# 2 Random variables, independence, integration and conditioning

#### 2.1 Measurable functions, products and measure pushforward

Let  $(\Omega, \mathcal{F}), (\Omega', \mathcal{F}')$  be two measurable spaces. When  $\Omega'$  is a topological space, we consider it per default endowed with the Borel  $\sigma$ -algebra. A function  $X : \Omega \to \Omega'$  is called *measurable* if

$$X^{-1}(B) \in \mathcal{F}, \text{ for all } B \in \mathcal{F}',$$
 (1)

where

$$X^{-1}(B) := \{ \omega \in \Omega : X(\omega) \in B \}.$$

When such a function is defined on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  we call X a random variable (with values in  $\Omega'$ ).

It is enough to require (1) to hold for B running over some set of generators of  $\mathcal{F}'$ . For instance, for  $\mathbb{R}$ -valued X, measurability (1) holds if (1) holds for every  $B = (-\infty, x]$  with x running over the set of rational numbers.

A function  $X : \Omega \to \mathbb{R}$  obtained by algebraic or analytic manipulations with a countable family  $(X_n)$  of measurable  $\mathbb{R}$ -valued functions is again a measurable function. For instance  $\limsup X_n$  is measurable (in general, as function into extended real line  $\mathbb{R} \cup \{\infty\}$ ).

**Example** The indicator function of  $A \in \mathcal{F}$ 

$$1_A(\omega) = \begin{cases} 1, & \omega \in A, \\ 0, & \omega \notin A \end{cases}$$

is measurable, and so for  $A_j \in \mathcal{F}$  are the *simple* functions of the form

$$X(\omega) = \sum_{j=1}^{n} y_j \mathbb{1}_{A_j}(\omega), \quad y_j \in \mathbb{R}.$$

**Definition 2.1.** Let  $(X_t, t \in T)$  be a family of measurable functions  $X_t : \Omega \to \Omega'$ . The smallest sub- $\sigma$ -algebra of  $\mathcal{F}$  which makes all  $X_t$ 's measurable is called the  $\sigma$ -algebra generated by  $(X_t, t \in T)$ and is denoted  $\sigma(X_t, t \in T)$ .

**Example** Let  $\Omega = \{0,1\}^{\infty}$  be the coin-tossing space,  $X_n(\omega) = \omega_n$  for  $\omega = (\omega_1, \omega_2 \cdots)$ . Then  $\sigma(X_1, X_2, \ldots)$  is the  $\sigma$ -algebra having the cylinder sets  $A(\epsilon_1, \cdots, \epsilon_n), n \in \mathbb{N}$ , as generators.

**Example** Generalising the example of the coin-tossing space, for  $((\Omega_t, \mathcal{F}_t), t \in T)$  a family of measurable spaces, consider the Cartesian product

$$\Omega := \prod_{t \in T} \Omega_t = \{ (\omega_t, \ t \in T) : \omega_t \in \Omega_t \},\$$

Define  $X_t$  to be the *t*th coordinate of  $\omega \in \Omega$ . The *product*  $\sigma$ -algebra is generated by the family  $(X_t, t \in T)$  and is denoted  $\bigotimes_{t \in T} \mathcal{F}_t$ ; this has the set of generators of the form

$$A_t \times \prod_{s \neq t} \Omega_s, \ A_t \in \mathcal{F}_t.$$

For two measure spaces  $(\Omega, \mathcal{F}, \mu)$  and  $(\Omega', \mathcal{F}', \mu')$  define a function on the family of rectanges

$$\nu(B \times B') := \mu(B)\mu(B'), \quad B \in \mathcal{F}, \ B' \in \mathcal{F}'.$$
<sup>(2)</sup>

**Theorem 2.2.** If  $\mu$  and  $\mu'$  are  $\sigma$ -finite measures, the function  $\nu$  defined by (2) has a unique extension to a measure on the  $\sigma$ -algebra  $\mathcal{F} \otimes \mathcal{F}'$ .

The extension is called *the product measure* and is denoted  $\mu \times \mu'$ , and the triple  $(\Omega \times \Omega', \mathcal{F} \otimes \mathcal{F}', \mu \times \mu')$  is called *the product measure space*.

Under measurable mapping the measure is transported from the source to the target space.

