors of the matrix

$$\begin{bmatrix} 6 & -4 & -15 \\ -1 & 3 & 9 \\ 4 & -4 & -13 \end{bmatrix}$$

From smallest to largest, the eigenvalues are $\lambda_1 < \lambda_2 < \lambda_3$ where

$$\lambda_1 = \underline{\hspace{2cm}} \text{ has an eigenvector } \begin{bmatrix} _ \\ _ \\ _ \end{bmatrix},$$

$$\lambda_2 = \underline{\hspace{2cm}} \text{ has an eigenvector } \begin{bmatrix} _ \\ _ \\ _ \end{bmatrix},$$

$$\lambda_3 = \underline{\hspace{2cm}} \text{ has an eigenvector } \begin{bmatrix} _ \\ _ \\ _ \end{bmatrix}.$$

Note: you may want to use a graphing calculator to estimate the roots of the polynomial which defines the eigenvalues.

13. (1 point) Library/Hope/Multi1/05-04-Diagonalization/DiagR_04.pg

$$A = \begin{bmatrix} -13 & -4 & 28 \\ 4 & 3 & -8 \\ -6 & -2 & 13 \end{bmatrix}$$

If possible, find an invertible matrix P so that $D = P^{-1}AP$ is a diagonal matrix. If it is not possible, enter the identity matrix for P and the matrix A for D . You must enter a number in every

answer blank for the answer evaluator to work properly.

$$P = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \\ _ & _ & _ \end{bmatrix}.$$

$$D = \begin{bmatrix} _ & _ & _ \\ _ & _ & _ \\ _ & _ & _ \end{bmatrix}.$$

Is A diagonalizable over \mathbb{R} ?

- choose
- diagonalizable
- not diagonalizable

Be sure you can explain why or why not.

14. (1 point) Library/TCNJ/TCNJ_LengthOrthogonality/problem3.

pg

Let W be the set of all vectors $\begin{bmatrix} x \\ y \\ x+y \end{bmatrix}$ with x and y real. Find

a basis of W^\perp .

$$\left\{ \begin{bmatrix} _ \\ _ \\ _ \end{bmatrix} \right\}.$$

15. (1 point) Library/Rochester/setLinearAlgebra17DotProductRn/ur_la_17_17.pg

Find the orthogonal projection of

$$\vec{v} = \begin{bmatrix} 0 \\ 0 \\ -9 \\ 0 \end{bmatrix}$$

onto the subspace W of \mathbb{R}^4 spanned by

$$\begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix}.$$

$$\text{proj}_W(\vec{v}) = \begin{bmatrix} _ \\ _ \\ _ \\ _ \end{bmatrix}$$

16. (1 point) Library/Rochester/setLinearAlgebra20LeastSquares/ur_la_20_2.pg

Find the least-squares solution \vec{x}^* of the system

$$\begin{bmatrix} 2 & -1 \\ -2 & 1 \\ 4 & 5 \end{bmatrix} \vec{x} = \begin{bmatrix} 13 \\ -17 \\ -5 \end{bmatrix}.$$

$$\vec{x}^* = \begin{bmatrix} _ \\ _ \end{bmatrix}$$