**Definition 2.3.** Let  $X : \Omega \to \Omega'$  be a measurable function on a measure space  $(\Omega, \mathcal{F}, \mu)$ . The *image* (or pushforward) measure is defined as

$$\mu'(B') = \mu(X^{-1}(B')).$$

Sometimes notation  $\mu_X$  for  $\mu'$  is used.

**Example** For simple random variable

$$X = \sum_{j=1}^{n} y_j \mathbf{1}_{A_j}$$

the image measure on  $\mathbb{R}$  is discrete,

$$\mu_X = \sum_{j=1}^n \mu(A_j) \delta_{y_j},$$

charging point  $y_i$  with mass  $\mu(A_i)$ .

For X a real random variable on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , the image probability measure measure is uniquely determined by the function

$$F_X(x) = \mathbb{P}(X \le x), \quad x \in \mathbb{R}$$

known as the cumulative distribution function of X.

For  $\mathbb{R}^n$ -valued random variable  $X = (X_1, \dots, X_n)$  (random vector) defined on some probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , the image measure on  $\mathbb{R}^n$  is called the *probability distribution* of X, or the *joint* probability distribution of  $X_1, \dots, X_n$ . Let  $i_1 < \dots < i_m$  be a subset of  $\{1, \dots, n\}$  and consider the projection  $(x_1, \dots, x_n) \mapsto (x_{i_1}, \dots, x_{i_m})$  which removes the entries outside the index set  $\{i_1, \dots, i_m\}$ . Under such projection, the joint distribution of  $(X_1, \dots, X_n)$  is mapped to the joint distribution of subvector  $(X_{i_1}, \dots, X_{i_m})$  called an *m*-dimensional *marginal* distribution of vector X.

#### 2.2 Independence

Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space. Events  $(A_t, t \in T) \subset \mathcal{F}$  are called independent if for every selection of distinct  $t_1, \ldots, t_k \in I$ 

$$\mathbb{P}(A_{t_1} \cap \cdots \cap A_{t_k}) = \mathbb{P}(A_{t_1}) \cdots \mathbb{P}(A_{t_k}).$$

Let  $(\mathcal{F}_t, t \in T)$  be sub- $\sigma$ -algebras of  $\mathcal{F}$ . They are called independent if for any choice of distinct indices  $t_1, \ldots, t_k$  any events  $A_{t_1} \in \mathcal{F}_{t_1}, \ldots, A_{t_k} \in \mathcal{F}_{t_k}$  are independent.

Independence of random variables  $X_i$  is defined as independence of their generated  $\sigma$ -algebras  $\sigma(X_i)$ .

For every family  $(P_t, t \in T)$  of probability measures on  $\mathbb{R}$  there exists a family of independent random variables  $(X_t, t \in T)$  with  $X_t$  having distribution P. This follows from the construction of the product measure.

### 2.3 Tail events

Let  $A_i \in \mathcal{F}$  be events,  $i \in \mathbb{N}$ . Consider the event ' $A_n$  occurs inifinitely often' (more precisely, 'infinitely many of  $A_n$ 's occur')

$$\{A_n \text{ i.o.}\} := \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k$$

#### Theorem. (Borel-Cantelli Lemma)

(a) If  $\sum_{n} \mathbb{P}(A_n) < \infty$  then  $\mathbb{P}(A_n \text{ i.o.}) = 0$ ,

(b) If  $A_1, A_2, \ldots$  are independent and  $\sum_n \mathbb{P}(A_n) = \infty$  then  $\mathbb{P}(A_n \text{ i.o.}) = 1$ .

Proof. Part (a) is an exercise from Lecture 1. We focus on (b). We have

$$\{A_n \text{ i.o.}\}^c = \bigcup_{n=1}^{\infty} \bigcap_{k=n}^{\infty} A_k^c$$

Clearly

$$\bigcap_{k=1}^{\infty} A_k^c \subset \bigcap_{k=2}^{\infty} A_k^c \subset \cdots,$$

hence

$$\mathbb{P}(\{A_n \text{ i.o.}\}^c) = \lim_{n \to \infty} \mathbb{P}\left(\bigcap_{k=n}^{\infty} A_k^c\right) = \lim_{n \to \infty} \lim_{m \to \infty} \mathbb{P}\left(\bigcap_{k=n}^m A_k^c\right) =$$

using independence and that  $\sum_{n} \mathbb{P}(A_n) = \infty$ 

$$= \lim_{n \to \infty} \lim_{m \to \infty} \prod_{k=n}^{m} (1 - \mathbb{P}(A_k)) = 0.$$

**Example** Let  $X_1, X_2, \ldots$  be independent  $\mathcal{N}(0, 1)$ -distributed random variables (any other continuous distribution would also work). We say that there is a record at index n if  $X_n = \max(X_1, \ldots, X_n)$ ; denote this event  $A_n$ . One can check that  $\mathbb{P}(A_n) = 1/n$  and that the events are independent. Since  $\sum_n 1/n = \infty$  the number of records is infinite with probability 1.

Suppose the occurence/not occurence of event  $A_n$  becomes known to an observer at time n. The Borel-Cantelli Lemma exemplifies situation where probability of some related 'distant' event may assume only values 0 and 1. Results of the kind are known as 'zero-one laws, which we discuss next.

Let  $\mathcal{F}_j, j \in \mathbb{N}$ , be  $\sigma$ -algebras (sub- $\sigma$ -algebras of  $\mathcal{F}$ ). We define the *tail*  $\sigma$ -algebra as

$$\mathcal{T} := \bigcap_{n=1}^{\infty} \sigma \left( \bigcup_{k=n}^{\infty} \mathcal{F}_k \right).$$

Each  $A \in \mathcal{T}$  is called *tail event*.

**Example** In the coin-tossing space, let  $\mathcal{F}_n$  be the  $\sigma$ -algebra generated by outcomes in n first trials. The event 'the pattern 1011101 occurs infinitely many times in the sequence' is a tail event.

**Theorem.** (Kolmogorov's 0-1 law) If  $\mathcal{F}_1, \mathcal{F}_2, \cdots$  are independent, then  $\mathcal{T}$  is trivial in the sense that  $\mathbb{P}(A) = 0$  or 1 for each  $A \in \mathcal{T}$ .

*Proof.* Suppose A is a tail event, since  $A \in \sigma(\bigcup_{k=n}^{\infty} \mathcal{F}_k)$ , we have that A is independent of  $\mathcal{F}_1, \ldots, \mathcal{F}_{n-1}$ . Since this holds for every n, A is independent of  $\sigma(\bigcup_{k=1}^{\infty} \mathcal{F}_k)$  and thus independent of smaller  $\sigma$ -algebra  $\mathcal{T}$ . In particular, A is independent of itself,  $\mathbb{P}(A) = \mathbb{P}(A \cap A) = \mathbb{P}(A)\mathbb{P}(A)$ , which is only possible when  $\mathbb{P}(A)$  is 0 or 1. **Example** Let  $X_1, X_2, \ldots$  be independent random variables, generating  $\sigma$ -algebras  $\sigma(X_j), j \in \mathbb{N}$ . The event

$$A = \{ \omega \in \Omega : \sum_{n=1}^{\infty} X_n \text{ converges} \}$$

is a tail event, therefore can only have probability 0 or 1.

**Theorem.** (Kolmogorov's Three Series Theorem) Series  $\sum_{n=1}^{\infty} X_n$  of independent random variable converges alsmost surely if and only if the following conditions hold with some constant c > 0

- (i)  $\sum_{n=1}^{\infty} \mathbb{P}(|X_n| > c) < \infty$ ,
- (ii)  $\sum_{n=1}^{\infty} \mathbb{E}(X_n \mathbb{1}_{\{|X_n| \le c\}}) < \infty$ ,
- (iii)  $\sum_{n=1}^{\infty} \operatorname{Var}(X_n 1_{\{|X_n| \le c\}}) < \infty.$

**Example** For independent normal random variables  $X_n \sim \mathcal{N}(m_n, \sigma_n^2)$  convergence of the series  $\sum_n X_n$  holds if and only if  $\sum_n m_n$  and  $\sum_n \sigma_n^2$  both converge.

### 2.4 Lebesgue integral and expectation

The expectation of discrete random variable X with values  $x_1, x_2, \ldots$  is

$$\mathbb{E} X = \sum_{j} x_{j} \mathbb{P}(X = x_{j}),$$

and if X has a density  $f_X$ 

$$\mathbb{E} X = \int_{-\infty}^{\infty} x f_X(x) dx.$$

These are unified by the general concept of Lebesgue integral.

For measurable function  $g:\mathbb{R}\to\mathbb{R}$  and a measure  $\mu$  on  $\mathbb{R}$  we wish to define

$$\int_{\mathbb{R}} g(x) d\mu(x) \text{ (also written as } \int_{\mathbb{R}} g(x) \mu(dx))$$

Suppose first that g is nonnegative. For simple

$$g(x) = \sum_{j=1}^{k} y_j \mathbb{1}_{A_j}(x), \quad A_j \in \mathcal{B}(\mathbb{R})$$

we set

$$\int_{\mathbb{R}} g(x) d\mu(x) = \sum_{j=1}^{k} y_j \mu(A_j).$$

For the general  $f \ge 0$ , consider sets

$$A_{jk} = \begin{cases} \left\{ x : \frac{k}{2^{j}} \le f(x) < \frac{k+1}{2^{j}} \right\}, & k = 0, 1, \dots, j2^{j} - 1, \\ \left\{ x : f(x) \ge j \right\}, & k = j2^{j}, \end{cases}$$

and simple functions

$$g_j(x) = \sum_{k=0}^{j_{2^j}} \frac{k}{2^j} \, \mathbf{1}_{A_{jk}}(x),$$

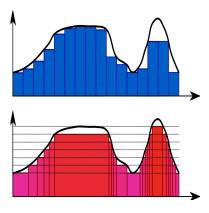


Figure 1: Lower Riemann integral sum and integral sum for Lebesgue integral.

so

$$\int_{\Omega} g_j(x) d\mu(x) = \sum_{k=0}^{j2^j} \frac{k}{2^j} \ \mu(A_{jk}),$$

which we consider as a lower approximation for Lebesgue integral. The *Lebesgue integral* of g is defined as the limit

$$\int_{\Omega} g(x) d\mu(x) := \lim_{j \to \infty} \int_{\Omega} g_j(x) d\mu(x).$$

**Example** Let  $g(x) = 1_{[0,1]\setminus\mathbb{Q}}$  be the indicator function of irrational numbers on [0, 1]. The Riemann integral over [0, 1] does not exist, because every upper integral sum is 1, and every lower is 0. The Lebesgue integral is

$$\int_{[0,1]} g(x)dx = 1 \cdot \lambda([0,1] \setminus \mathbb{Q}) + 0 \cdot \lambda([0,1] \cap \mathbb{Q}) = 1$$

Note that here dx means the same as  $d\lambda(x)$ .

For the general  $g: \Omega \to \mathbb{R}$  let  $g_+(x) = \max(g(x), 0), g_-(x) = \max(-g(x), 0)$  be positive and negative parts, then  $g(x) = g_+(x) - g_-(x)$ . If

$$\int_{\Omega} |g(x)| d\mu(x) < \infty$$

we say that g is integrable and we define the Lebesgue integral of f as

$$\int_{\Omega} g(x)d\mu(x) = \int_{\Omega} g_{+}(x)d\mu(x) - \int_{\Omega} g_{-}(x)d\mu(x)$$

Note that  $\int_0^\infty x^{-1}(\sin x)dx = \lim_{a\to\infty} \int_0^a x^{-1}(\sin x)dx = \pi/2$  exists as improper Riemann integral over  $\mathbb{R}_+$ , but not as Lebesgue integral because  $\int_0^\infty |(\sin x)/x|dx = \infty$ .

The definition of Lebesgue integral for random variable X defined on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  is analogous to the inegral over  $\mathbb{R}$ . These are related as

$$\mathbb{E}X := \int_{\Omega} X(\omega) d \mathbb{P}(\omega) = \int_{\mathbb{R}} x dP_X(x),$$

where  $P_X$  is the distribution of X.

### 2.5 Absolute continuity of measures

Let  $p_j, j \in \mathbb{N}$  be positive numbers, with sum 1. We may treat the identity function on  $\mathbb{N}$  as a random variable  $X : \mathbb{N} \to \mathbb{N}$  with the probability mass function  $P = (p_j, j \in \mathbb{N})$ . For any function g we have the expectation of g(X) calculated as

$$\mathbb{E}_P\left[g(X)\right] = \sum_{j \in \mathbb{N}} g(j) p_j$$

If  $Q = (Q_j, j \in \mathbb{N})$  is some other probability mass function, the corresponding expectation is

$$\mathbb{E}_Q\left[g(X)\right] = \sum_{j \in \mathbb{N}} g(j)q_j.$$

To write the Q-expectation in terms of P, let  $\xi(j) = q_j/p_j$ , then

$$\mathbb{E}_Q g(X) = \sum_{j \in \mathbb{N}} g(j)\xi_j p_j = \mathbb{E}_P [\xi g(X)].$$

The random variable  $\xi$  is an instance of the Radon-Nikodym derivative (or density).

In full generality, let  $\mu, \nu$  be two measures on  $(\Omega, \mathcal{F})$ . Call  $\nu$  absolutely continuous with respect to  $\mu$ , written as  $\mu \gg \nu$  if

$$A \in \mathcal{F}, \ \mu(A) = 0 \quad \Rightarrow \quad \nu(A) = 0.$$

The measures are called *equivalent*, denoted  $\mu \sim \nu$ , if

$$\mu(A) = 0 \quad \Leftrightarrow \quad \nu(A) = 0,$$

which means that the measures have the same null-sets.

**Theorem.** (Radon-Nikodym theorem.) If  $\mu \gg \nu$  and  $\mu$  is  $\sigma$ -finite then there exists a nonnegative measurable function  $\xi$  on  $\Omega$  such that for any measurable  $g : \Omega \to \mathbb{R}$ 

$$\int_{\Omega} f(x)d\nu(x) = \int_{\Omega} f(x)\xi(x)d\mu(x),$$

provided one of the integrals exists.

In particular,  $\nu(A) = \int_A \xi(x) d\mu(x)$ . We write  $\xi = \frac{d\nu}{d\mu}$  and call  $\xi$  the Radon-Nikodym deritative of  $\nu$  with respect to  $\mu$ . Such  $\xi$  is unique up to values on a set of  $\mu$ -measure 0.

**Example** For  $\lambda$  the lebesgue measure,  $\nu$  the normal  $\mathcal{N}(0, 1)$  distribution, the Radon-Nikodym derivative is the normal density

$$\xi(x) = \frac{e^{-x^2/2}}{\sqrt{2\pi}}.$$

### 2.6 Conditional expectation

For two random variables, X, Y, recall that the conditional expectation  $\mathbb{E}[X|Y]$  is defined as follows. Calculate the function  $h(y) = \mathbb{E}[X|Y = y]$ , in case of discrete random variables as

$$\mathbb{E}[X|Y = y_j] = \sum_j x_i \mathbb{P}(X = x_i|Y = y_j],$$

or when (X, Y) have joint density as

$$\mathbb{E}[X|Y=y] = \int_{-\infty}^{\infty} x f_{X|Y=y}(x) dx,$$

where

$$f_{X|Y=y}(x) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

is the conditional density. Then define  $\mathbb{E}[X|Y] = h(Y)$  by subsituting random variable Y for dummy variable y.

Intuitively,  $\mathbb{E}[X|X] = X$ , and in the discrete case this is easily checked. When X has density, this is still true but we cannot use the above formula with Y = X, because (X, X) has no *joint* density function.

We wish to introduce more general conditional expectation  $\mathbb{E}[X|\mathcal{G}]$  given sigma-algebra  $\mathcal{G} \subset \mathcal{F}$ . Suppose first  $X \ge 0$ . Let

$$\mathbb{Q}(A) := \mathbb{E}[X \cdot 1_A] = \int_A X d \mathbb{P}.$$

For disjoint sets  $A_n \in \mathcal{G}$ 

$$\int_{\bigcup_n A_n} Xd\,\mathbb{P} = \sum_n \int_{A_n} Xd\,\mathbb{P},$$

which entails that  $\mathbb{Q}$  is a measure, and  $\mathbb{Q}$  is absolutely continuous with respect to  $\mathbb{P}$ . By the Radon-Nikodym theorem there exists a  $\mathcal{G}$ -measurable random variable  $\xi$  such that

$$\mathbb{Q}(A) = \int_A \xi d \,\mathbb{P} \,.$$

We denote this variable as

$$\xi = \mathbb{E}[X|\mathcal{G}],$$

and call it the conditional expectation of X given  $\mathcal{G}$ . The defining property is

$$\int_{A} X d \mathbb{P} = \int_{A} \mathbb{E}[X|\mathcal{G}] d \mathbb{P}, \quad A \in \mathcal{G}.$$

For any X, we write  $X = X_{+} - X_{-}$  and define the conditional expectation by

$$\mathbb{E}[X|\mathcal{G}] = \mathbb{E}[X_+|\mathcal{G}] - \mathbb{E}[X_-|\mathcal{G}],$$

which exists if X is integrable.

The following rules will be used in the sequel:

- (i)  $\mathbb{E}[X|\{\emptyset,\Omega\}) = \mathbb{E}X$ ,
- (ii)  $\mathbb{E}[aX + bY|\mathcal{G}] = a \mathbb{E}[X|\mathcal{G}] + b \mathbb{E}[Y|\mathcal{G}],$

(iii) 
$$\mathbb{E}[1|\mathcal{G}] = 1$$
,

(iv) taking out what is known: if Y is  $\mathcal{G}$ -measurable, then

$$\mathbb{E}[XY|\mathcal{G}] = Y \cdot \mathbb{E}[X|\mathcal{G}]$$

(v) tower property: for  $\mathcal{G}_1 \subset \mathcal{G}_2$ 

$$\mathbb{E}[\mathbb{E}[X|\mathcal{G}_2]|\mathcal{G}_1] = \mathbb{E}[X|\mathcal{G}_1]$$

in particular  $\mathbb{E}[\mathbb{E}[X|\mathcal{G}]] = \mathbb{E} X.$ 

## **Exercises**

- 1. Let  $Y_1, Y_2, \ldots$  be independent, exponentially distributed random variables with  $\mathbb{E} Y_i = 1$ . Show that  $\mathbb{P}(Y_n > \log n \text{ i.o.}) = 1$ .
- 2. Show that condition (i) in the three series theorem is necessary for convergence of the series.
- 3. Suppose rv's  $X_1, \dots, X_n$  independent, rv's  $Y_1, \dots, Y_m$  independent, and random vectors  $(X_1, \dots, X_n)$  and  $(Y_1, \dots, Y_m)$  are independent. Show that the (n+m) random variables  $X_1, \dots, X_n, Y_1, \dots, Y_m$  are independent.
- 4. Let  $X_1, X_2, \ldots$  be arbitrary random variables. Prove that if  $\sum_{j=1}^{\infty} \mathbb{E}|X_j| < \infty$  then the series  $\sum_{j=1}^{\infty} X_j$  converges absolutely with probability one.
- 5. Suppose  $\mathbb{E}X$  exists. Argue that for every  $\epsilon$  there exists  $\delta$  such that  $\mathbb{P}(A) < \delta$  implies

$$\mathbb{E}(|X| \cdot 1_A) < \epsilon$$

(where  $1_A$  indicator of event A).

- 6. Show that  $\mathbb{E}[XY] = \mathbb{E}X \mathbb{E}Y$  if the rv's are independent.
- 7. For three measures suppose  $\mu \gg \nu \gg \rho$  and that  $\mu, \nu, \rho$  are  $\sigma$ -finite. Prove the chain rule for the Radon-Nikodým derivative:

$$\frac{d\rho}{d\mu} = \frac{d\nu}{d\mu} \frac{d\rho}{d\nu}$$

- 8. Let  $\mu$  be a normal distribution  $\mathcal{N}(m, \sigma^2)$ , and  $\nu$  the exponential distribution with parameter  $\beta$ . Argue that  $\mu \gg \nu$  and find the Radon-Nikodym derivative  $d\nu/d\mu$ .
- 9. Let A<sub>i,j</sub> be a system of disjoint events, with ∪<sub>i,j</sub>A<sub>i,j</sub> = Ω. Let A<sub>i</sub> = ∪<sub>j</sub>A<sub>i,j</sub>. Let G<sub>2</sub> be generated by all A<sub>i,j</sub>'s, and let G<sub>1</sub> be generated by A<sub>i</sub>'s. Describe as precise as you can the random variables E[X|G<sub>1</sub>], E[X|G<sub>2</sub>]. Assuming P(A<sub>i,j</sub>) > 0, prove the tower property in this example.

### Literature

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